



# Global Computing

WAN programming  
for building *global  
systems*.

They are hard to  
be made robust  
because:

- Absence of centralised control  
Client-Server not enough: **P2P**
- Administrative domains (**Security**)
- Interoperability
  - different platforms
  - different devices  
(e.g. PDA, laptop, mobile phones...)
- “Mobility” (resources **and** computation)
- ...





# Global Computing

WAN programming  
for building *global  
systems*.

They are hard to  
be made robust  
because:

- *Network Awareness*
  - Applications are location dependent
  - Locations have different features
  - and allow multiple (security) policies
- *Service Level Agreement*
- *Independently programmed in a distributed environment*
- *Reasoning on space and time*
- ...





# Web Services: A programming metaphor


- Applications access *services* that must be
  - Published
  - Searched
  - Binded
- Services are
  - “Autonomous”
  - Independent (local choices, independently built)
  - Mobile/stationary
  - “Interconnected”
- Security issues: hostile environment





- Ambient [?, ?, ?]

● Djoin [?, ?]

  $D\pi$  [?, ?]

● Klaim [?, ?, ?]

Seal [?]





**In collaboration with G. Ferrari and U. Montanari**





# Hypergraphs Programming model<sup>2</sup>

- Graphs for distributed systems [?]
- Edge replacement for graph rewritings [?]
- Edge replacement/distributed constraint solving problem [?]
- Graphs grammars for software architecture styles [?]
- Synchronised Hyperedge Replacement (SHR) with mobility for name passing calculi [?]





# Hypergraphs Programming model<sup>3</sup>

We aim at tackling new *non-functional* computational phenomena of systems using SHR.

The metaphor is

- “WAN systems *as* Hypergraphs”
- “WAN computations *as* SHR”

In other words:

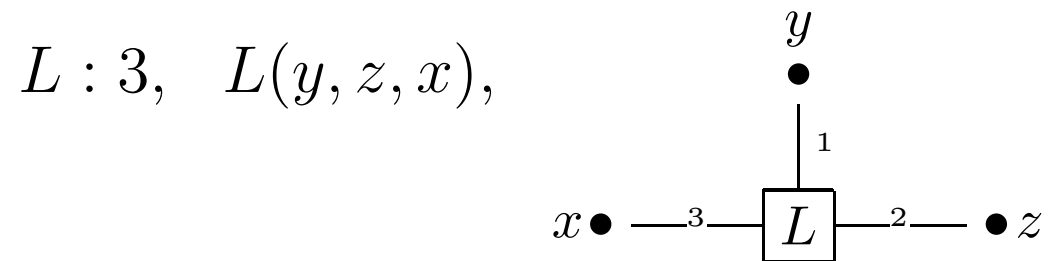
- Components are represented by hyperedges
- Systems are *bunches* of (connected) hyperedges
- Computing means to rewrite hyperedge...
- ...according to a synchronisation policy





# Hyperedges and Hypergraphs Syntax

A hyperedge generalises edges: It connects more than two nodes



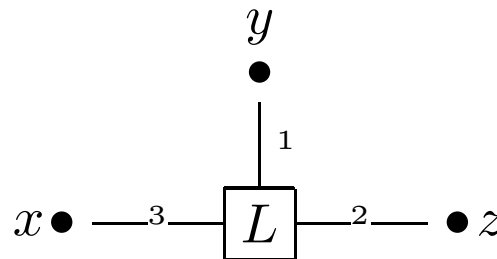




# Hyperedges and Hypergraphs Syntax

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$L : 3, \quad L(y, z, x),$

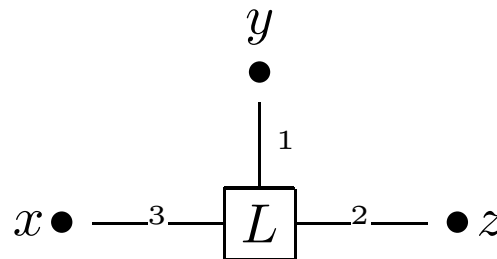

$$\begin{array}{l} G ::= nil \mid \nu y.G \\ \mid L(\vec{x}) \mid G|G \end{array}$$



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Syntactic Judgement

$\Gamma \vdash G,$

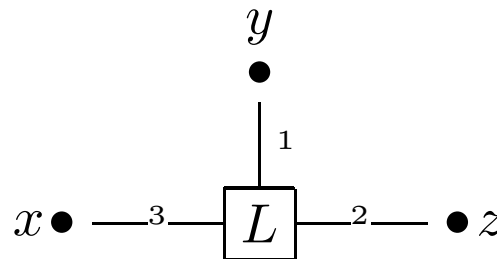
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An example:

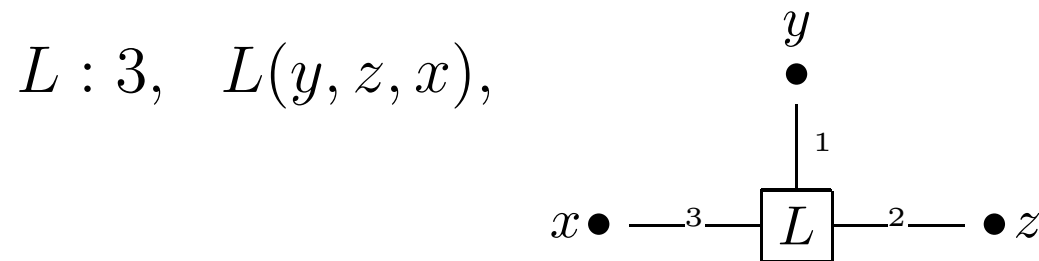
$L : 3, \quad M : 2$

$x, y \vdash \nu z.(L(y, z, x)|M(y, z))$



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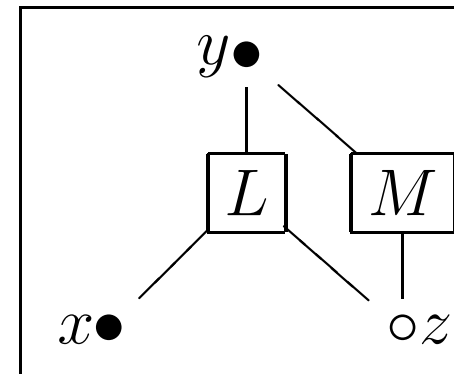
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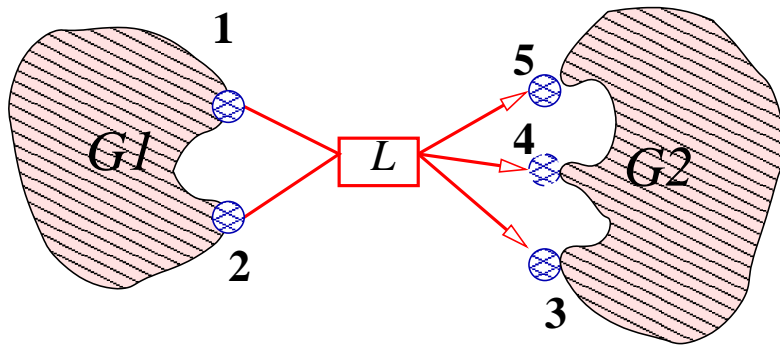






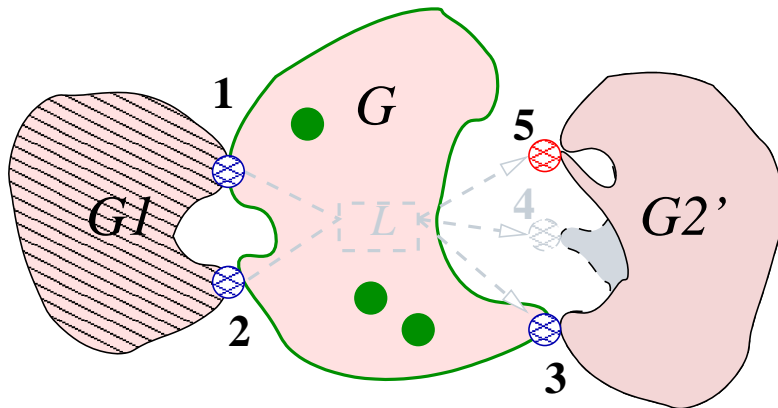
# Replacement of Hyperedges

$$L \rightarrow G$$



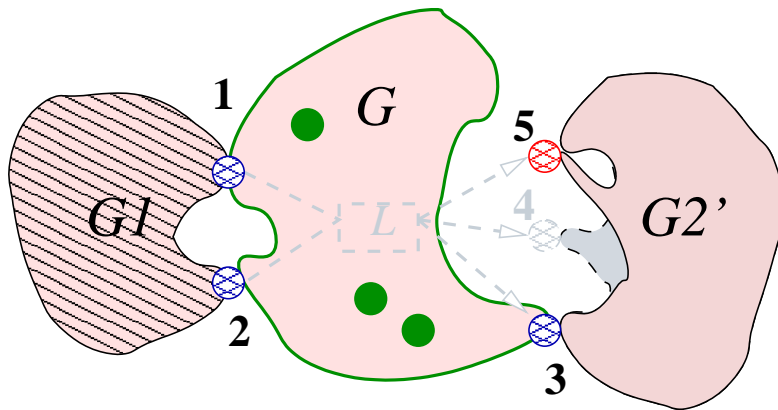
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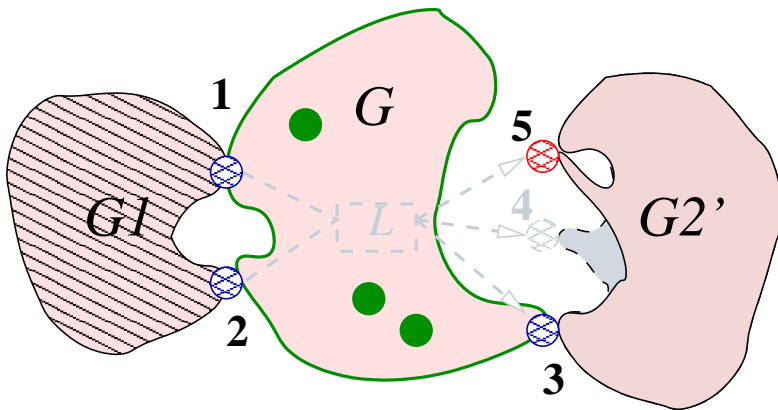


- Edge replacement: local
- Synchronisation as distributed constraint solving
- Multiple synchronisation
- New node creation
- Node fusion: mobility model



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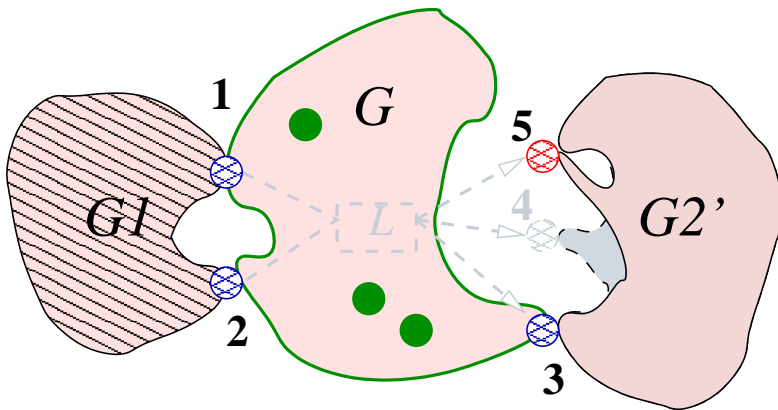
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## Benefits:

- Uniform framework for  $\pi$ ,  $\pi$ -I, fusion
- LTS for Ambient ...
- ... for Klaim ...

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## Benefits:

- Uniform framework for  $\pi$ ,  $\pi$ -I, fusion
- LTS for Ambient ...
- ... for Klaim ...
- ... and *path reservation* for Qlaim
- wireless networks
- expressive for distributed coordination



- $\Lambda \subseteq X \times Act \times \mathcal{N}^*$  set of constraints
- $\pi : X \rightarrow X$  fusion substitution, i.e.

- $\Gamma = \pi(X) \cup (\mathbf{n}(\Lambda) \setminus X)$
- $\mathbf{fn}(G) \subseteq \Gamma$





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# Applying the Model

Ambient

$a[\dots] \mid \text{open } a \rightarrow \dots$



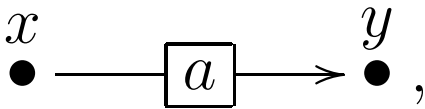
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Ambient

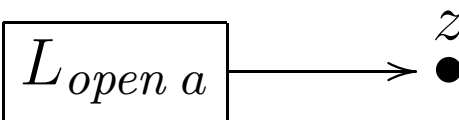
$a[\dots] \mid \text{open } a \rightarrow \dots$

Components

$a[\dots] :$



$\text{open } a :$





# Applying the Model

Ambient

$$a[\dots] | \text{open } a \rightarrow \dots$$

Components

$$a[\dots] : \quad x \xrightarrow{\quad} \boxed{a} \rightarrow y \bullet ,$$

$$\text{open } a : \quad \boxed{L_{\text{open } a}} \rightarrow z \bullet$$

$$x \xrightarrow{\quad} \boxed{a} \rightarrow y \bullet \xRightarrow{[y/x]} y = x \bullet$$

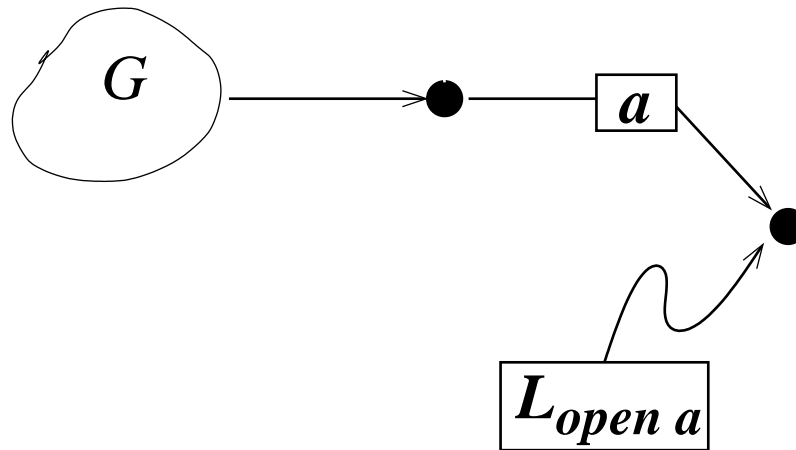
*open a*

Productions

$$\boxed{L_{\text{open } a}} \rightarrow \frac{z \bullet}{\text{open } a} \Rightarrow z \bullet$$



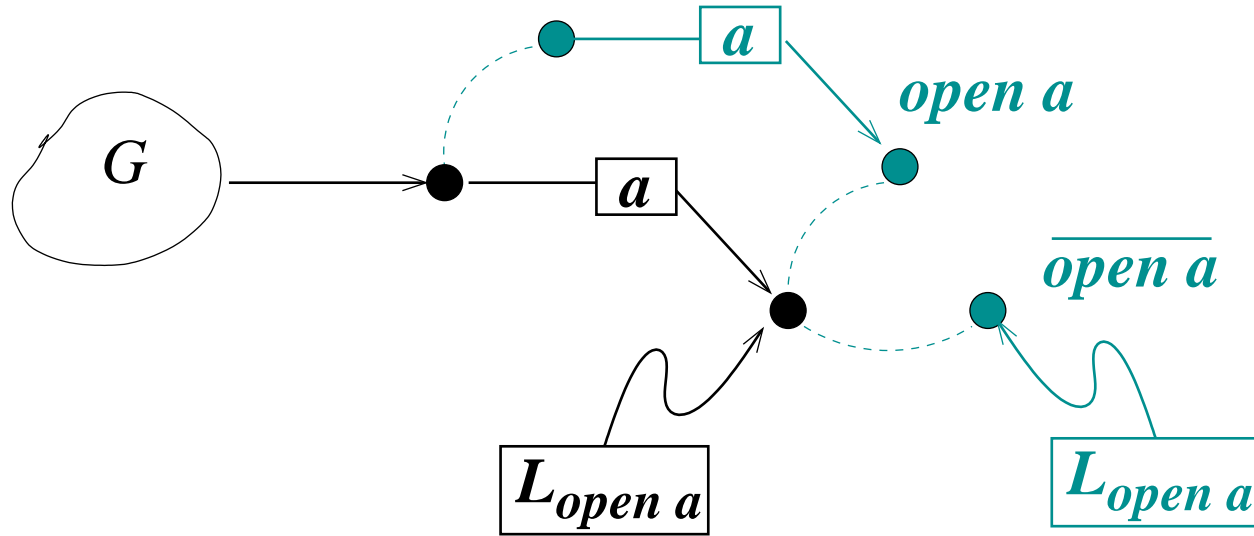
# Applying the Model: Node Fusion





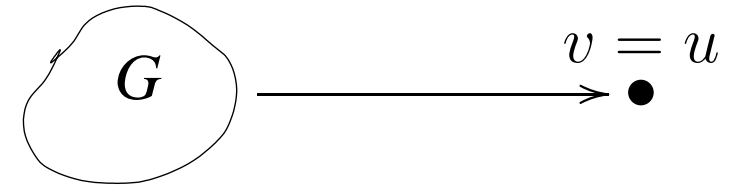
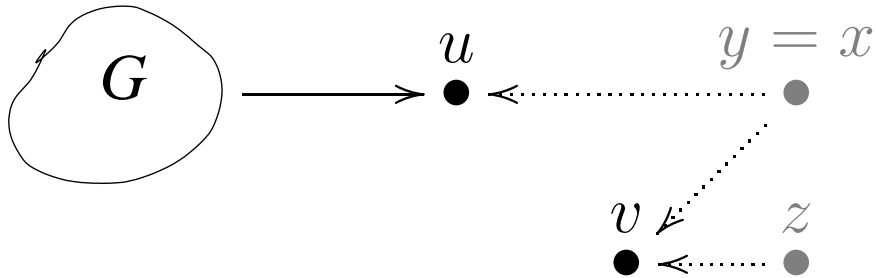
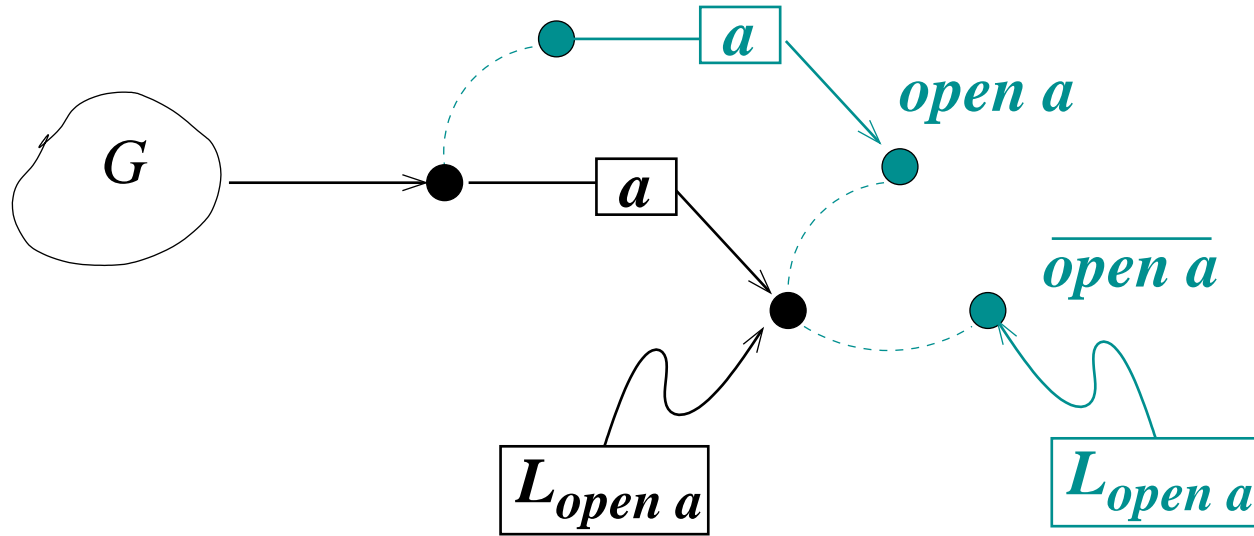


# Applying the Model: Node Fusion





# Applying the Model: Node Fusion



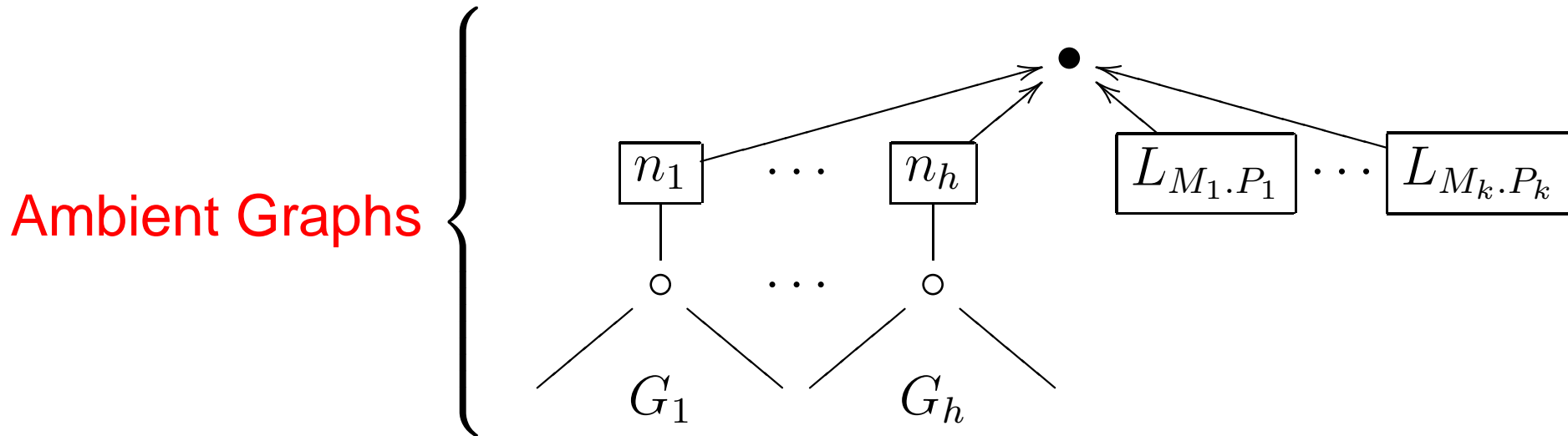
$$\llbracket \mathbf{nil} \rrbracket_x = x \vdash \mathbf{nil}$$

$$\llbracket n[P] \rrbracket_x = x \vdash \nu y.(G \mid n(y, x)), \quad \text{if } y \neq x \wedge \llbracket P \rrbracket_y = y \vdash G$$

$$\llbracket M.P \rrbracket_x = x \vdash L_{M.P}(x)$$

$$\llbracket P_1 \mid P_2 \rrbracket_x = x \vdash G_1 \mid G_2, \quad \text{if } \llbracket P_i \rrbracket_x = x \vdash G_i \wedge i = 1, 2$$

$$\llbracket \mathbf{rec} X.P \rrbracket_x = \llbracket P[\mathbf{rec} X.P / X] \rrbracket_x$$



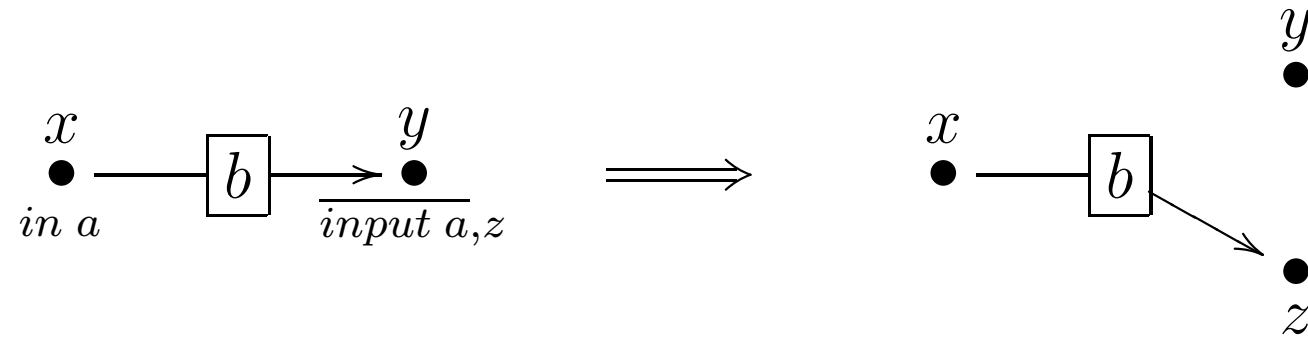
**Theorem**  $\llbracket \_ \rrbracket$  is a bijection on ambient graphs



# Coordination Productions for Ambient

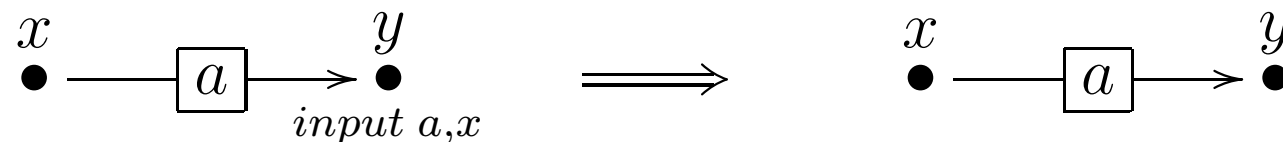
$$x, y \vdash b(x, y) \xrightarrow{\{(x, \text{in } a, \langle \rangle), (y, \overline{\text{input } a, \langle z \rangle})\}} x, y, z \vdash b(x, z)$$

(input1)



$$x, y \vdash a(x, y) \xrightarrow{\{(y, \text{input } a, \langle x \rangle)\}} x, y \vdash a(x, y)$$

(input2)

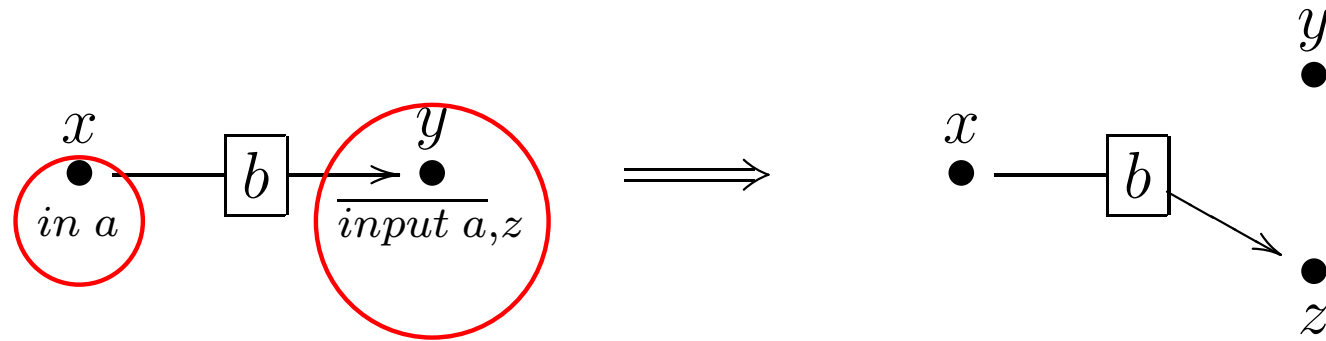




# Coordination Productions for Ambient

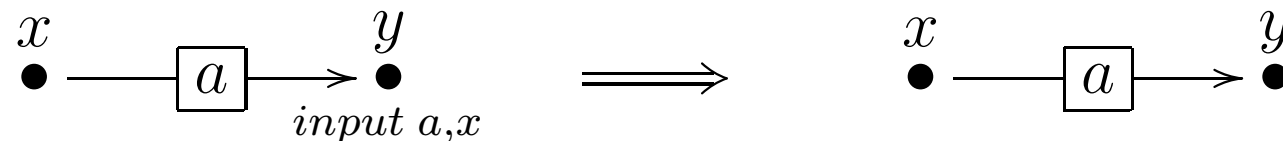
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(input2)





# Semantic Correspondence

**Theorem** If  $P \rightarrow Q$  then  $\llbracket P \rrbracket_x \xrightarrow[id]{\Lambda} \llbracket Q \rrbracket_x$  and

- either  $\Lambda = \emptyset$
- or  $\Lambda = \{(x, \tau, \langle \rangle)\}$

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- either  $\Lambda = \emptyset$
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**Theorem** If  $\llbracket P \rrbracket_x \xrightarrow[\pi]{\Lambda} \Gamma \vdash G$  is a **basic transition**, then

- either  $\llbracket P \rrbracket_x = \Gamma \vdash G$
- or  $\exists Q \in Proc : P \rightarrow Q \wedge \Gamma \vdash G = \llbracket Q \rrbracket_x$



# Qlaim: Expressing and reasoning on Connection Properties

In collaboration with R. De Nicola, G. Ferrari, U. Montanari,  
R. Pugliese







# Klaim [?]

## ● Multiple TS





# Klaim [?]

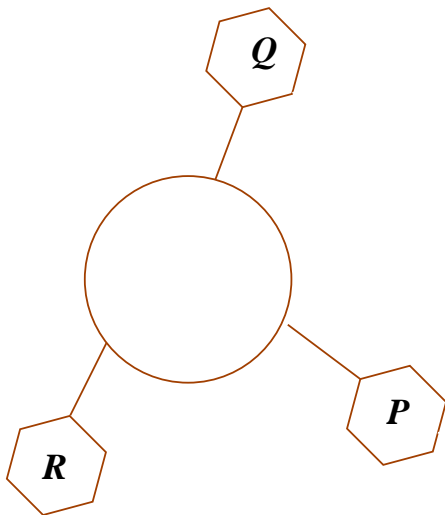
- Multiple TS
- Localities: first class citizens



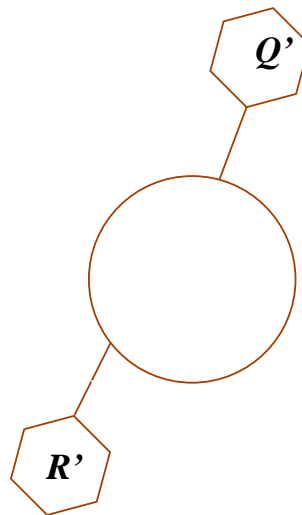


-

- Multiple TS
- Localities: first class citizens
- Process migration

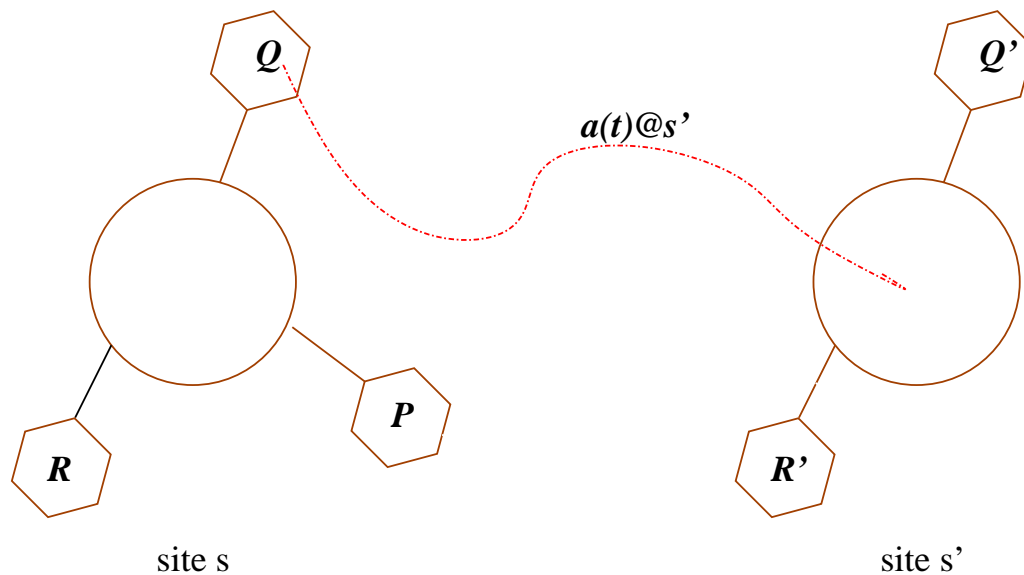


site  $s$

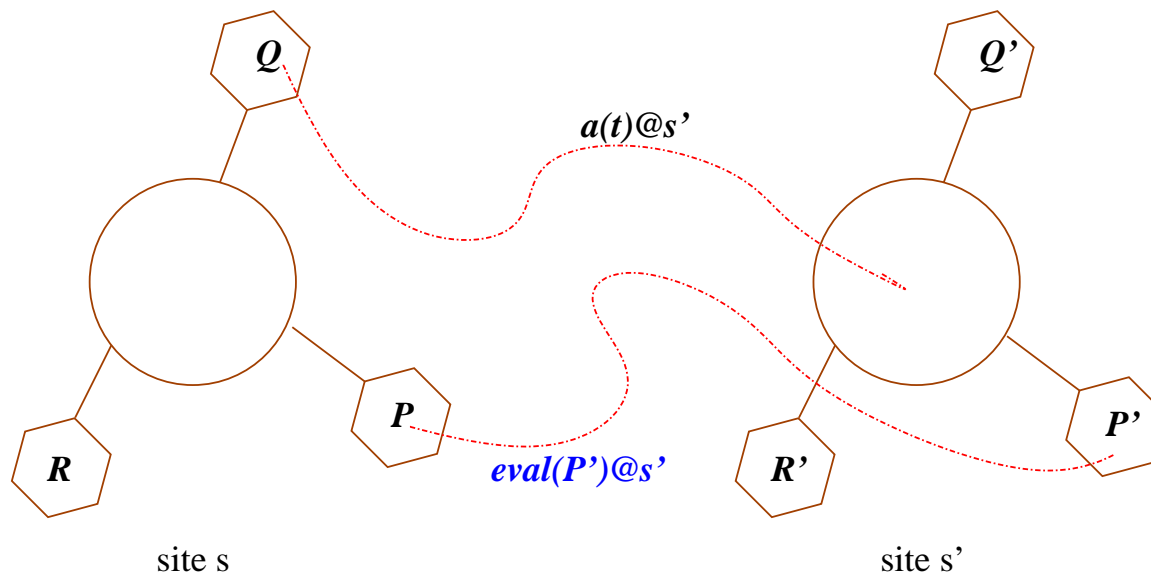


site  $s'$

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- Localities: first class citizens
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$$\begin{aligned}
 P &::= \text{nil} \\
 &| \alpha.P \\
 &| P_1 \mid P_2 \\
 \alpha &::= a@_s \\
 a &::= \dots \text{ // Klaim actions} \\
 &| \text{eval}(P)
 \end{aligned}$$



# Claim: Gateways

In [?]





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In [?]

- Coordinators (super processes)





# Qlaim: Gateways

In [?]

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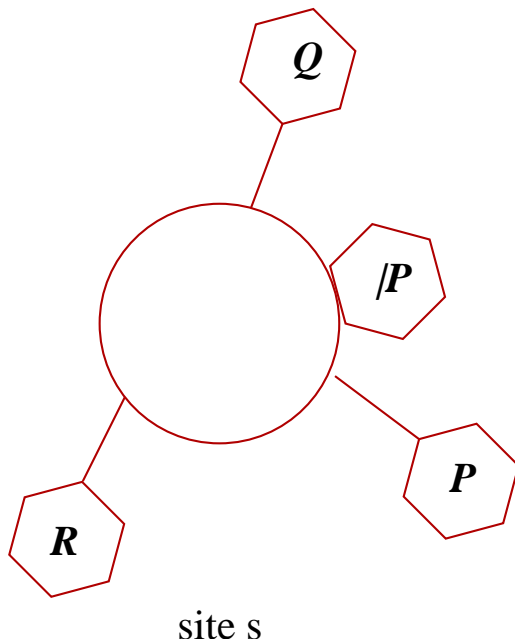




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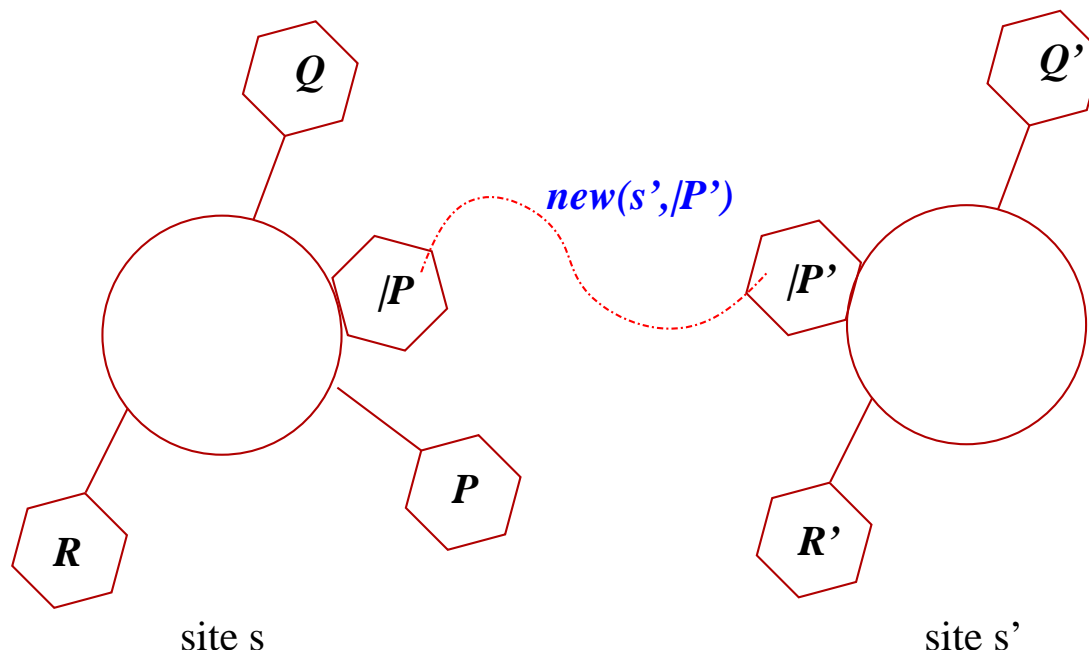
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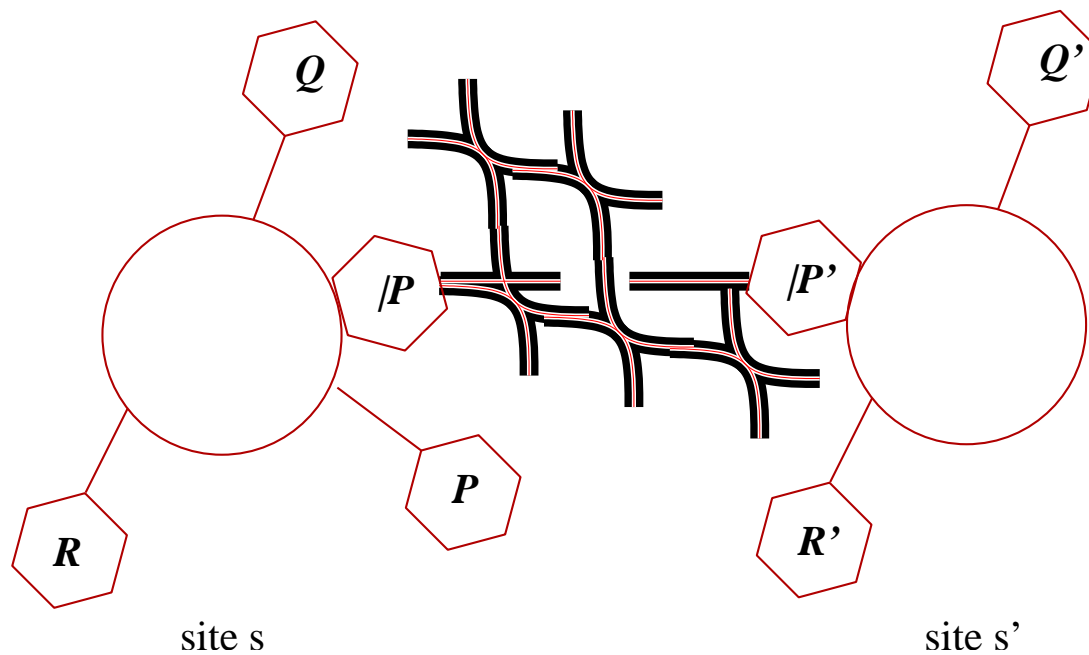
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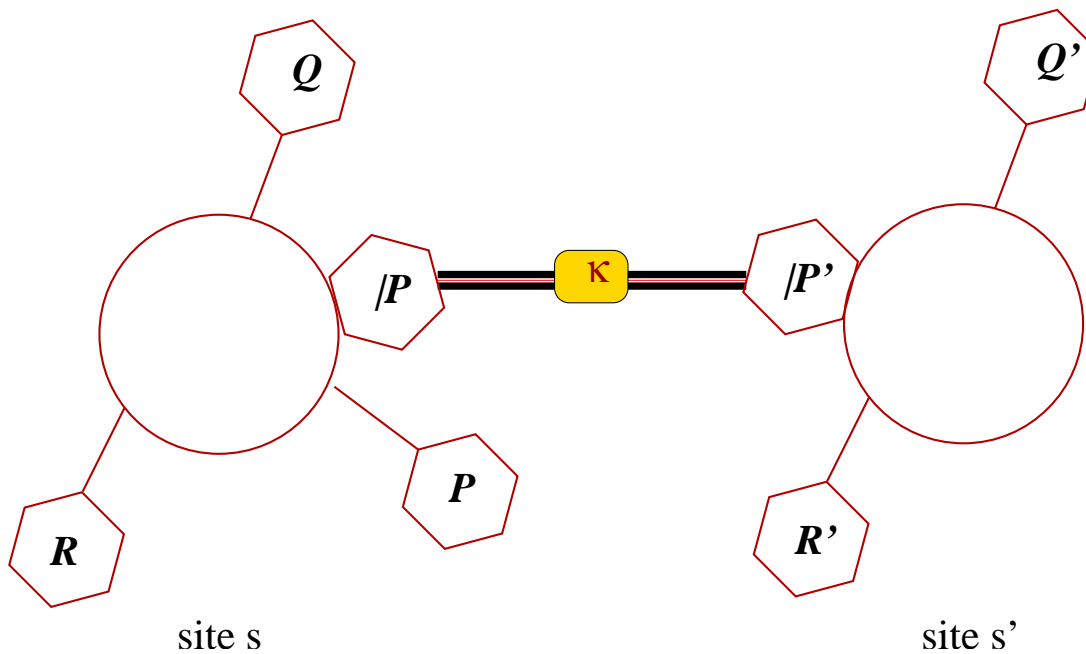
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# Qlaim: Gateways

In [?]

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$$\mathbb{P} ::= \gamma.\mathbb{P} \mid \mathbb{P}_1 \mid \mathbb{P}_2$$

$$\gamma ::= \alpha$$

$$\mid \text{new}(s, \mathbb{P})$$

$$\mid \text{login}(s, \kappa)$$

$$\mid \text{accept}(s, \kappa)$$

$$\mid \text{logout}(s, \kappa)$$

$$\mid \text{disconnect}(s, \kappa)$$

# Connection costs

Cost  $\kappa$  abstracts characteristics of connections (bandwidth, latency, distance, access rights ...)



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Algebra on costs: **c-semiring**. For instance

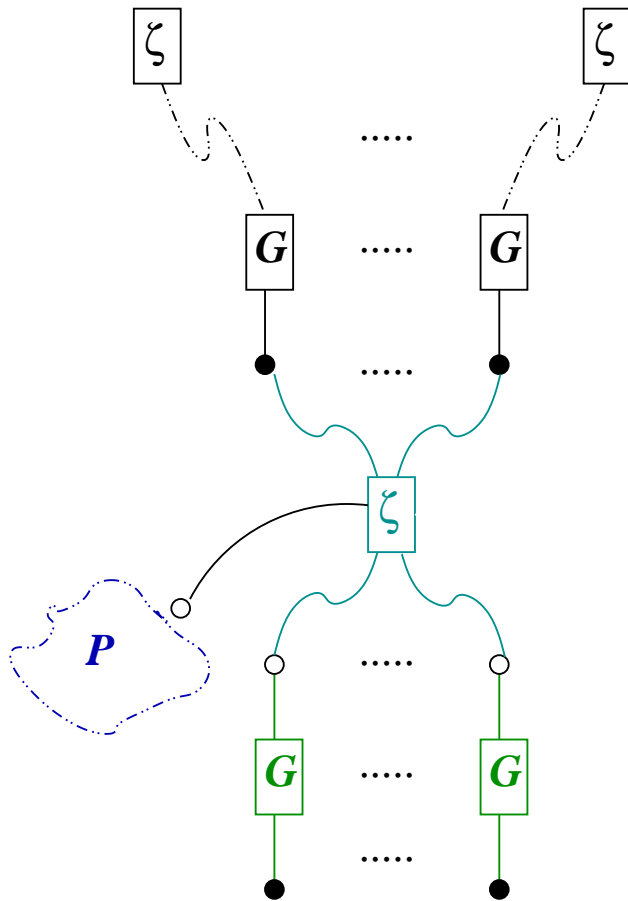
$$\langle c_1, \pi_1 \rangle \oplus \langle c_2, \pi_2 \rangle = \langle c_1 + c_2, \pi_1 \cup \pi_2 \rangle$$

$$\langle c_1, \pi_1 \rangle \otimes \langle c_2, \pi_2 \rangle = \begin{cases} \langle c_1 + c_2, \pi_1 \cap \pi_2 \rangle & \text{if } c_2 < c_1 \text{ and } \pi_2 \subset \pi_1 \\ \perp & \text{otherwise} \end{cases}$$



# Qlaim & Hypergraphs

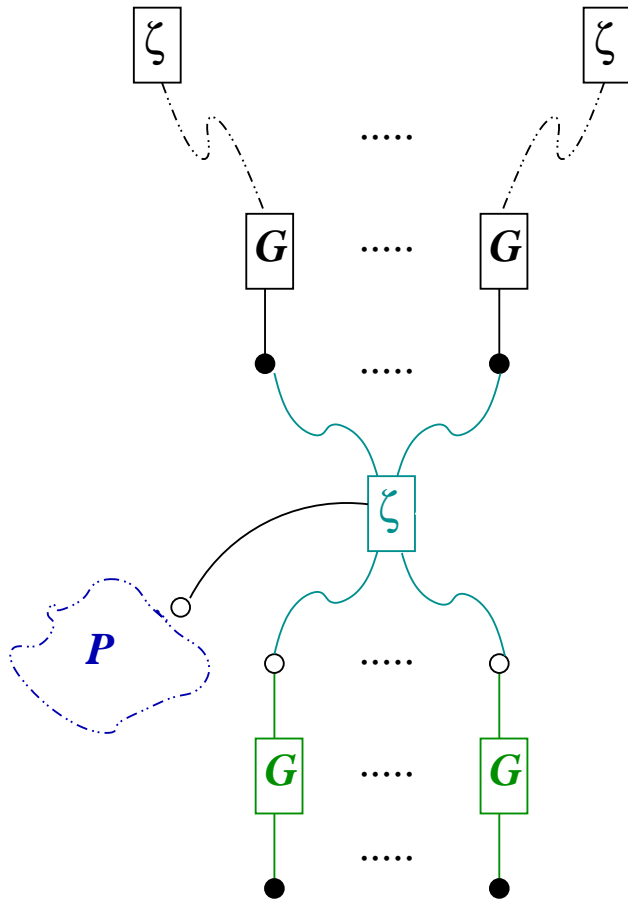
$$\llbracket s ::^L, P \rrbracket = \Gamma \vdash (\nu \vec{x}, p)(\llbracket P \rrbracket_p \mid \mathfrak{S}_{m,n}^s(\vec{u}, \vec{x}, p) \mid \prod_{j=1}^n G_{t_j}^{\kappa_j}(x_j, v_j))$$





# Qlaim & Hypergraphs

$$\llbracket s ::^L, P \rrbracket = \Gamma \vdash (\nu \vec{x}, p)(\llbracket P \rrbracket_p \mid \mathfrak{S}_{m,n}^s(\vec{u}, \vec{x}, p) \mid \prod_{j=1}^n G_{t_j}^{\kappa_j}(x_j, v_j))$$



$$\llbracket \mathbf{nil} \rrbracket_p = nil$$

$$\llbracket \mathbf{outt} \rrbracket_p = L_{\mathbf{outt}}(p)$$

$$\llbracket \gamma.P \rrbracket_p = L_{\gamma.P}(p)$$

$$\llbracket \mathbf{eval}(P)@s \rrbracket_p = (\nu u)(\mathbf{eval}_s^{T(P)}(u, p) \mid S_P(u))$$

$$\llbracket P_1 \mid P_2 \rrbracket_p = \llbracket P_1 \rrbracket_p \mid \llbracket P_2 \rrbracket_p$$

$$\llbracket \mathbf{rec} X.P \rrbracket_p = \llbracket P[\mathbf{rec} X.P / X] \rrbracket_p.$$



# Qlaim's Graph semantics: pros & cons

---



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- Many productions (recently reduced :-)



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# Qlaim's Graph semantics: pros & cons

- Many productions (recently reduced :-)
- + Determines the “optimal” path (also Qlaim)
- + Path reservation
- + Path routing







- Theorem** Qclaim remote actions are routed on paths with minimal cost  
(wrt the c-semiring operations)





# Hypergraph & Software Design

In [?] graph transformation is used for modelling dynamic behaviour of UML specifications.

- + Formal semantics of computations
- No local rewritings
- Distribution is not considered

SHR has been applied as a further refinement step in the software design process.





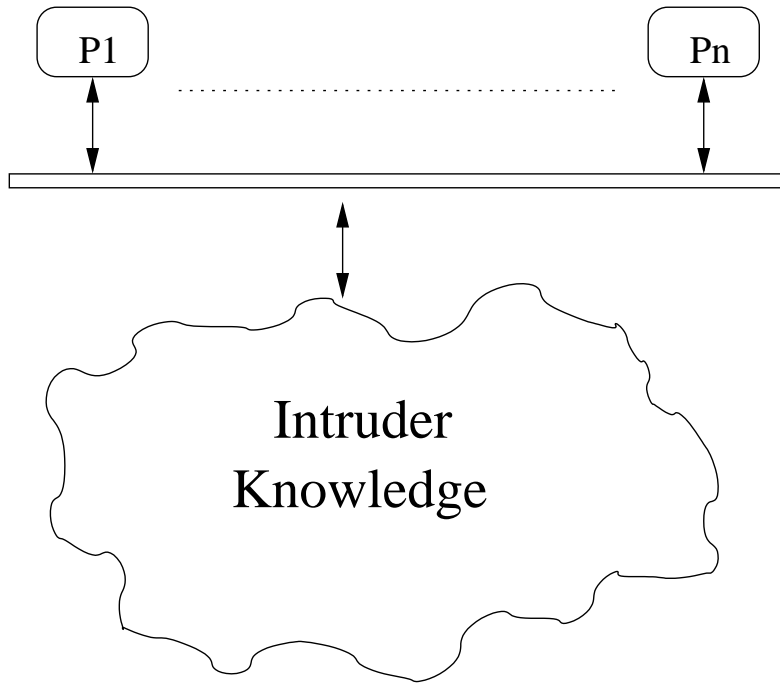
# Security

**In collaboration with A. Bracciali, A. Brogi and G. Ferrari**



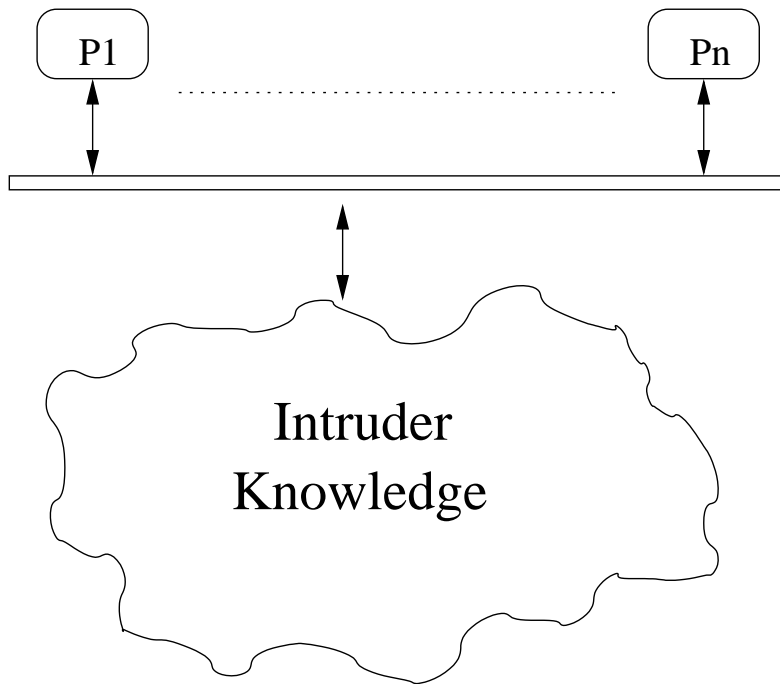


# The Dolev-Yao Model





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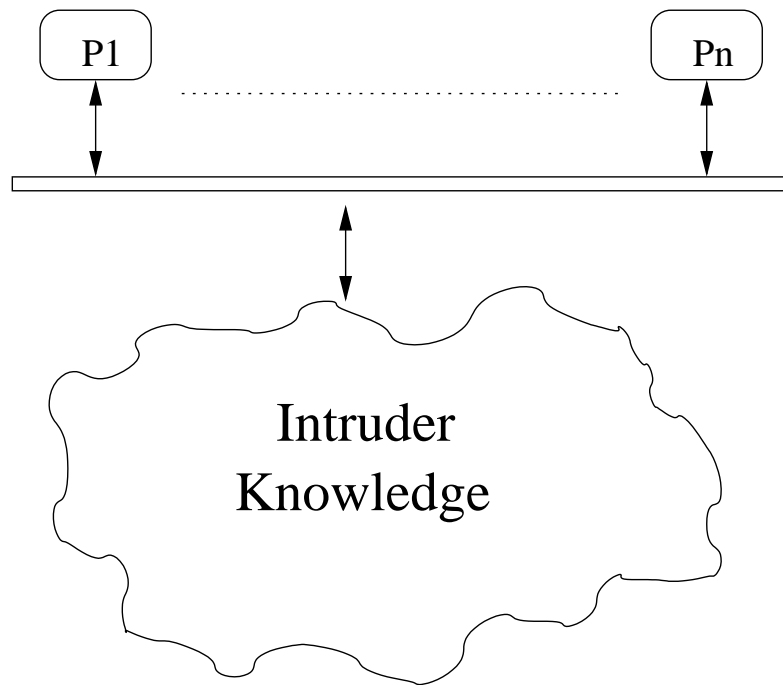


- Receive and store any transmitted message
- Hinder a message
- Decompose messages into parts
- Forge messages using known data
- Perfect Encryption Hypothesis





# The Dolev-Yao Model



- Receive and store any transmitted message
- Hinder a message
- Decompose messages into parts
- Forge messages using known data
- Perfect Encryption Hypothesis

**Names**  $n, m, \dots, A, B, S, \dots$

**Keys**  $k, k', \dots, A^+, A^-, \dots$

**Messages**  $M ::= N \mid K \mid M, M \mid \{M\}_M$





## Theorem $\bowtie$ is decidable



## Some design choices:

- Extension of **IP** [?]
- Cryptography & communication (pattern-matching)
- Key-sharing via “name fusion”
- Rôle based calculus
- Multi-session facilities

$$E, F ::= \mathbf{nil} \mid \alpha.E \mid E + E \mid E \parallel E$$

$$\alpha, \beta ::= in(d) \mid out(d)$$

$$d ::= N \mid K \mid d, d \mid \{d\}_d \mid x \mid ?x$$



1.  $A \rightarrow B : \{na, A\}_{B^+}$
2.  $B \rightarrow A : \{na, nb\}_{A^+}$
3.  $A \rightarrow B : \{nb\}_{B^+}$

$$A \triangleq (y) [ \text{out}(\{na, A\}_{y^+}). \\ \text{in}(\{na, ?u\}_{A^-}). \\ \text{out}(\{u\}_{y^+}) ]$$

$$B \triangleq () [ \text{in}(\{?x, ?z\}_{B^-}). \\ \text{out}(\{x, nb\}_{z^+}). \\ \text{in}(\{nb\}_{B^-}) ]$$

$$\boxed{
 \begin{array}{c}
 \frac{}{\alpha.E \xrightarrow{\alpha} E} \qquad \frac{E \xrightarrow{\alpha} E'}{E + F \xrightarrow{\alpha} E'} \\
 \\
 \frac{E \xrightarrow{\alpha} E'}{E \parallel F \xrightarrow{\alpha} E' \parallel F} \text{bn}(\alpha) \cap \text{fn}(F) = \emptyset
 \end{array}
 }$$

$$\boxed{
 \begin{array}{c}
 \frac{E_i \xrightarrow{\text{in}(d)} E'_i \quad \partial(\kappa) \triangleright m : \exists \sigma \text{ grounds.t. } d\sigma \sim m}{\langle (\tilde{X}_i)[E_i] \cup \mathcal{C}, \chi, \kappa \rangle \mapsto \langle (\tilde{X}_i)[E'_i\sigma] \cup \mathcal{C}, \chi\sigma, \kappa \rangle} \\
 \\
 \frac{E_i \xrightarrow{\text{out}(m)} E'_i}{\langle (\tilde{X}_i)[E_i] \cup \mathcal{C}, \chi, \kappa \rangle \mapsto \langle (\tilde{X}_i)[E'_i] \cup \mathcal{C}, \chi, \kappa \cup m \rangle} \\
 \\
 \frac{\mathcal{C}' = \text{join}(A_i, \gamma, \mathcal{C}) \quad A \triangleq (\tilde{X})[E] \quad i \text{ new}}{\langle \mathcal{C}, \chi, \kappa \rangle \mapsto \langle \mathcal{C}', \chi\gamma, \kappa \cup \{A_i\} \rangle}
 \end{array}
 }$$

# A symbolic cIP trace

$$\langle (y_1)[\text{out}(\{na_1, A_1\}_{y_1^+}).in(\{na_1, ?u_1\}_{A_1^-}).out(\{u_1\}_{y_1^+})], \varepsilon, \{A_1\}\rangle$$

$$\left\{ \begin{array}{l} o \{na_1, A_1\}_{y_1^+} \\ \vee \end{array} \right.$$

$$\langle (y_1)[in(\{na_1, ?u_1\}_{A_1^-}).out(\{u_1\}_{y_1^+})], \varepsilon, \{A_1, \{na_1, A_1\}_{y_1^+}\}\rangle$$

$$\left\{ \begin{array}{l} j \ B_2 \ [^{B_2}/_{y_1}] \\ \vee \end{array} \right.$$

$$\kappa = \{A_1, B_2, \{na_1, A_1\}_{B_2^+}\}$$

$$\langle \begin{array}{l} ()[in(\{na_1, ?u_1\}_{A_1^-}).out(\{u_1\}_{B_2^+})], \\ ()[\text{in}(\{?x_2, ?z_2\}_{B_2^-}).out(\{x_2, nb_2\}_{z_2^+}).in(\{nb_2\}_{B_2^-})] \end{array}, \ [^{B_2}/_{y_1}], \ \kappa \rangle$$

$$\left\{ \begin{array}{l} i \ \{x_2(\kappa), A_1^+\}_{B_2^+} \\ \vee \end{array} \right.$$

$$\langle \begin{array}{l} ()[in(\{na_1, ?u_1\}_{A_1^-}).out(\{u_1\}_{B_2^+})], \\ ()[out(\{x_2(\kappa), nb_2\}_{A_1^+}).in(\{nb_2\}_{B_2^-})] \end{array}, \ [B_2, x_2(\kappa), A_1 / y_1, x_2, z_2], \ \kappa \rangle$$





# $\mathcal{PL}$ : Formalising Security Properties

$$\begin{array}{lcl}
 \phi, \psi & ::= & \delta \in \mathcal{K} \\
 & | & \forall \alpha : A. \phi \\
 & | & x @ \alpha = \delta \\
 & | & \alpha = \beta \\
 & | & \neg \phi \mid \phi \wedge \psi \\
 \delta & ::= & d \mid \alpha \mid x @ \alpha
 \end{array}$$

$$\kappa \models_{\chi} \phi$$

*“If  $B$  completes a protocol session and thinks that he has been talking to  $A$ , then  $A$  had started a protocol session thinking that she has been talking to  $B$ ”*

$$\forall \beta : B. \exists \alpha : A. (z @ \beta = \alpha \rightarrow y @ \alpha = \beta)$$





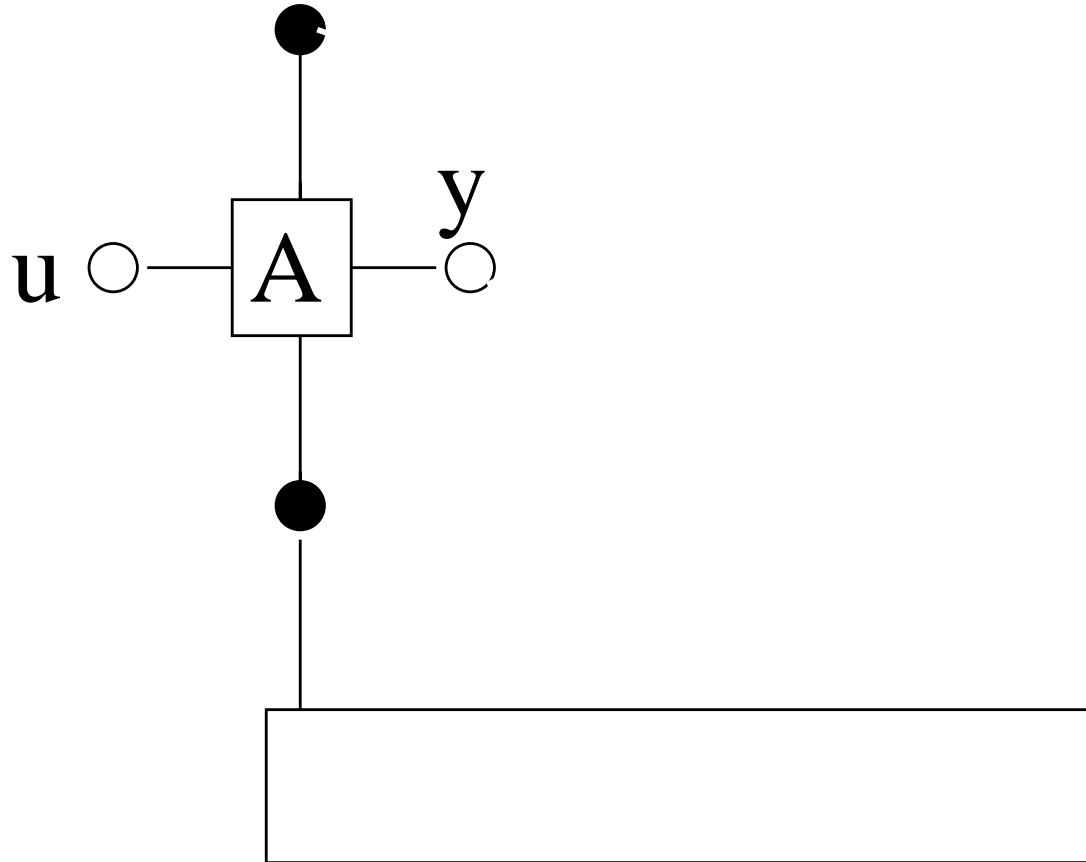
# Hypergraphs for security

$$A \stackrel{\Delta}{=} (y) [ \text{out}(\{na, A\}_{y^+}). \\ \text{in}(\{na, ?u\}_{A^-}). \\ \text{out}(\{u\}_{y^+}) ]$$

$$B \stackrel{\Delta}{=} () [ \text{in}(\{?x, ?z\}_{B^-}). \\ \text{out}(\{x, nb\}_{z^+}). \\ \text{in}(\{nb\}_{B^-}) ]$$



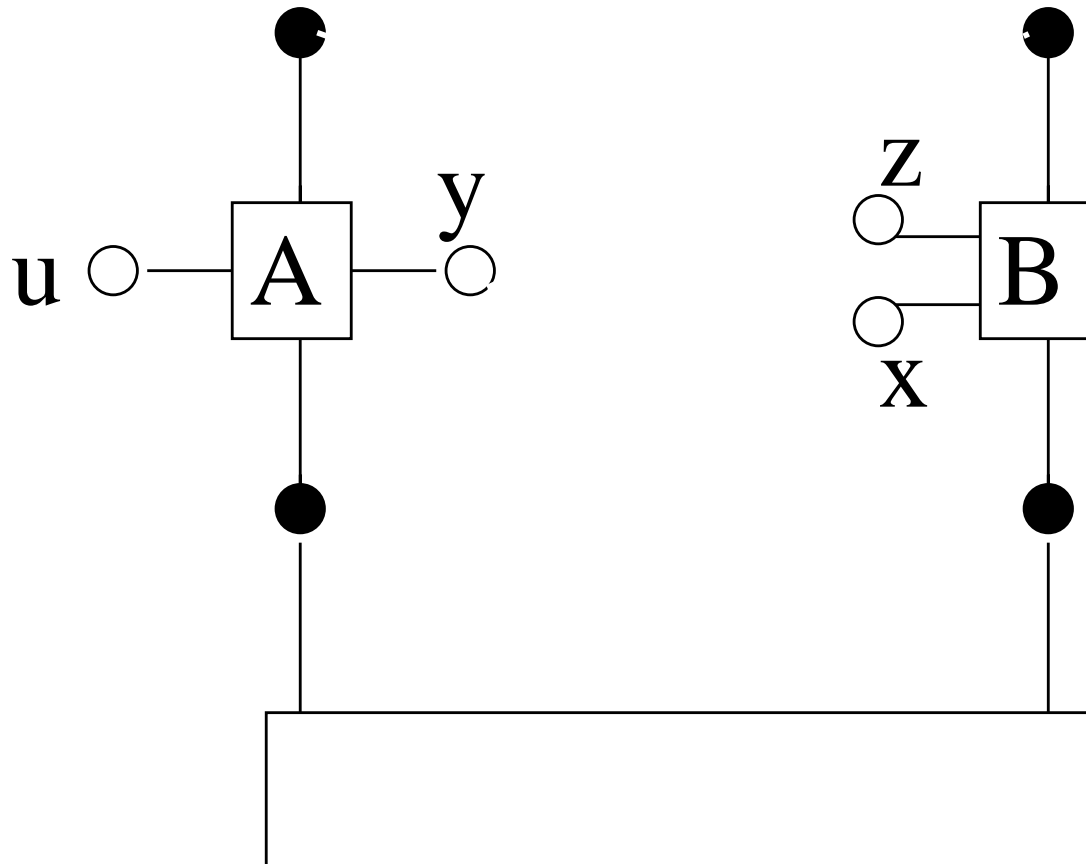
# Hypergraphs for security



$$A^{\triangle}(y)[ \text{out}(\{na, A\}_{y^+}). \\ \text{in}(\{na, ?u\}_{A^-}). \\ \text{out}(\{u\}_{y^+}) ]$$

$$B^{\triangle}()[ \text{in}(\{?x, ?z\}_{B^-}). \\ \text{out}(\{x, nb\}_{z^+}). \\ \text{in}(\{nb\}_{B^-}) ]$$

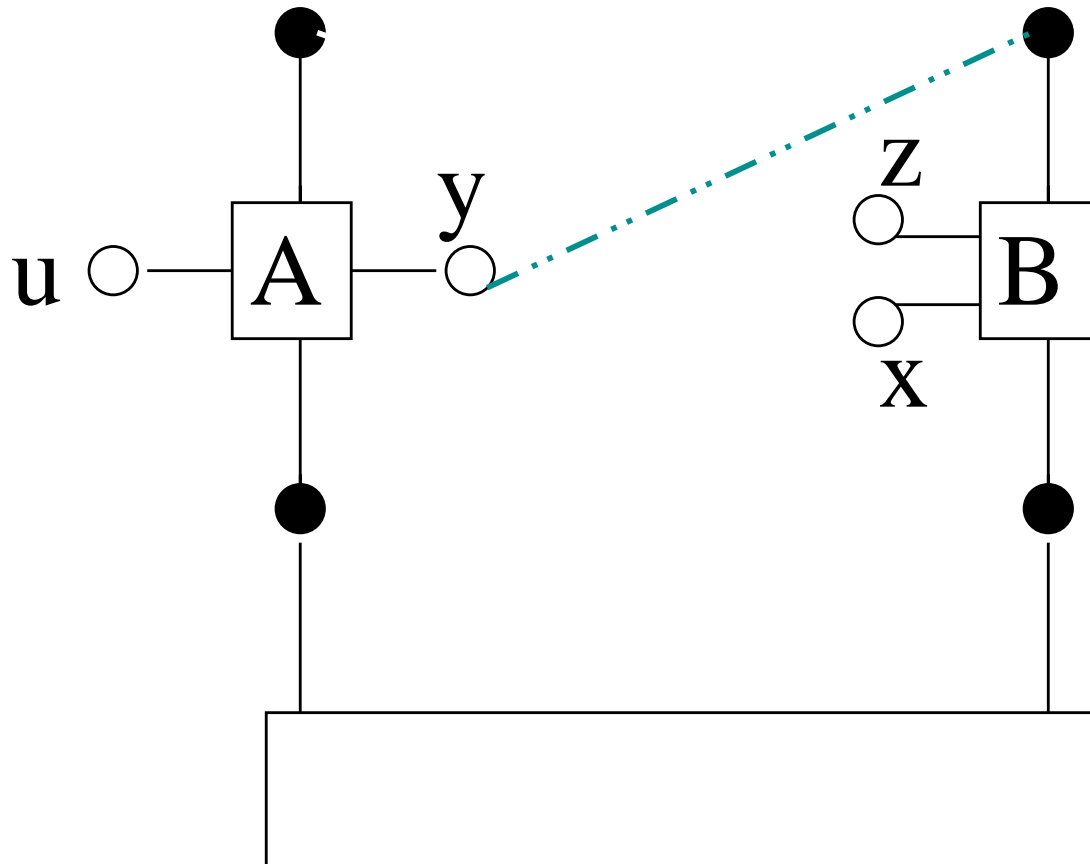
# Hypergraphs for security



$$A^{\triangle}(y)[ \text{out}(\{na, A\}_{y+}). \\ \text{in}(\{na, ?u\}_{A-}). \\ \text{out}(\{u\}_{y+}) ]$$

$$B^{\triangle}()[ \text{in}(\{?x, ?z\}_{B-}). \\ \text{out}(\{x, nb\}_{z+}). \\ \text{in}(\{nb\}_{B-}) ]$$

# Hypergraphs for security

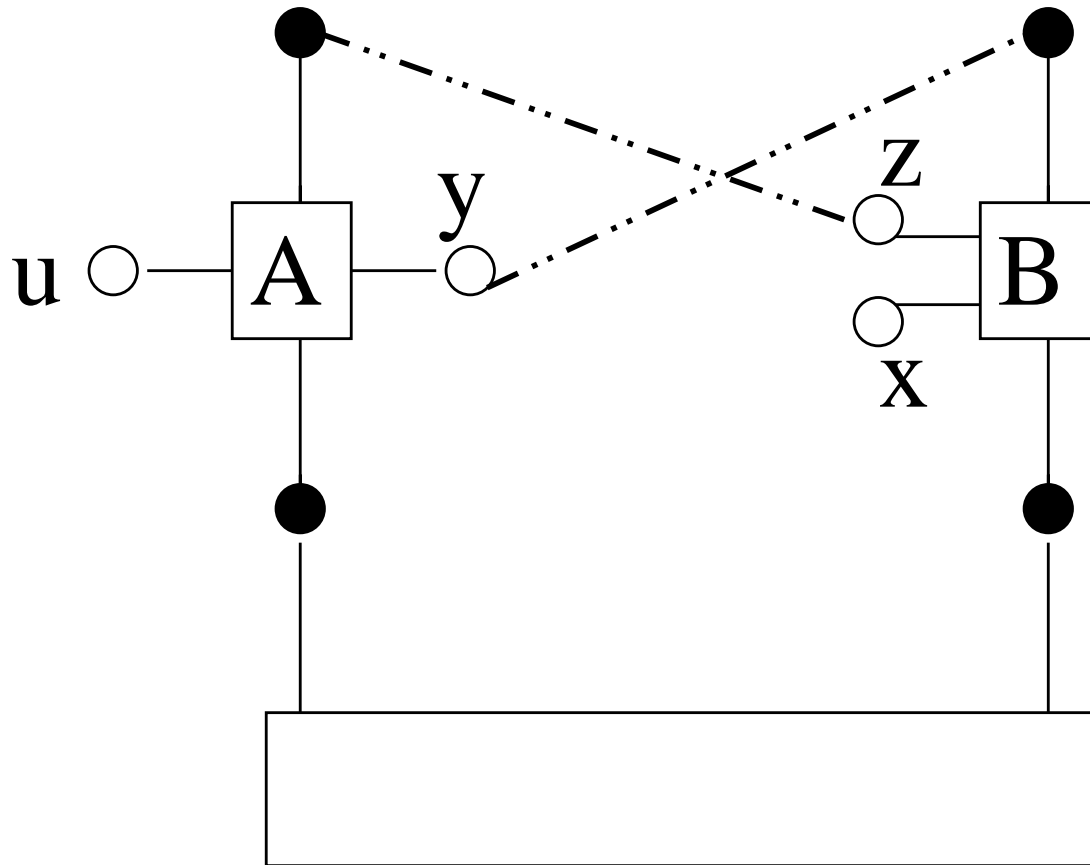


$$A^{\triangle}(y)[ \text{out}(\{na, A\}_{y+}). \\ \text{in}(\{na, ?u\}_{A-}). \\ \text{out}(\{u\}_{y+}) ]$$

$$B^{\triangle}()[ \text{in}(\{?x, ?z\}_{B-}). \\ \text{out}(\{x, nb\}_{z+}). \\ \text{in}(\{nb\}_{B-}) ]$$



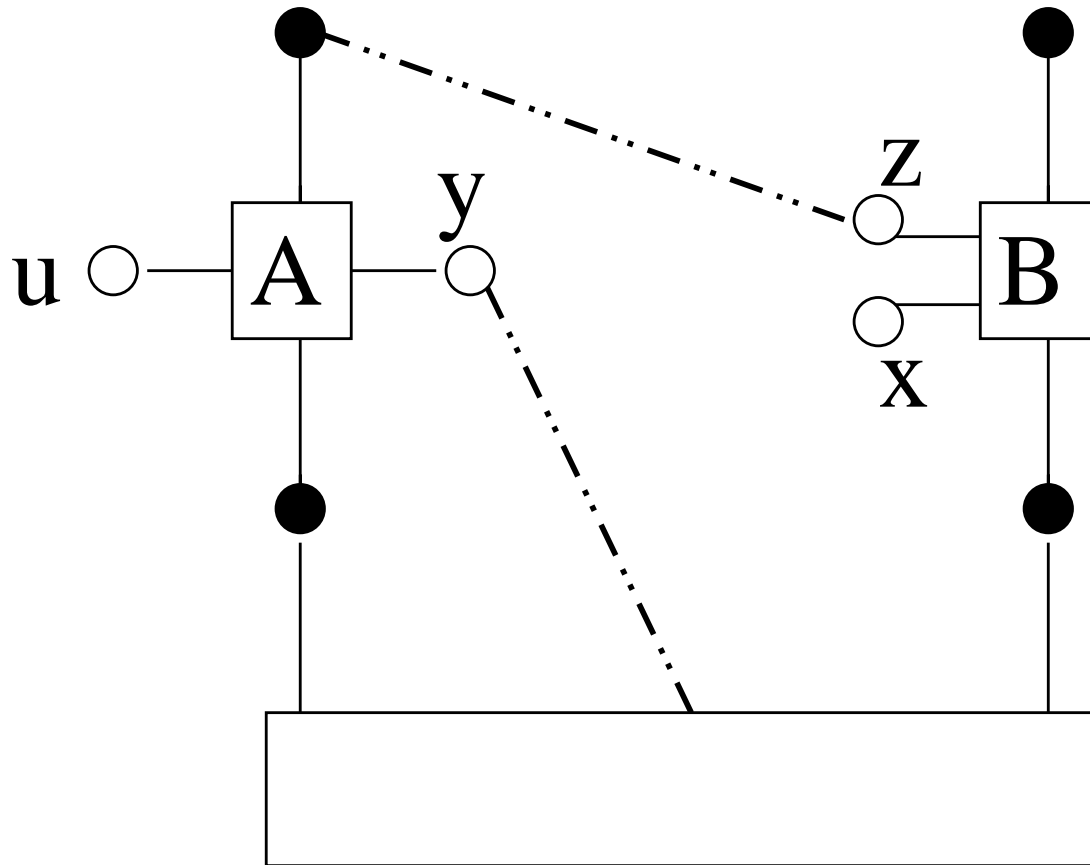
# Hypergraphs for security



$$A^{\triangle}(y)[ \text{out}(\{na, A\}_{y+}). \\ \text{in}(\{na, ?u\}_{A-}). \\ \text{out}(\{u\}_{y+}) ]$$

$$B^{\triangle}()[ \text{in}(\{?x, ?z\}_{B-}). \\ \text{out}(\{x, nb\}_{z+}). \\ \text{in}(\{nb\}_{B-}) ]$$

# Hypergraphs for security

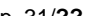


$$A^{\triangle}(y)[ \text{out}(\{na, A\}_{y+}). \\ \text{in}(\{na, ?u\}_{A-}). \\ \text{out}(\{u\}_{y+}) ]$$

$$B^{\triangle}()[ \text{in}(\{?x, ?z\}_{B-}). \\ \text{out}(\{x, nb\}_{z+}). \\ \text{in}(\{nb\}_{B-}) ]$$



**In collaboration with G. Ferrari, U. Montanari and R. Raggi**

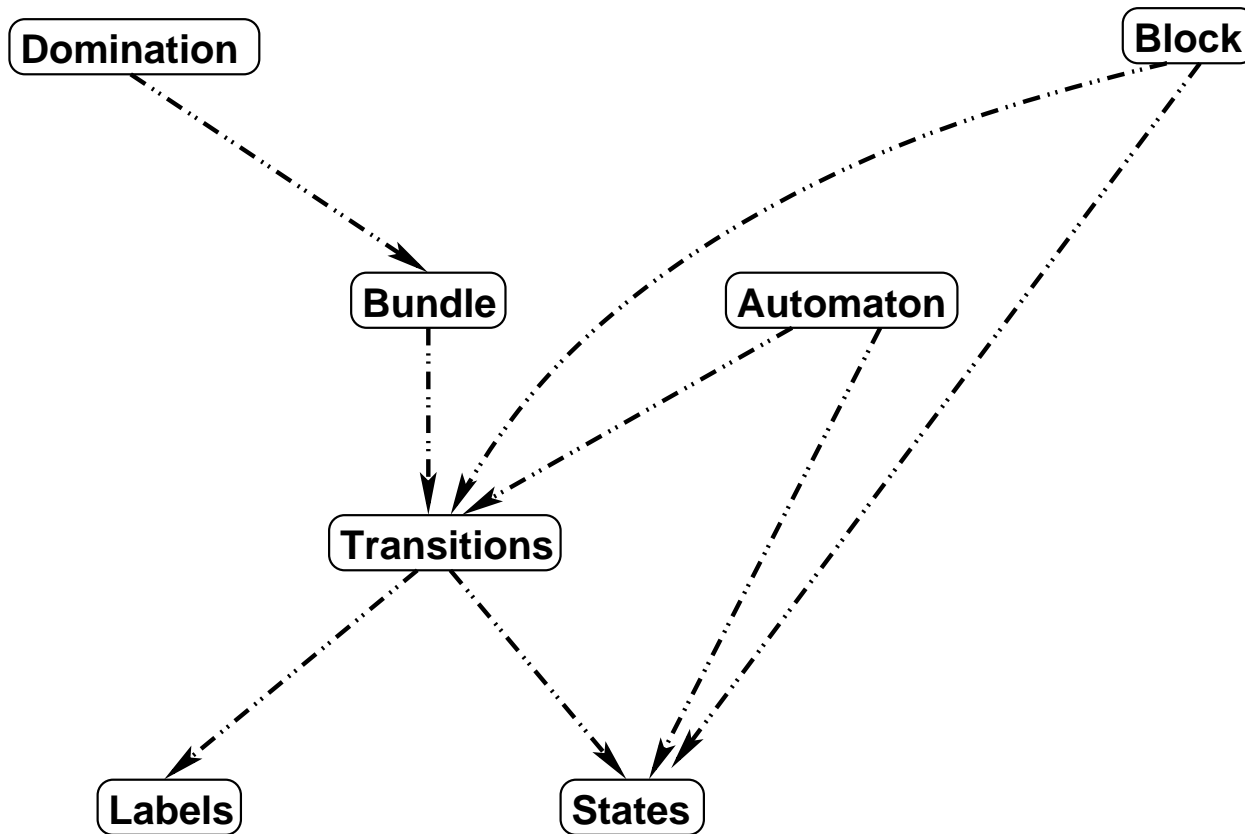


## Minimizing History Dependent Automata:

- HD-automata for history dependent calculi
- Co-algebraic specification
- Partition Refinement Algorithm based on co-algebraic specification [?]
- Mihda: Ocaml implementation (refining  $\lambda^{\rightarrow, \Pi, \Sigma}$  spec.)

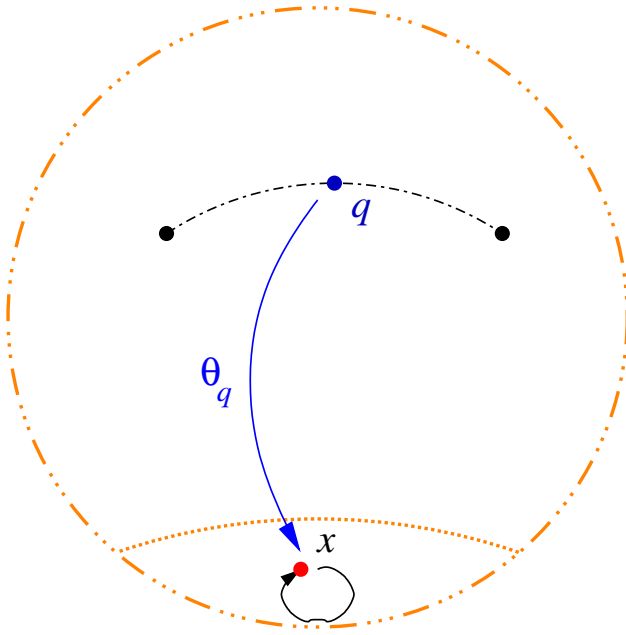
|           | Comp. Time | States | Trans. | Min. Time  | States | Trans. |
|-----------|------------|--------|--------|------------|--------|--------|
| GSM small | 0m 0.931s  | 211    | 398    | 0m 4.193s  | 105    | 197    |
| GSM full  | 0m 8.186s  | 964    | 1778   | 0m 54.690s | 137    | 253    |

# Mihda Architecture

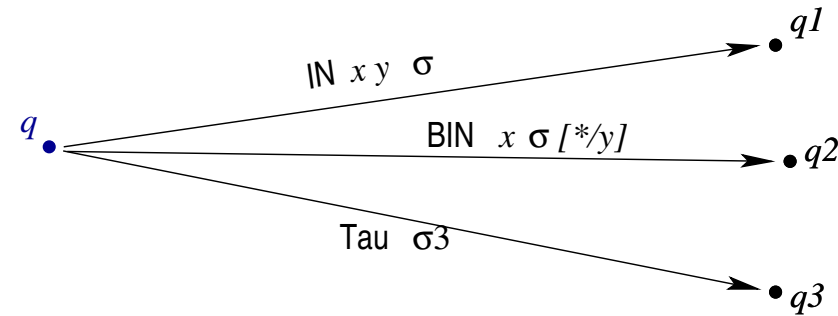
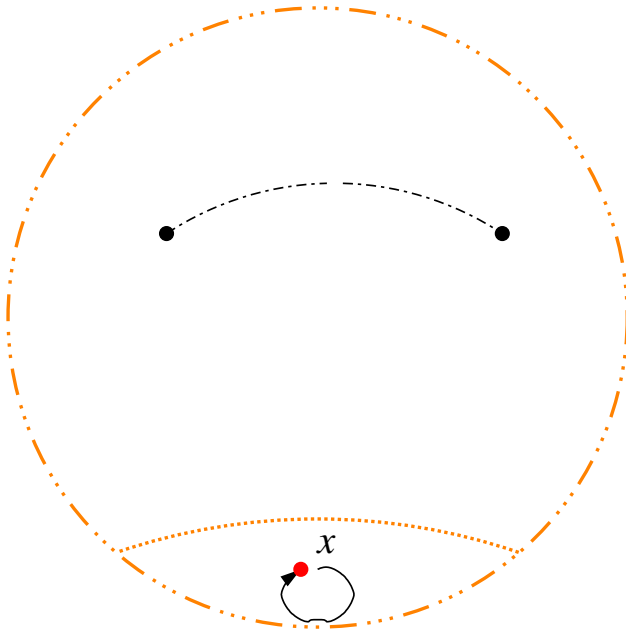


- Adherent to specs
- Highly modular
- Easily extendible

# The main step



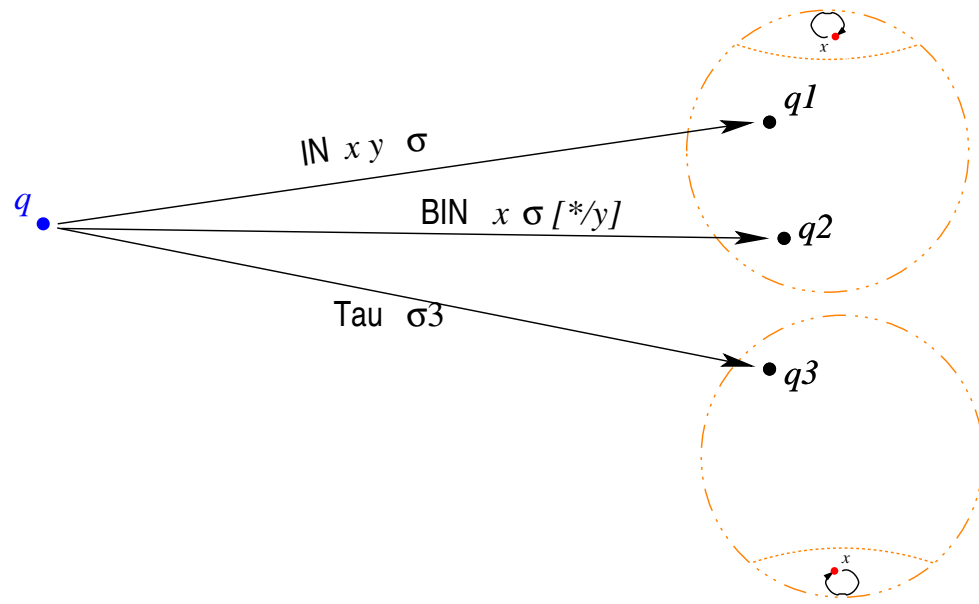
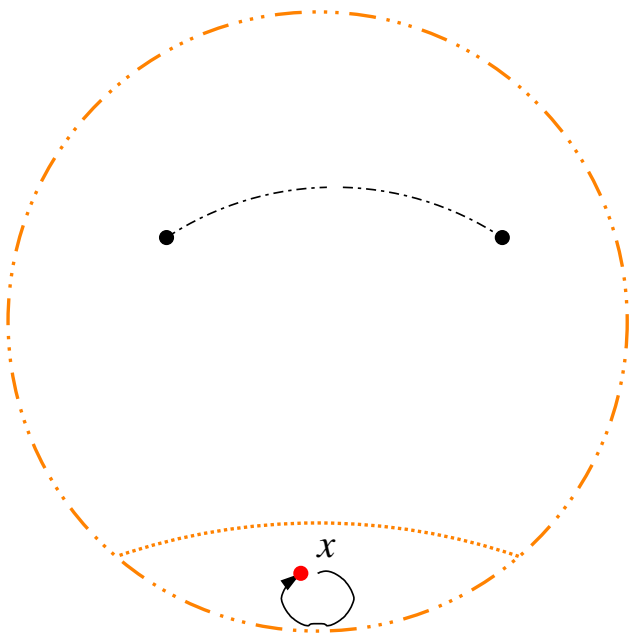
# The main step



let bundle hd  $q$  =  
 List.sort compare  
 (List.filter (fun h  $\rightarrow$  (Arrow.source h) =  $q$ ) (arrows hd))



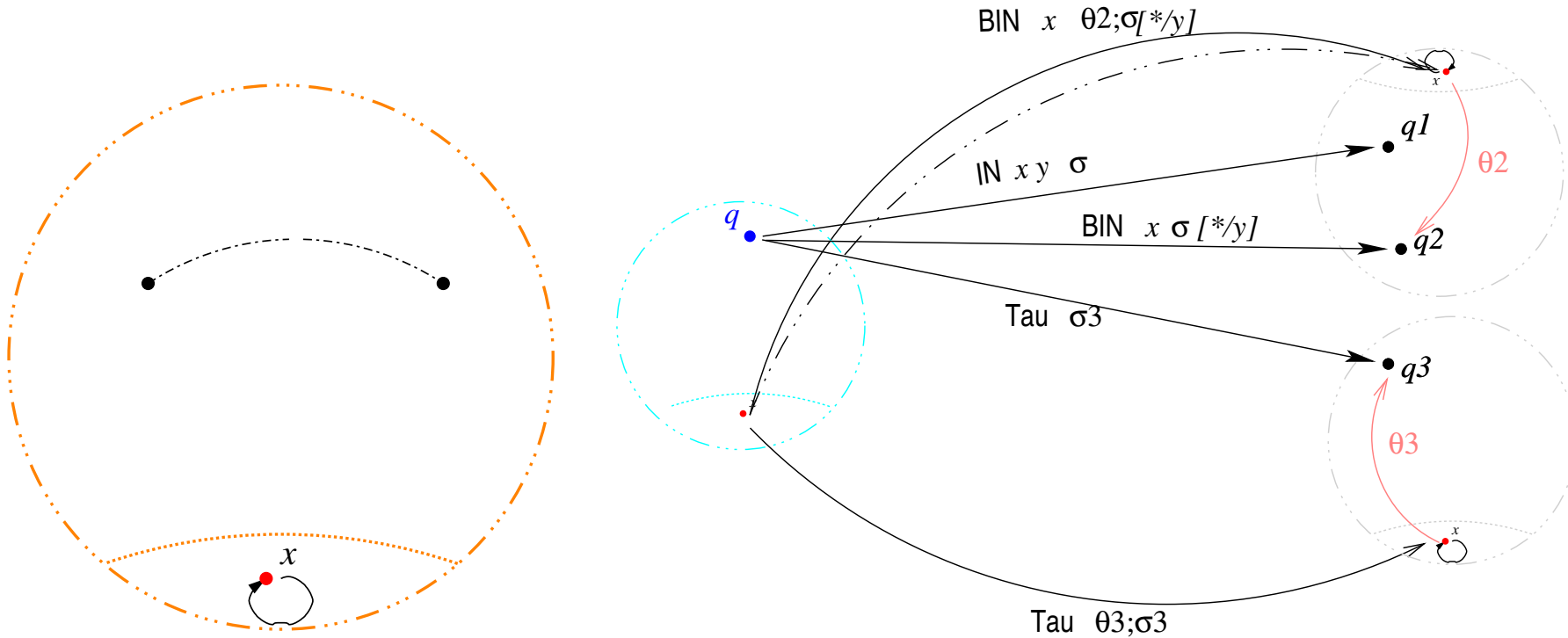
# The main step



List.map  $h_n$  bundle



# The main step



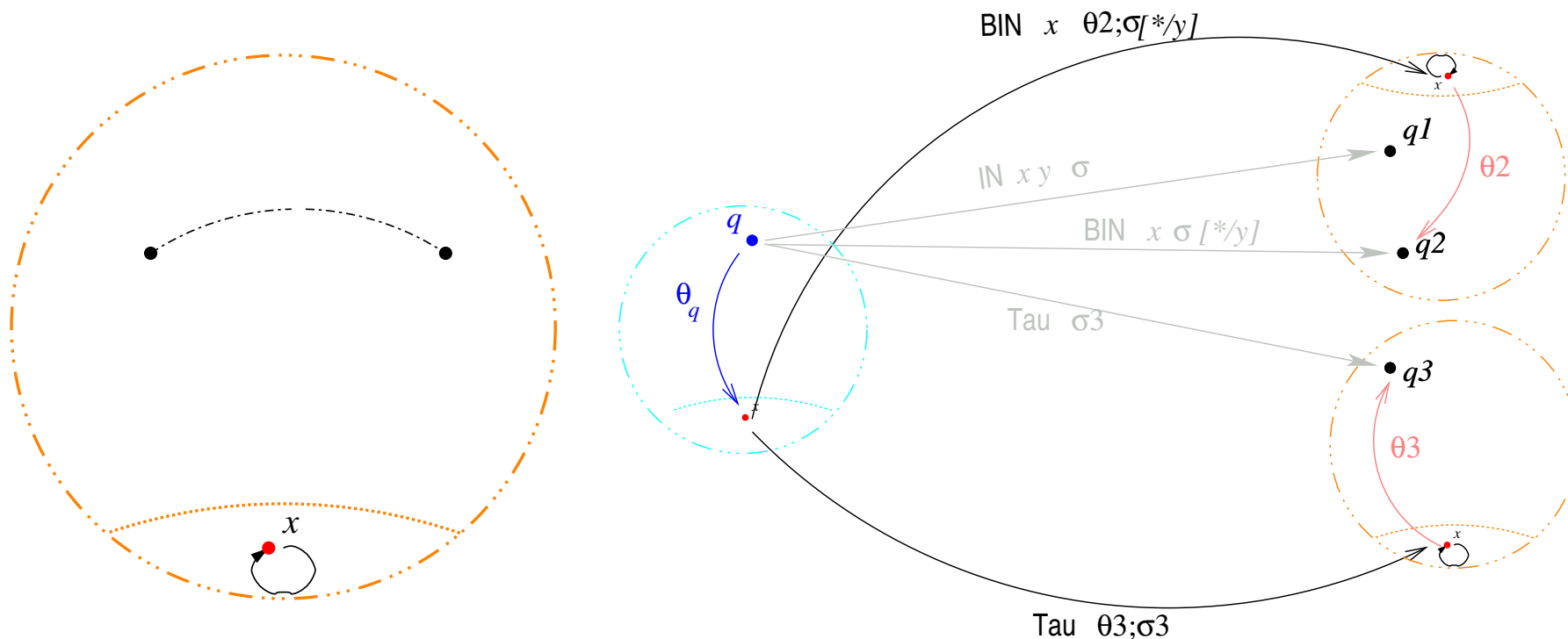
$$h_{n+1} = \text{norm} \langle \text{states}, \{ \langle \ell, \pi, h_n(q'), \sigma'; \sigma \rangle \mid q \xrightarrow{\ell \pi \sigma} q' \wedge \sigma' \in \Sigma_n(q') \} \rangle$$

let red bl = .....

let bl\_in = List.filter covered\_in bl

in list\_diff bl bl\_in

# The main step

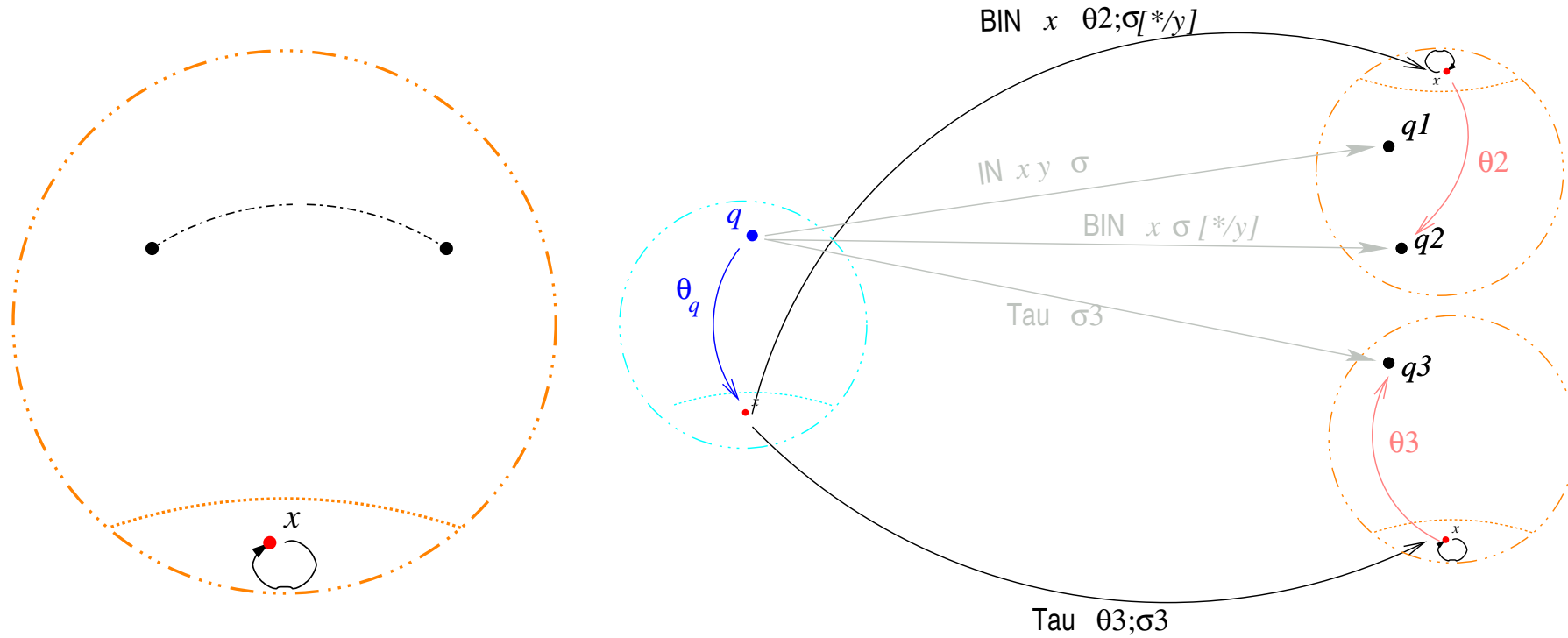


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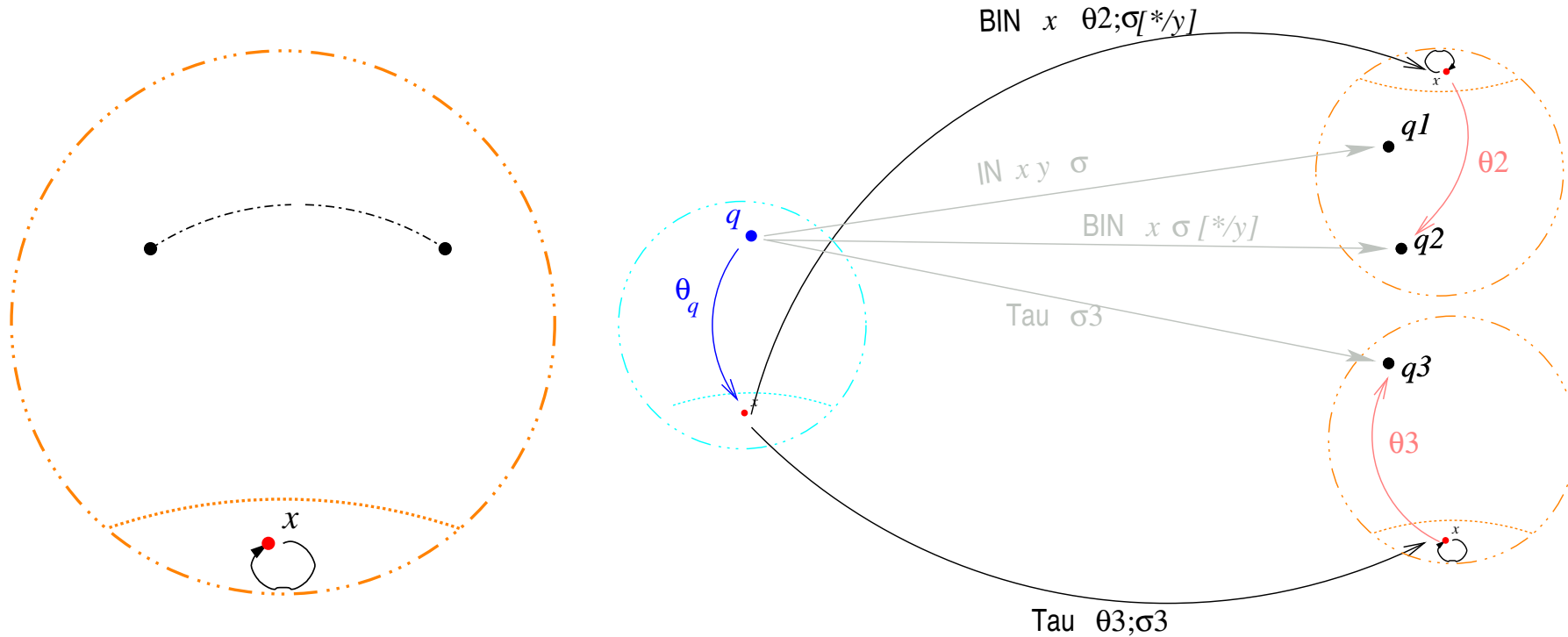
let an = active_names_bundle (red bundle) in
let remove_in ar = match ar with
| Arrow(_,_,In(_,_)) → not (List.mem (obj ar) an)
| _ → false in
list_diff bundle (List.filter remove_in bundle)
  
```



# The main step



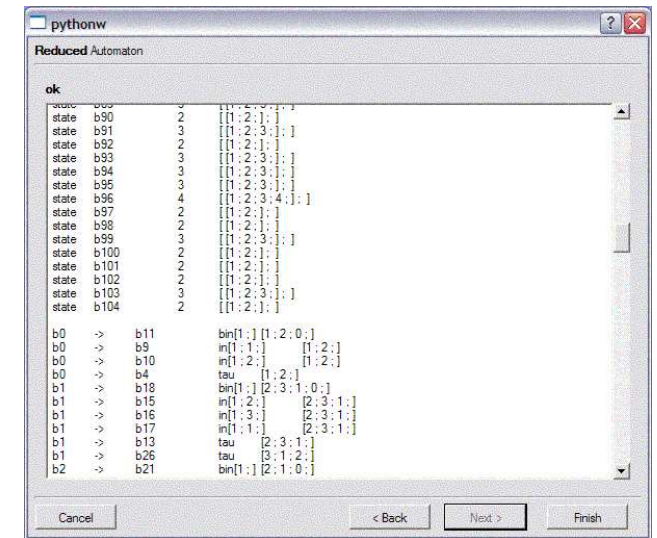
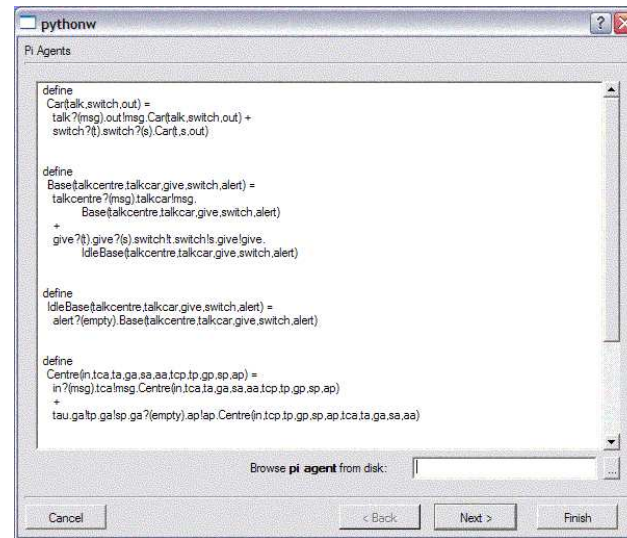
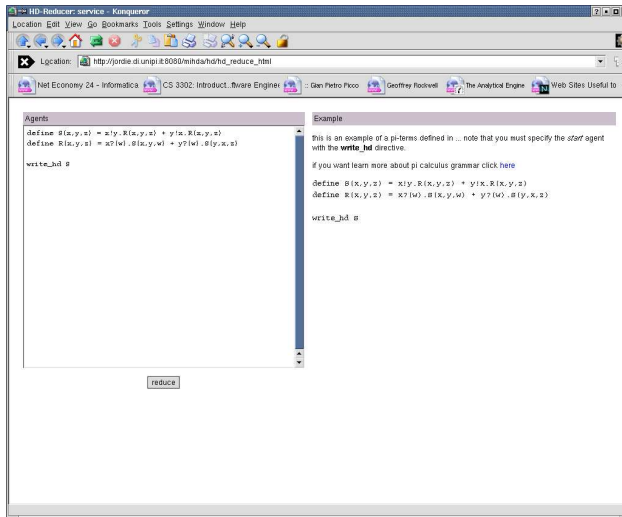
$$\Sigma_{n+1}(q) = (\text{compute\_group} \text{ (norm bundle)}) ; \theta_q^{-1}$$



$$\Sigma_{n+1}(q) = (\text{compute\_group} \text{ (norm bundle)}) ; \theta_q^{-1}$$

**Theorem** At the end of each iteration  $i$  blocks corresponds to  $h_{H_i}$

# Mihda Web Interface



<http://jordie.di.unipi.it:8080/pweb>

- Declarative approach to WAN programming
  - Foundational aspects
  - QoS at application level
  - Modelling wireless communications (ongoing)
  - Integrating Milner & Hoare synchronizations
  - Web Services
  - Secure composition of components
  - Coordination mechanism
- Tool development
  - Distributed infrastructure
  - Base on Web Services metaphor
  - Proof strategies as programmable coordinators



# Published papers

- Ferrari, G., Pugliese, R., Tuosto, E. [Calculi for Network Aware Programming](#). WOA'00
- Ferrari, G., Montanari, U., Tuosto, E. [LTS Semantics of Ambients via Graph Synchronization with Mobility](#). ICTCS'01
- Bracciali, A., Brogi, A., Ferrari, G., Tuosto, E.. [Security Issues in Component Based Design](#). ConCoord'01
- Bracciali, A., Brogi, A., Ferrari, G., Tuosto, E., [Security and Dynamic Compositions of Open Systems](#). PDPTA'02
- Ferrari, G., Montanari, U., Tuosto, E. [Graph-based Models of Internetworking Systems](#). UNU/IIST Colloquium'03
- R. De Nicola, G. Ferrari, Ugo Montanari, R. Pugliese [A Formal Basis for Reasoning on Programmable QoS](#). International Symposium on Verification'03



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