

Choreography Synthesis as Contract Agreement

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We propose a formal model for distributed systems, where each participant advertises its requirements and obligations as behavioural *contracts*, and where multiparty sessions are started when a set of contracts allows to synthesise a *choreography*. Our framework is based on the CO₂ calculus for contract-oriented computing, and borrows concepts and results from the session type literature.

It supports sessions where the number of participants is not determined beforehand, and keeps CO₂'s ability to rule out which participants are *culpable* if contracts are not fulfilled at runtime. We show that we have *progress* and *session fidelity* in CO₂, as a result of the *honesty* of participants — i.e., their ability to always adhere to their contracts.

1 Introduction

Distributed applications are nowadays omnipresent but even for seemingly simple cases, there is still a pressing need to make sure they do work as their designers intended. Indeed, such systems are difficult to design, verify, implement, deploy, and maintain. Besides the intrinsic issues due to the underlying execution model (concurrency, physical distribution, etc.), applications have to be designed within a strange paradox: they are made of components that, on the one hand, collaborate with each other and, on the other hand, may compete for resources, or for achieving conflicting goals. This paradox is especially relevant in inter-organisational service-oriented scenarios, where services may be deployed by different entities: even under common policies, the implementations may reflect diverging and changing requirements, up to the point of departing from the agreed specifications. This issue is reflected in standards such as [11], which includes runtime monitoring and logging to check that interactions in SOAs actually adhere to agreed policies and service descriptions.

We propose a formal model for distributed systems where *contracts* drive interactions: components advertise behavioural contracts, such contracts are used at runtime to establish multiparty *agreements*, and such agreements steer the behaviour of components. Therefore, contracts are not just a specification or a design mechanism any more, rather they become a pivotal element of the execution model.

In this work we combine two approaches: *session types* [9] and *contract-oriented computing* [5]. From the former, we adopt concepts, syntax and semantics — and in particular, the interplay between local behaviours and choreographies (i.e., between local types and global types) as a method for specifying and analysing the interactions of participants in a distributed system. However, in our framework we do not assume that a participant will necessarily always adhere to its specification, nor that a global description is available beforehand to validate the system.

We adopt CO₂ [4], a generic contract-oriented calculus where participants advertise their requirements and obligations through contracts, and interact with each other once *compliant* contracts have been found. Here, we tailor CO₂ to a multiparty model where contracts have the syntax of local types. We say that contracts c_1, \dots, c_n are compliant when, roughly, they can be used to synthesise a choreography — i.e., a global type whose projections are c_1, \dots, c_n themselves [10]. Once a set of compliant contracts has been found, a CO₂ session may be established, wherein the participants who advertised

the contracts can interact. However, in line with what may happen in real life scenarios, the runtime behaviour of these participants may then depart from the contracts: the calculus allows to model these situations, and reason about them.

1.1 Contributions

Our framework models multiparty contractual agreements as “tangible” objects — i.e., choreographies. This allows us to rely on results and properties from the session type literature — in particular, the well-formedness of a choreography ensures that contractual agreements enjoy knowledge of choice, error/deadlock freedom, and progress. Furthermore, it allows us to easily check that some meta-level properties are satisfied at runtime, e.g. on the number of involved participants, whether or not the session may terminate, etc.

Our adaptation of CO₂ to a multiparty, choreography-based contract model preserves the properties of the original calculus. In particular, if a system gets stuck, it is possible to identify which participants violated their contracts.

We also discuss how the properties of a well-formed choreography are reflected in a context where participants can misbehave. We introduce global progress and session fidelity in CO₂, again inspired by analogous concepts in theories based on session types. We show that they hold in systems where all participants are *honest* (i.e., always respect their contracts in any context) — even when a participant takes part in multiple sessions.

Synopsis. The rest of the paper is structured as follows. In the rest of this section, we introduce an example that we use to motivate and illustrate our framework. In Section 2, we introduce a multiparty contract model based on choreography synthesis. In Section 3, we present our version of CO₂ and highlight its main features. In Section 4, we define the notion of *honesty*, and its practical importance in our contract-oriented scenario. In Section 5, we present our results, which link the notion of honesty to the progress and safety of a CO₂ system (due to lack of space, the proofs are omitted). Finally, we discuss related work and conclude in Section 6.

1.2 A motivating example

We introduce a simple example that we will use throughout the paper to illustrate our framework. We use A, B, \dots for participant names, and a, a', b, \dots for participant variables, and use the colour **blue** to highlight contracts.

An on-line store A allows two buyers b_1 and b_2 to make a joint purchase through a simplified protocol: after they both request the same item, a quote is sent to b_1 , who is then expected to either place an order or end the session (bye); the store also promises to notify b_2 about whether the order was placed (ok) or cancelled (bye). A 's behaviour is described by the following contract:

$$c_A = b_1?req; b_2?req; b_1!quote; (b_1?order; b_2!ok + b_1?bye; b_2!bye)$$

What kind of contracts would be compliant with c_A ? One answer consists in the following contracts, advertised by buyers B_1 and B_2 .

$$\begin{aligned} c_{B_1} &= a!req; a?quote; (b'_2!ok; a!order \oplus b'_2!bye; a!bye) \\ c_{B_2} &= a!req; (b'_1?ok; a'?ok + b'_1?bye; a'?bye) \end{aligned}$$

Here, B_1 promises to send the request to the store (a), wait for the quote, and then notify the other buyer (b'_2) before accepting or rejecting the store offer; symmetrically, B_2 's contract sends the request to the store (a'), and then expects to receive the same notification (either ok or bye) from both the other buyer (b'_1) and the store itself. Each contract represents the local viewpoint of the participant who advertises it: c_A represents the local viewpoint of the store, and thus it does not (and indeed, it cannot) capture the communications between B_1 and B_2 .

An agreement among c_A , c_{B_1} and c_{B_2} may be found by replacing the participant variables in each contract with actual names, e.g. with substitutions $\{A/a, a'\}$, $\{B_1/b_1, b'_1\}$ and $\{B_2/b_2, b'_2\}$. Such an agreement is based on the existence of the following choreography (i.e., global type), which can be synthesised similarly to what is done in [10]:

$$\begin{aligned} \mathcal{G}_{AB_1B_2} = & B_1 \rightarrow A : req ; B_2 \rightarrow A : req ; A \rightarrow B_1 : quote ; \\ & (B_1 \rightarrow B_2 : ok ; B_1 \rightarrow A : order ; A \rightarrow B_2 : ok \quad + \quad B_1 \rightarrow B_2 : bye ; B_1 \rightarrow A : bye ; A \rightarrow B_2 : bye) \end{aligned}$$

The ability to synthesise $\mathcal{G}_{AB_1B_2}$ guarantees that the global type is well-formed and projectable back to the initial contracts c_A , c_{B_1} and c_{B_2} (with the substitutions above); this, in turn, guarantees progress and safety [10] of the contractual agreement.

However, in a realistic scenario, the existence of a contractual agreement among participants does not guarantee that progress and safety will also hold at runtime: in fact, a participant may advertise a contract promising some behaviour, and then fail to respect it — either maliciously or accidentally. Such failure may then cascade on other participants, e.g. if they remain stuck waiting for a promised message that is never sent.

This sort of situations can be modelled using the CO_2 calculus. A CO_2 system for the store-and-two-customers example may be implemented as follows:

$$S_1 = (x, y, z) (A[\text{tell}_A \downarrow_x c_A \cdot \text{fuse} \cdot P_A] \mid B_1[\text{tell}_A \downarrow_y c_{B_1} \cdot P_{B_1}] \mid B_2[\text{tell}_A \downarrow_z c_{B_2} \cdot P_{B_2}])$$

Here, participant A advertises its contract c_A to itself via the primitive $\text{tell}_A \downarrow_x c_A$, where x is used as a session handle for interacting with other participants. B_1 and B_2 advertise their respective contracts to A with a similar invocation.

In this example, A also plays the role of *contract broker*: once all contracts have been advertised, the *fuse* prefix can establish a new session, based on the fact that the global agreement $\mathcal{G}_{AB_1B_2}$ can be synthesised from c_A , c_{B_1} and c_{B_2} . This new session is shared among participants A , B_1 and B_2 .

At this point, the execution of the system (i.e., the reduction of processes P_A , P_{B_1} and P_{B_2}) is not required to respect the contracts. In fact, we will see that when the contracts are violated, the calculus allows for *culpable* participants to be always ruled out. Furthermore, we will discuss *honesty*, i.e. the guarantee that a participant will always fulfil its advertised contracts — even in contexts where other participants fail to fulfil theirs. When such a guarantee holds, the contractual progress and safety are also reflected in the runtime behaviour of the CO_2 system.

Other possible agreements. Our contract model allows for other scenarios. For instance, a participant B_{12} may impersonate both customers, and promise to always accept the store offer, by advertising the following contract:

$$c_{B_{12}} = a''!req; a''!req; a''?quote; a''!order; a''?ok$$

where the request to the store (a'') is sent twice (i.e., once for each impersonated customer). In this case, if we combine c_A and $c_{B_{12}}$ with substitutions $\{A/a''\}$, $\{B_{12}/b_1, b_2\}$, we can find an agreement by synthesising

the following global type:

$$\mathcal{G}_{AB_{12}} = B_{12} \rightarrow A : \text{req}; B_{12} \rightarrow A : \text{req}; A \rightarrow B_{12} : \text{quote}; B_{12} \rightarrow A : \text{order}; A \rightarrow B_{12} : \text{ok}$$

Similarly to the previous case, this scenario may be modelled with the following CO₂ system:

$$S_2 = (x, w) (A[\text{tell}_A \downarrow_x c_A \cdot \text{fuse} \cdot P_A] \mid B_{12}[\text{tell}_A \downarrow_w c_{B_{12}} \cdot P_{B_{12}}])$$

where the fuse prefix can now create a session involving A and B₁₂.

The participants in the CO₂ systems S_1 and S_2 may also be combined, so to obtain:

$$S_{12} = (x, y, z, w) (A[\text{tell}_A \downarrow_x c_A \cdot \text{fuse} \cdot P_A] \\ \mid B_1[\text{tell}_A \downarrow_y c_{B_1} \cdot P_{B_1}] \mid B_2[\text{tell}_A \downarrow_z c_{B_2} \cdot P_{B_2}] \\ \mid B_{12}[\text{tell}_A \downarrow_w c_{B_{12}} \cdot P_{B_{12}}])$$

In this case, after all contracts have been advertised to A, either a session corresponding to $\mathcal{G}_{AB_1B_2}$, or to $\mathcal{G}_{AB_{12}}$ may take place, thus involving a different number of participants depending on which contracts are fused. In this case, it makes sense to consider whether one of the agreements should take precedence over the other, and which criteria should drive this choice.

2 A Choreography-Based Contract Model

We introduce a contract model based on concepts and results from the session types literature. Individual contracts are expressed using the syntax of local session type; while contractual compliance is based on global types synthesis: a set of contracts is compliant if it is possible to synthesise a choreography from it, as described in [10]. For simplicity, we adopt syntax and semantics in the style of [6, 8]: we use participant names (instead of channels) for message exchange — i.e., we consider systems with just one channel between each pair of participants.

Syntax & Semantics. Let \mathbb{P} and \mathcal{P} be disjoint sets of, respectively, *participant names* (ranged over by A, B, \dots) and *participant variables* (ranged over by a, b, \dots). Let α, β range over $\mathbb{P} \cup \mathcal{P}$. The syntax of contracts below is parametrised wrt *sorts* (ranged over by e) which abstract data types (either simple or complex). We use the colour **blue** for single contracts, and **green** for *systems* of contracts.

$$\begin{array}{lcl} T, T' & ::= & T \mid T' \quad \mid \quad A \langle c \rangle \quad \mid \quad (AB) : \rho \quad \mid \quad \mathbf{0} \\ c, c' & ::= & \bigoplus_{i \in I} \alpha_i ! e_i ; c_i \quad \mid \quad \sum_{i \in I} \alpha_i ? e_i ; c_i \quad \mid \quad \mu \mathbf{x}. c \quad \mid \quad \mathbf{x} \end{array}$$

A contract c may be either: (i) an internal choice \bigoplus , with the intuitive semantics that after sending the message e_i to participant α_i , behaviour c_i take places; (ii) an external choice \sum , saying that if a message of sort e_i is received by α_i , then behaviour c_i takes place; or (iii) a recursive behaviour. We assume that $\forall i \neq j \in I. (\alpha_i, e_i) \neq (\alpha_j, e_j)$ in internal and external choices. We write $\text{fv}(c)$ for the free participant variables in c .

A system of contract T may be either: (i) a parallel composition of systems $T \mid T'$; or (ii) a *named* contract $A \langle c \rangle$, saying that participant A promises to behave according to c ; (iii) a *queue* $(AB) : \rho$ of messages from A to B. In a system T , we assume that there is at most one queue per pair of participants, (i.e., one channel per direction), and that participant names are pairwise distinct.

We consider systems of contracts as processes whose semantics is given by the following main reduction rules (see App. A for the omitted ones):

$$\begin{aligned} A\langle B!e; c_0 \oplus c_1 \rangle \mid (AB):\rho \mid T &\xrightarrow{A \rightarrow B:e} A\langle c_0 \rangle \mid (AB):\rho \cdot e \mid T \\ A\langle B?e; c_0 + c_1 \rangle \mid (BA):e \cdot \rho \mid T &\xrightarrow{A \leftarrow B:e} A\langle c_0 \rangle \mid (BA):\rho \mid T \end{aligned}$$

The first rule says that, after an internal choice, participant A puts a message e on its queue for participant B. The second rule says that A's external choice can receive a message of the right sort from an input queue BA. We write $T \xrightarrow{A \leftarrow B:e} T'$ when either $T \xrightarrow{A \rightarrow B:e} T'$ or $T \xrightarrow{A \leftarrow B:e} T'$, and $Q(T)$ for the parallel composition of the empty queues connecting all pairs of participants in T .

Example 2.1 *From the example in Section 1.2, consider the instantiated contracts of the store A and its customer B₁₂. We illustrate the initial system, and how it progresses:*

$$\begin{aligned} T_{AB_{12}Q} &= A\langle c_A \{A/a''\} \{B_{12}/b_1, b_2\} \rangle \mid B_{12}\langle c_{B_{12}} \{A/a''\} \{B_{12}/b_1, b_2\} \rangle \mid (AB_{12}):[] \mid (B_{12}A):[] \\ &= A\langle B_{12}?req; B_{12}?req; \dots \rangle \mid B_{12}\langle A!req; A!req; \dots \rangle \mid (AB_{12}):[] \mid (B_{12}A):[] \\ \xrightarrow{B_{12} \rightarrow A:req} & A\langle B_{12}?req; B_{12}?req; \dots \rangle \mid B_{12}\langle A!req; \dots \rangle \mid (AB_{12}):[] \mid (B_{12}A):req \\ \xrightarrow{A \leftarrow B_{12}:req} & A\langle B_{12}?req; \dots \rangle \mid B_{12}\langle A!req; \dots \rangle \mid (AB_{12}):[] \mid (B_{12}A):[] \end{aligned}$$

Choreography Synthesis as Compliance. We briefly introduce the compliance relation that tells whether some contracts can be combined to describe a correct interaction. We reuse the main results from [10]: a set of contracts is *compliant* if it can be assigned a choreography, i.e. a global type.

For simplicity, we use only a subset of the global types in [10] (we conjecture that extending this would not pose any difficulties). The main difference is that, in the style of [6, 8], we replace channels with participant names.

The syntax of global types is as follows:

$$\mathcal{G} ::= A \rightarrow B:e; \mathcal{G} \mid \mathcal{G} + \mathcal{G}' \mid \mathcal{G} \mid \mathcal{G}' \mid \mu\chi.\mathcal{G} \mid \chi \mid \mathbf{0}$$

where the first production means that a participant A sends a message of sort e to B, then interactions in \mathcal{G} take place; $\mathcal{G} + \mathcal{G}'$ means that either interactions in \mathcal{G} , or in \mathcal{G}' take place; $\mathcal{G} \mid \mathcal{G}'$ means that interactions in \mathcal{G} and \mathcal{G}' are executed concurrently; the rest of the productions are for recursive interactions, and end.

Similarly to [10], we use judgements of the form $\Gamma \vdash T \blacktriangleright \mathcal{G}$, where Γ is an environment to keep track of recursion variables, T is a system of contracts, and \mathcal{G} is the global type assigned to T . We say that a system of contracts T has global type \mathcal{G} , if one can infer the judgement $\circ \vdash T \blacktriangleright \mathcal{G}$ from the rules in App. B (simplified from [10]). The main properties that we are interested in — and that are guaranteed by the synthesis — is that the inferred global type is well-formed and projectable back to the original contracts. Essentially, this means that each local type must be single-threaded, and that *knowledge of choice* is preserved — i.e., each choice is made by exactly one participant, and all the others are either made aware of the choice, or they have the same behaviour whatever choice is made. Whenever a global type satisfies these properties, we have that the system of contracts is error/deadlock free.

Example 2.2 *Building up on the example from Section 1.2, we combine the contract of store A with those of customers B₁ and B₂, and we obtain the system:*

$$\begin{aligned} T_{AB_1B_2} &= A\langle c_A \{B_1/b_1\} \{B_2/b_2\} \rangle \mid B_1\langle c_{B_1} \{A/a\} \{B_2/b_2\} \rangle \mid B_2\langle c_{B_2} \{A/a'\} \{B_1/b_1\} \rangle \\ &= A\langle B_1?req; B_2?req; B_1!quote; (B_1?order; B_2!ok + B_1?bye; B_2!bye) \rangle \\ &\quad \mid B_1\langle A!req; A!quote; (B_2!ok; A!order \oplus B_2!bye; A!bye) \rangle \\ &\quad \mid B_2\langle A!req; (B_1?ok; A?ok + B_1?bye; A?bye) \rangle \end{aligned}$$

which can be assigned the following global type:

$$\begin{aligned} \mathcal{G}_{AB_1B_2} = & B_1 \rightarrow A : \text{req}; B_2 \rightarrow A : \text{req}; A \rightarrow B_1 : \text{quote}; \\ & (B_1 \rightarrow B_2 : \text{ok}; B_1 \rightarrow A : \text{order}; A \rightarrow B_2 : \text{ok} \quad + \quad B_1 \rightarrow B_2 : \text{bye}; B_1 \rightarrow A : \text{bye}; A \rightarrow B_2 : \text{bye}) \end{aligned}$$

that is to say that $\circ \vdash T_{AB_1B_2} \blacktriangleright \mathcal{G}_{AB_1B_2}$ holds. Instead, if we combine the store A with B_{12} we have

$$\begin{aligned} T_{AB_{12}} &= A \langle C_A \{B_{12}/b_1, b_2\} \rangle \mid B_{12} \langle C_{B_{12}} \{A/a''\} \rangle \\ &= A \langle B_{12} ? \text{req}; B_{12} ? \text{req}; B_{12} ! \text{quote}; (B_{12} ? \text{order}; B_{12} ! \text{ok} + B_{12} ? \text{bye}; B_{12} ! \text{bye}) \rangle \\ &\quad \mid B_{12} \langle A ! \text{req}; A ! \text{req}; A ? \text{quote}; A ! \text{order}; A ? \text{ok} \rangle \\ \mathcal{G}_{AB_{12}} &= B_{12} \rightarrow A : \text{req}; B_{12} \rightarrow A : \text{req}; A \rightarrow B_{12} : \text{quote}; B_{12} \rightarrow A : \text{order}; A \rightarrow B_{12} : \text{ok} \end{aligned}$$

and, again, the judgement $\circ \vdash T_{AB_{12}} \blacktriangleright \mathcal{G}_{AB_{12}}$ holds.

3 A Multiparty Version of CO₂

We introduce a version of the CO₂ calculus (for Contract-Oriented COmputing) [4] adapted to multiparty contracts and sessions. Let \mathbb{S} and \mathcal{S} be disjoint sets of, respectively, *session names* (ranged over by s, s', \dots) and *session variables* (ranged over by x, y, z, \dots). Let u, v, \dots range over $\mathbb{S} \cup \mathcal{S}$.

Syntax & Semantics. The syntax of CO₂ is given by the following productions:

$$\begin{array}{ll} \text{Processes} & P ::= \sum_{i \in I} p_i . P_i \mid P \mid P \mid (\vec{u}, \vec{a})P \mid X(\vec{u}, \vec{a}) \mid \mathbf{0} \\ \text{Prefixes} & p ::= \tau \mid \text{tell}_{\alpha} \downarrow_u c \mid \text{fuse} \mid \text{do}_{\alpha}^u e \\ \text{Latent contracts} & K ::= \downarrow_u A \text{ says } c \mid K \mid K \\ \text{Systems} & S ::= A[P] \mid A[K] \mid s[T] \mid S \mid S \mid (\vec{u}, \vec{a})S \mid \mathbf{0} \end{array}$$

CO₂ features CCS-style processes, equipped with branching \sum (not to be confused with the choice operator used in contracts), parallel composition \mid , restrictions of session and participant variables, and named process invocation. The prefixes are for internal action (τ), contract advertisement (tell_{\downarrow}), session creation upon contractual agreement (fuse), and execution of contractual actions (do). A latent contract of the form $\downarrow_u A \text{ says } c$ represents the promise of participant A to fulfil c by executing do -actions on a session variable u . CO₂ systems may be parallel compositions of processes $A[P]$ (where A is the participant executing P), latent contracts $A[K]$ (where A is the participant to which the contracts in K have been advertised), and established sessions $s[T]$ (where s is a session name, and T is a system of contracts as in Section 2).

We give the main reduction rules for the semantics of CO₂ (see App. C for the rest of the rules):

$$\begin{array}{l} [\text{CO}_2\text{-TELL}] \quad A[\text{tell}_B \downarrow_x c . P + P' \mid Q] \rightarrow A[P \mid Q] \mid B[\downarrow_x A \text{ says } c] \\ \\ [\text{CO}_2\text{-FUSE}] \quad \frac{K \triangleright_{\pi}^{\sigma} T \quad \vec{u} = \text{dom}(\sigma) \quad \vec{a} = \text{dom}(\pi) \quad \text{ran}(\sigma) = \{s\} \quad s \text{ fresh}}{(\vec{u}, \vec{a}) (A[\text{fuse} . P + P' \mid Q] \mid A[K] \mid S) \rightarrow (s) (A[P \mid Q] \sigma\pi \mid s[T \mid Q(T)]) \mid S\sigma\pi} \\ \\ [\text{CO}_2\text{-DO}] \quad \frac{T \xrightarrow{A=B:e} T'}{s[T] \mid A[\text{do}_B^s e . P + P' \mid Q] \rightarrow s[T'] \mid A[P \mid Q]} \end{array}$$

[CO₂-TELL] allows a participant A to advertise a contract c to B; as a result, a new latent contract is created, recording the fact that it was promised by A. [CO₂-FUSE] establishes a new session: the latent contracts held in $A[K]$ are combined, and their participant variables substituted, in order to find an *agreement*, i.e. a T which satisfies the relation $K \triangleright_{\pi}^{\sigma} T$ (see Definition 3.2 below). Provided an agreement is found, fresh session variable s and participants names are shared among the parties, via substitutions σ and π . Rule [CO₂-DO] allows A to perform an input/output action e towards B on session s , provided that T permits it.

When needed, we label CO₂ system transitions: $S \xrightarrow{A:p} S'$ means that S reduces to S' through a prefix p fired by participant A.

Example 3.1 Consider the CO₂ system:

$$S = A[\text{do}_B^s \text{int} + \text{do}_B^s \text{bool}] \mid s[A\langle B!\text{int} \rangle \mid B\langle A?\text{int} \rangle \mid (AB):[] \mid (BA):[]] \mid B[\text{do}_A^s \text{int}]$$

Here, the CO₂ process of participant A can perform an action towards B on session s , with either a message of sort `int` or `bool`. However, A's contract in s only specifies that A should send a message of sort `int` to B: therefore, according to rule [CO₂-DO], only the first branch of A may be chosen, and the system reduces as follows.

$$\begin{array}{l} S \xrightarrow{A:\text{do}_B^s \text{int}} A[\mathbf{0}] \mid s[A\langle \mathbf{0} \rangle \mid B\langle A?\text{int} \rangle \mid (AB):\text{int} \mid (BA):[]] \mid B[\text{do}_A^s \text{int}] \\ \xrightarrow{B:\text{do}_A^s \text{int}} A[\mathbf{0}] \mid s[A\langle \mathbf{0} \rangle \mid B\langle \mathbf{0} \rangle \mid (AB):[] \mid (BA):[]] \mid B[\mathbf{0}] \end{array}$$

A main difference between our adaptation of CO₂ and the original presentation comes from the way we specify session establishment. Session agreement in CO₂ is based on the relation defined below.

Definition 3.2 ($K \triangleright_{\pi}^{\sigma} T$) Let $K \equiv \prod_{i \in I} \downarrow_{x_i} A_i \text{ says } c_i$, such that $\forall i \neq j \in I : A_i \neq A_j$, and let $\pi : \mathcal{P} \rightarrow \mathbb{P}$ and $\sigma : \mathcal{S} \rightarrow \mathbb{S}$ be two substitutions mapping participant variables to names, and session variables to names, respectively. Also, let $T \equiv \prod_{i \in I} A_i \langle c_i \rangle \pi$. We define:

$$\begin{aligned} K \triangleright_{\pi}^{\sigma} T \iff & \text{dom}(\sigma) = \bigcup_{i \in I} \{x_i\} \quad \wedge \quad \text{dom}(\pi) = \bigcup_{i \in I} \text{fv}(c_i) \\ & \wedge \\ & \forall i \in I. \forall a \in \text{fv}(c_i). \pi(a) \neq A_i \quad \wedge \quad \exists \mathcal{G}. \circ \vdash T \blacktriangleright \mathcal{G} \end{aligned}$$

Intuitively, a system of contracts T is constructed from a set of latent contracts K , using a substitution π that maps all the participant variables in K to the participant names in K itself. If it is possible to synthesise a global type \mathcal{G} out of T , then the relation holds, and a contractual agreement exists. The first two conditions, on σ and π , guarantee that all the session and participant variables are indeed instantiated. The third condition ensures that within a contract c_i , belonging to A_i , no free participant variable in c_i is substituted by A_i itself. Note that due to the condition imposed on K , each participant may have at most one contract per session.

Example 3.3 We now illustrate how Definition 3.2 works. Consider the following CO₂ system, with A, B_1, B_2 from Section 1.2, and $T_{AB_1B_2}$ from Example 2.2:

$$\begin{aligned} S_1 &= (x, y, z) (A[\text{tell}_A \downarrow_x c_A \cdot \text{fuse} \cdot P_A] \mid B_1[\text{tell}_A \downarrow_y c_{B_1} \cdot P_{B_1}] \mid B_2[\text{tell}_A \downarrow_z c_{B_2} \cdot P_{B_2}]) \\ \rightarrow \rightarrow \rightarrow & (x, y, z) (A[\text{fuse} \cdot P_A] \mid A[\downarrow_x A \text{ says } c_A \mid \downarrow_y B_1 \text{ says } c_{B_1} \mid \downarrow_z B_2 \text{ says } c_{B_2}] \mid B_1[P_{B_1}] \mid B_2[P_{B_2}]) \\ \xrightarrow{A:\text{fuse}} (s) S'_1 &= (s) (A[P_A] \sigma \pi \mid s[T_{AB_1B_2} \mid Q(T_{AB_1B_2})] \mid B_1[P_{B_1}] \sigma \pi \mid B_2[P_{B_2}] \sigma \pi) \end{aligned}$$

where $\sigma = \{s/x, y, z\}$ and $\pi = \{A/a, a', B_1/b_1, b'_1, B_2/b_2, b'_2\}$

The initial system S_1 is the one considered in Section 1.2, where all the participants are ready to advertise their respective contracts to the store A , by using a $\text{tell}_A \downarrow$ -primitive. This has the effect of creating corresponding latent contracts within A . Once all the latent contracts are in a same location, they may be fused. In this case, given σ and π as above, Definition 3.2 is indeed applicable: the domains of σ and π comply with its premises, and we already saw that a system consisting of c_A , c_{B_1} and c_{B_2} may be assigned a global type. Hence, a new session s is created, based on the system of contracts $T_{AB_1B_2}$, plus the queues connecting all pairs of participants. The session variables of the latent contracts being fused (i.e., x for participant A , y for B_1 , and z for B_2) are all substituted with the fresh session name s in the processes P_A , P_{B_1} and P_{B_2} , via σ . Similarly for participant variables which are substituted with participant names, via π .

The CO_2 semantic rules are to be considered up-to a standard structural congruence relation \equiv (cf. App. C): we just point out that $A[K] \mid A[K'] \equiv A[K \mid K']$ allows to select a compliant subset from a group of latent contracts, before performing a fuse — thus adding flexibility to the synthesis of choreographies.

Example 3.4 Consider the system:

$$\dots B[\text{fuse}.P \mid Q] \mid B[\downarrow_x A_1 \text{ says } a!\text{int} \mid \downarrow_y A_2 \text{ says } a'?\text{int} \mid \downarrow_z A_3 \text{ says } b?\text{bool}] \dots$$

The fuse prefix cannot be fired: no contract matches A_3 's, and thus the three latent contracts cannot be assigned a global type. However, by rearranging the system with congruence \equiv , we have:

$$\dots B[\text{fuse}.P \mid Q] \mid B[\downarrow_x A_1 \text{ says } a!\text{int} \mid \downarrow_y A_2 \text{ says } a'?\text{int}] \mid B[\downarrow_z A_3 \text{ says } b?\text{bool}] \dots$$

It is now possible to synthesise a global type $A_1 \rightarrow A_2 : \text{int}$, and a session may be created for A_1 and A_2 . A_3 's latent contract may be fused later on.

Dynamicity and Flexibility of Session Establishment. We discuss a few examples illustrating the flexibility exhibited by our definition of contract agreement, together with the semantics of CO_2 .

Both participants names and variables may appear in contracts. A may want to sell an item to a *specific* participant B , via *any* shipping company that provides a package tracking system. A 's contract is:

$$B!\text{price}; B?\text{ack}; a!\text{request}; a?\text{tracking}; B!\text{tracking}$$

saying that the seller A must send a price to the buyer B ; once B has acknowledged, A must send a shipping request to a shipper a — who must send back a tracking number, which is then forwarded to B . This contract may be fused only if B takes part in the session, while the role of shipper a may be played by any participant.

It is also possible for different contracts to refer to common participant variables, thus making links between them. Consider:

$$\dots A[\text{tell}_{A \downarrow x}(b!\text{request}) \dots X(\vec{z}, b)] \dots \quad \text{where } X(\vec{z}, b) := (y, b')\text{tell}_{A \downarrow y}(b'!\text{quote}; \dots b!\text{address}) \dots X(\vec{z}, b)$$

Here, A advertises two contracts: the first one ($b!\text{request}$) is used by A to find a shipping company, and the second ($b'!\text{quote}; \dots b!\text{address}$) to sell items. Whenever the first one is fused, variable b is instantiated to a participant name, say B , which is also substituted in the second. This means that whenever a new selling session starts, B will also be involved as the receiver of the address message.

Possible Extensions. The participants firing fuse-primitives are playing the role of brokers in our framework. Depending on their implementation, they may also have some obligations in the contracts they fuse, or they may want to enforce some general policy — therefore they may have additional requirements before agreeing to start a session. Several variations of the fuse primitive are possible thanks to the fact that we base contract agreements on objects representing the overall choreography. We introduce $\text{fuse}[n]$, a version of fuse that only fuses sessions where there are at least n participants; fuse_T , which has the additional constraint that no recursive behaviour is allowed in the synthesised choreography (i.e. therefore ensuring that the session will eventually terminate), and fuse_R , which only creates sessions when the synthesised choreography never terminates (i.e. it only consists of recursive behaviours).

The three extensions may be defined directly via small modifications of Definition 3.2:

- $\text{fuse}[n]$: we add the condition $|\mathcal{P}(\mathcal{G})| \geq n$, where $\mathcal{P}(\mathcal{G})$ is the set of participants in \mathcal{G} ;
- fuse_T : we add the condition that there should not be any recursion variable χ in \mathcal{G} ;
- fuse_R : we add the condition that $\mathbf{0}$ does not appear in \mathcal{G} .

This kind of properties must be checked for at the global level because it cannot always be decided by looking at the individual contracts. For instance, a participant might exhibit a recursive behaviour in one of the branches of an external choice, while the participant it interacts with may always choose a branch that is not recursive. Note that none of these variations actually affect the results that follow, since the original fuse primitive is also blocking. The variations only restrict some of its applications. Further variations of fuse are sketched in Section 6, as future work.

4 The Problem of Honesty

In this section, we discuss and define the notion of *honesty* [4], i.e. the ability of a participant to always fulfil its contracts, in any context. Broadly speaking, in our contract-oriented setting, honesty is the counterpart of well-typedness in a session type setting: the static proof that a participant always honours its contracts provides guarantees about its runtime behaviour.

As seen in Example 3.1, each do prefix within the process of a participant, say $A[P]$, is driven by the contract that A promised to abide by. In a sense, CO_2 is *culpability-driven*, according to Definition 4.1 below: when a participant is culpable, it has the duty of making the session progress according to its contract.

Definition 4.1 (Culpability) *Let S be a CO_2 system with a session s , i.e. $S \equiv (\vec{u}, \vec{a}) (A[P] \mid s[T] \mid S_1) \mid S_2$. We say that A is culpable in S when there exist B and e such that $T \xrightarrow{A \Leftarrow B:e}$.*

A culpable participant can overcome its status by firing its do prefixes, according to $[\text{CO}_2\text{-Do}]$, until someone else becomes culpable or the session terminates. Hence, as long as a participant A does not enable a do-prefix matching a contractual action, the session state will keep A’s culpability.

When a participant A is always able to fulfil its contractual actions (i.e., overcome its culpability), no matter what other participants do, then it is said to be *honest* (cf. Definition 4.8). This is a desirable property in a distributed contract-oriented scenario: a participant may be stuck in a culpable condition both due to “simple” bugs (cf. Example 4.7), and to the unexpected (or malicious) behaviour of other participants (cf. Example 5.6). Therefore, before deploying a service, its developers might want to ensure that it will always exculpate itself.

Formally, as in [1], we base the definition of honesty on the relationship between the ready sets of a contract, and those of a CO_2 process. We call the former *contract ready sets*, and the latter *process*

ready sets. The concept of contract ready sets is similar to [7, 4, 1], where only bilateral contracts are considered. Here, we adapt it to suit our multiparty contract model.

Definition 4.2 (Contract Ready Sets) *The ready sets of a contract c , written $\text{CRS}(c)$, are:*

$$\text{CRS}(c) = \begin{cases} \text{CRS}(c') & \text{if } c = \mu x.c' \\ \{\{(A_i, e_i) \mid i \in I\}\} & \text{if } c = \bigoplus_{i \in I} A_i!e_i; c_i \text{ and } I \neq \emptyset \\ \{\{(A_i, e_i) \mid i \in I\}\} & \text{if } c = \sum_{i \in I} A_i?e_i; c_i \end{cases}$$

Intuitively, when a participant A is bound to a contract c , the ready sets of c tell which interactions A must be able to perform towards other participants. Each interaction has the form of a pair, consisting of a participant name and a message sort. The interactions offered by an external choice are all available at once, while those offered by an internal choice are mutually exclusive.

Example 4.3 *Consider the system of contracts $T_{AB_1B_2}$ from Example 2.2 — and in particular, the stipulated contracts therein, with substitution $\pi = \{A/a, a', B_1/b_1, b'_1, B_2/b_2, b'_2\}$ from Example 3.3:*

$$\begin{aligned} \tilde{c}_A &= c_A \pi = B_1?req; B_2?req; B_1!quote; (B_1?order; B_2!ok + B_1?bye; B_2!bye) \\ \tilde{c}_{B_1} &= c_{B_1} \pi = A!req; A?quote; (B_2!ok; A!order \oplus B_2!bye; A!bye) \\ \tilde{c}_{B_2} &= c_{B_2} \pi = A!req; (B_1?ok; A?ok + B_1?bye; A?bye) \end{aligned}$$

We have $\text{CRS}(\tilde{c}_A) = \{\{(B_1, req)\}\}$: in other words, at this point of the contract, an interaction is expected between A and B_1 (since A is waiting for req), while no interaction is expected between A and B_2 .

Let us now equip $T_{AB_1B_2}$ with one queue between each pair of participants, and let it perform the request exchange between B_1 and A, with the transitions:

$$T_{AB_1B_2} \mid Q(T_{AB_1B_2}) \xrightarrow{B_1 \rightarrow A: req} \xrightarrow{A \leftarrow B_1: req} T'_{AB_1B_2} \mid Q(T_{AB_1B_2})$$

We have that \tilde{c}_A in $T'_{AB_1B_2}$ is now reduced to:

$$\tilde{c}_A' = B_2?req; B_1!quote; (B_1?order; B_2!ok + B_1?bye; B_2!bye)$$

and thus we have $\text{CRS}(\tilde{c}_A') = \{\{(B_2, req)\}\}$, i.e. A is now waiting for a request from B_2 .

If we let the system reduce further, \tilde{c}_A' reaches its external choice:

$$\tilde{c}_A'' = B_1?order; B_2!ok + B_1?bye; B_2!bye$$

Now, the ready sets become $\text{CRS}(\tilde{c}_A'') = \{\{(B_1, order), (B_1, bye)\}\}$, i.e. A must handle both answers from B_1 . Instead, when \tilde{c}_{B_1} reduces to its internal choice, we have:

$$\tilde{c}_{B_1}'' = B_2!ok; A!order \oplus B_2!bye; A!bye$$

Thus, its ready sets become $\text{CRS}(\tilde{c}_{B_1}'') = \{\{(B_2, ok)\}, \{(B_2, bye)\}\}$, i.e. B_1 is free to choose either branch.

Example 4.3 shows that, when a contract c of a principal A evolves within a system T , its ready sets change. Now we need to define the counterpart of contract ready sets for CO_2 processes, i.e. the *process ready sets*. Again, we adapt the definition from [1] to our multiparty contract model.

Definition 4.4 (Process Ready Set) For all CO₂ systems S , all participants A, B and sessions u , we define the set of pairs:¹

$$\text{PRS}_u^A(S) = \{(B, e) \mid \exists \vec{v}, \vec{a}, P, P', Q, S' . S \equiv (\vec{v}, \vec{a}) (A[\text{do}_B^u e . P + P' \mid Q] \mid S_0) \mid S_1 \wedge u \notin \vec{v}\}$$

Intuitively, Definition 4.4 says that the process ready set of A over a session u in a system S contains the interactions that A is immediately able to perform with other participants through its do_-^u prefixes. Just as in contract ready sets, the interactions are represented by participant/sort pairs.

Next, we want to characterise a weaker notion of the process ready set, so it only takes into account the first actions *on a specific session* that a participant is ready to do.

Definition 4.5 (Weak Process Ready Set) We write $S \xrightarrow{\neq(A: \text{do}_B^u)} S'$ iff:

$$(\exists p . S \xrightarrow{B: p} S') \vee (\exists C, p . S \xrightarrow{C: p} S') \vee (\exists p . S \xrightarrow{A: p} S' \wedge \forall e . p \neq \text{do}_-^u e) \quad \text{where } C \neq A$$

We then define the set of pairs $\text{WPRS}_u^A(S)$ as:

$$\text{WPRS}_u^A(S) = \left\{ (B, e) \mid \exists S' . S \xrightarrow{\neq(A: \text{do}_B^u)} S' \wedge (B, e) \in \text{PRS}_u^A(S') \right\}$$

In Definition 4.5, we are not interested in the actions that do not relate to the session u . Thus, we allow the system to evolve either by (i) letting any other participant other than A do an action, or (ii) letting A act on a different session than u , or (iii) do internal actions.

We now introduce the final ingredient for honesty — that is, the notion of *readiness* of a participant.

Definition 4.6 (Readiness) We say that A is ready in S iff, whenever $S \equiv (\vec{u}, \vec{b}) S_1 \mid S_2$ for some \vec{u}, \vec{b} and $S_1 = s[A\langle c \rangle \mid \dots] \mid S_0$, the following holds:

$$\exists X \in \text{CRS}(c) . ((B, e) \in X \implies (B, e) \in \text{WPRS}_s^A(S_1))$$

Definition 4.6 says that a participant A is *ready* in a system S whenever its process ready sets for a session s will eventually contain all the participant/sort pairs of one of the contract ready sets of A 's contract in s . When a participant A is “ready”, then, for any of its contracts c , the CO₂ process of A is (eventually) able to fulfil at least the interactions in c 's prefix.

Example 4.7 We have seen that, after reduction, and fusion of the latent contracts of S_1 (in Example 3.3) we obtain the following system

$$(s)S'_1 \equiv (s)(A[P_A\sigma\pi] \mid s[T_{AB_1B_2} \mid Q(T_{AB_1B_2})] \mid B_1[P_{B_1}\sigma\pi] \mid B_2[P_{B_2}\sigma\pi])$$

where the substitutions σ and π are also from Example 3.3. Let us define the three processes (after application of the substitutions):

$$\begin{aligned} P_A\sigma\pi &= \text{do}_{B_1}^s \text{req} . \text{do}_{B_2}^s \text{req} . \text{do}_{B_1}^s \text{quote} . (\text{do}_{B_1}^s \text{order} . \text{do}_{B_2}^s \text{ok} + \text{do}_{B_1}^s \text{bye} . \text{do}_{B_2}^s \text{bye}) \\ P_{B_1}\sigma\pi &= \tau . \text{do}_A^s \text{req} . \text{do}_A^s \text{quote} . \text{do}_A^s \text{order} \\ P_{B_2}\sigma\pi &= \text{do}_A^s \text{req} . (\text{do}_{B_1}^s \text{ok} . \text{do}_A^s \text{ok} + \text{do}_{B_1}^s \text{bye} . \text{do}_A^s \text{bye}) \end{aligned}$$

¹The side condition “ $u \notin \vec{v}$ ” of Definition 4.4 deals with cases like $S_0 = (s)(A[\text{do}_B^s \text{int}])$ and $S = S_0 \mid s[A\langle B!\text{int} \rangle \mid \dots] \mid \dots$: without the side condition, $\text{PRS}_u^A(S_0) = \{(B, \text{int})\}$ — hence, by Def. 4.6, A would result to be ready in S .

Thus, we have:

$$\begin{aligned} \text{PRS}_s^A(S'_1) &= \{(B_1, \text{req})\} = \text{WPRS}_s^A(S'_1) \\ \text{PRS}_s^{B_1}(S'_1) &= \emptyset \neq \{(A, \text{req})\} = \text{WPRS}_s^{B_1}(S'_1) \\ \text{PRS}_s^{B_2}(S'_1) &= \{(A, \text{req})\} = \text{WPRS}_s^{B_2}(S'_1) \end{aligned}$$

Note that the τ prefix in P_{B_1} prevents B_1 from interacting immediately with A on session s , although it is “weakly ready” to do it. Hence, considering that the weak process ready sets of each participant in S'_1 match their respective contract ready sets in $T_{AB_1B_2}$ (Example 4.3) according to Definition 4.6 we have that participants A , B_1 and B_2 are all ready in $(s)S'_1$.

Definition 4.8 (Honesty) We say that $A[P]$ is honest iff, for all S with no latent/stipulated contracts of A nor $A[\cdot\cdot]$, and for all S' such that $A[P] \mid S \rightarrow^* S'$, A is ready in S' .

A process $A[P]$ is said to be honest when, for all contexts and reductions that $A[P]$ may be engaged in, A is persistently ready. In other words, there is a continuous correspondence between the interactions exposed in the contract ready sets, and the process ready sets of the possible reductions of any system involving $A[P]$. The definition rules out contexts with latent/stipulated contracts of A — otherwise, A could be made trivially dishonest, e.g. by inserting a latent contract $\downarrow_u A \text{ says } c$ that A cannot fulfil.

Example 4.9 Consider the process $B_1[\text{tell}_A \downarrow_y c_{B_1} \cdot P_{B_1}]$ of system S_1 , as defined in Examples 3.3 and 4.7. We show that this process is not honest. In fact, S_1 can reduce as $S_1 \rightarrow^* (s)S'_1 \rightarrow^* (s)S''_1$, where:

$$\begin{aligned} (s)S''_1 &= (s) \left(A[\text{do}_{B_1}^s \text{ order} \cdot \text{do}_{B_2}^s \text{ ok} + \text{do}_{B_1}^s \text{ bye} \cdot \text{do}_{B_2}^s \text{ bye}] \right. \\ &\quad | s [A \langle B_1 ? \text{order}; B_2 ! \text{ok} + B_1 ? \text{bye}; B_2 ! \text{bye} \rangle \\ &\quad \quad | B_1 \langle B_2 ! \text{ok}; A ! \text{order} \oplus B_2 ! \text{bye}; A ! \text{bye} \rangle | B_2 \langle B_1 ? \text{ok}; A ? \text{ok} + B_1 ? \text{bye}; A ? \text{bye} \rangle \\ &\quad \quad | (AB_1) : [] | (B_1A) : [] | (AB_2) : [] | (B_2A) : [] | (B_1B_2) : [] | (B_2B_1) : []] \\ &\quad \left. | B_1[\text{do}_A^s \text{ order}] | B_2[\text{do}_{B_1}^s \text{ ok} \cdot \text{do}_A^s \text{ ok} + \text{do}_{B_1}^s \text{ bye} \cdot \text{do}_A^s \text{ bye}] \right) \end{aligned}$$

At this point, we see that there is a problem in the implementation of B_1 : it does not notify the other buyer before making an order. In fact, B_1 's process is trying to perform $\text{do}_A^s \text{ order}$, but its contract requires that $\text{do}_{B_2}^s \text{ ok}$ is performed first (or $\text{do}_{B_2}^s \text{ bye}$, if the quote is rejected). This is reflected by the mismatch between B_1 's process ready set in S''_1 , and its contract ready sets, in session s :

$$\begin{aligned} \text{PRS}_s^{B_1}(S''_1) &= \{\{(A, \text{order})\}\} \\ \text{CRS}(B_2 ! \text{ok}; A ! \text{order} \oplus B_2 ! \text{bye}; A ! \text{bye}) &= \{\{(B_2, \text{ok})\}, \{(B_2, \text{bye})\}\} \end{aligned}$$

In terms of the above definitions, there exists a system S_1 — containing $B_1[\text{tell}_A \downarrow_y c_{B_1} \cdot P_{B_1}]$ — that reduces to a $(s)S''_1$ where B_1 is not ready (Definition 4.6). Therefore, $B_1[\text{tell}_A \downarrow_y c_{B_1} \cdot P_{B_1}]$ is not honest. In fact, B_1 is culpable in $(s)S''_1$, according to Definition 4.1.

As in [1], the definition of honesty subsumes a *fair* scheduler, eventually allowing participants to fire persistently (weakly) enabled *do* actions.

Honesty is not decidable in general [4], but for a bilateral contract model it has been approximated either via an abstract semantics [4] or a type discipline [1] for CO_2 . Considering that our systems of multiparty contracts form a (strict) subset of the local and global types considered in [8], for which each configuration is reachable by a 1-buffer execution, we believe that these approximations may be easily adapted to our setting.

5 Results

We now give the main properties our framework guarantees. We ensure that two basic features of CO₂ hold in our multiparty adaptation: the state of a session always allows to establish who is responsible for making the system progress (Theorem 5.1) and honest participants can always exculpate themselves (Theorem 5.3). We then formalize a link between the honesty of participants, and two key properties borrowed from the session types literature: Theorem 5.4 introduces session fidelity in CO₂; and Theorem 5.5 introduces a notion of progress in CO₂, based on the progress of the contractual agreement (and hence, on the progress of the underlying choreography).

Theorem 5.1 (Unambiguous culpability) *Given a CO₂ system S , if S contains a session $s[T]$ such that $T \neq \mathbf{0}$, then there exists at least one culpable participant.*

Theorem 5.1 says that in an active session, there is always at least one participant $A[P]$ who leads the next interaction. Thus, if a corresponding $\text{do}_B^s e$ prefix is not in P , S may get stuck, and A is culpable.

Example 5.2 *Consider the system S_1'' in Example 4.9, and the system of contracts in its session s :*

$$\begin{aligned} T_s = & A(B_1?order; B_2!ok + B_1?bye; B_2!bye) \\ & | B_1(B_2!ok; A!order \oplus B_2!bye; A!bye) | B_2(B_1?ok; A?ok + B_1?bye; A?bye) \\ & | (AB_1):[] | (B_1A):[] | (AB_2):[] | (B_2A):[] | (B_1B_2):[] | (B_2B_1):[] \end{aligned}$$

We have $T_s \xrightarrow{B_1 \Leftarrow B_2:ok}$ and $T_s \xrightarrow{B_1 \Leftarrow B_2:bye}$. Hence, B_1 is responsible for the next interaction, and culpable for S_1'' being stuck.

Theorem 5.3 (Exculpation) *Given a CO₂ system S_0 with a honest participant $A[P]$, whenever $S_0 \rightarrow^* S \equiv (\vec{u}, \vec{a})(s[T] | S_1) | S_2$ and A is culpable in S , there exist B and e such that:*

$$T \xrightarrow{A \Leftarrow B:e} \quad \text{and} \quad S \xrightarrow{A:\tau}^* \xrightarrow{A:\text{do}_s^B e}$$

Theorem 5.3 follows from the definition of honesty, and formalises the idea that honest participants can always overcome their culpability, simply by firing their contractual do actions (possibly after some internal actions).

Theorem 5.4 (Fidelity) *For all S with only honest participants s.t. $S \rightarrow^* S' \equiv (\vec{u}, \vec{a})(A[P] | s[T] | S_0) | S_1$, $(S' \xrightarrow{-s}^* \xrightarrow{A:\text{do}_s^B e}) \implies (T \xrightarrow{A \Leftarrow B:e})$ (where $\xrightarrow{-s}^*$ is any reduction not involving session s).*

Theorem 5.4 essentially says that each (honest) participant will strictly adhere to its contracts, once they have been fused in a session. It follows directly from the semantics of CO₂ (that forbid non-contractual do prefixes to be fired) and from the definition of honesty.

Theorem 5.5 below introduces the notion of global progress, which is slightly different from the contractual progress. In fact, progress in CO₂ is only meaningful *after* a session has been established, and thus a culpable participant exists. A system stuck without sessions may not progress because a set of compliant contracts cannot be found, or a fuse prefix is not enabled. In both cases, no participant may be deemed culpable, and thus responsible for the next move. However, the system may progress again if other (honest) participants joins it, allowing a session to be established.

Theorem 5.5 (Global Progress) *Given a CO₂ system S_0 with only honest participants, whenever $S_0 \rightarrow^* S \equiv (\vec{u}, \vec{a})(s[T] | S_1) | S_2$ where $T \neq \mathbf{0}$, then $S \rightarrow$.*

Theorem 5.5 follows from the definition of honesty (i.e. participants are always ready to fulfil their contracts), the fact that contract compliance guarantees contractual progress [10], Theorem 5.3, and the semantics of CO_2 (in particular, rule $[\text{CO}_2\text{-Do}]$). This result also holds for systems where a process takes part in multiple sessions: the honesty of all participants guarantees that all sessions will be completed.

Example 5.6 *We now give a simple example on a system with multiple sessions. We show how a seemingly honest process (B) could be deemed culpable due to the unexpected behaviour of other participants, and how honest participants guarantee progress of the whole system. Consider:*

$$S = (x, y, z, w) \left(\begin{array}{l} A[\text{tell}_A \downarrow_x (\mathbf{B!int}) . \text{fuse} . \text{fuse}] \quad | \quad B[\text{tell}_A \downarrow_y (\mathbf{A?int}) . \text{tell}_A \downarrow_z (\mathbf{C!bool}) . \text{do}_A^y \text{int} . \text{do}_C^z \text{bool}] \\ | \quad C[\text{tell}_A \downarrow_w (\mathbf{B?bool}) . \text{do}_B^w \text{bool}] \end{array} \right)$$

After all four contracts have been advertised to A and fused, the system reduces to:

$$S' = (s_1, s_2) \left(\begin{array}{l} A[\mathbf{0}] \quad | \quad B[\text{do}_A^{s_1} \text{int} . \text{do}_C^{s_2} \text{bool}] \quad | \quad C[\text{do}_B^{s_2} \text{bool}] \\ | \quad s_1[\mathbf{A\langle B?int \rangle} \quad | \quad \mathbf{B\langle A!int \rangle} \quad | \quad (\mathbf{AB}) : [] \quad | \quad (\mathbf{BA}) : []] \quad | \quad s_2[\mathbf{B\langle C!bool \rangle} \quad | \quad \mathbf{C\langle B?bool \rangle} \quad | \quad (\mathbf{BC}) : [] \quad | \quad (\mathbf{CB}) : []] \end{array} \right)$$

Even if both sessions s_1 and s_2 enjoy contractual progress, S' is stuck: A does not perform the promised action, thus remaining culpable in s_1 ; B is stuck waiting for A in s_1 , thus remaining culpable in s_2 .² Indeed, neither A nor B are ready in S' , and thus their implementations in S are not honest. Hence, global progress is not guaranteed.

Let us now consider the following variant of S , where all participants are honest:

$$\hat{S} = (x, y, z, w) \left(\begin{array}{l} A[(\text{tell}_A \downarrow_x (\mathbf{B!int}) . \text{do}_B^x \text{int}) \quad | \quad \text{fuse} \quad | \quad \text{fuse}] \\ | \quad B[\text{tell}_A \downarrow_y (\mathbf{A?int}) . \text{tell}_A \downarrow_z (\mathbf{C!bool}) . (\text{do}_A^y \text{int} . \text{do}_C^z \text{bool} + \tau . (\text{do}_A^y \text{int} \quad | \quad \text{do}_C^z \text{bool}))] \\ | \quad C[\text{tell}_A \downarrow_w (\mathbf{B?bool}) . \text{do}_B^w \text{bool}] \end{array} \right)$$

In this case, A will respect its contractual duties, while B will be ready to fulfil its contracts on both sessions — even if one is not activated, or remains stuck (here, τ represents an internal action, e.g. a timeout: if the first $\text{do}_A^y \text{int}$ cannot reduce, B falls back to running the sessions in parallel). The honesty of all participants in \hat{S} guarantees that, once a session is active, it will reach its completion.

6 Conclusions

CO_2 has been introduced in [2], and in [4] it has been instantiated to a theory of bilateral contracts inspired by [7]. Other variations are possible (e.g., with contracts based on logic formulae or event structures), since the core calculus abstracts from the contract model in use [3]. In this work, we explored the interplay between CO_2 and a contract model that fulfilled two basic requirements: (i) it supports multiparty agreements, and (ii) it provides an explicit description of the choreography that embodies each agreement. To the best of our knowledge, no other contract model provides the latter — and this prompted us towards the well-established results coming from the session types setting.

The seminal top-down approach of multiparty session types has been first described in [9]. In summary, the framework works as follows: designers specify a choreography (i.e. a global type), which is then projected onto local behaviours (i.e. local types), which in turn are used to typecheck processes. Our multiparty contract model uses these results “bottom up”, i.e. by synthesising a global type from local

²In this case, B is deemed culpable in s_2 because its implementation did not expect A to misbehave.

contracts, as in [10]. We built our framework upon a simple version of session types, and yet it turns out to be quite flexible.

We plan to extend our work so to offer even more flexibility. For example, by introducing a parameterised fuse primitive which, when more than one possible agreement is available (as in our introductory example), will form a session according to different criteria, e.g. by choosing the agreement involving the most (or least) number of participants. These criteria may be based on a semantic characterization of global types, e.g. as the one in [6]. We also plan to study the possibility for a participant to be involved in a session under multiple contracts — e.g. when a bank advertises two different services, and a customer publishes a contract which uses both of them (and possibly others) in a well-formed choreography.

Another research direction is the concept of “group honesty”. In fact, the current definition of honesty is quite strict: it basically verifies each participant in isolation, thus providing a sufficient (but not necessary) condition for progress. Consider, for example, a CO₂ system like:

$$S = (x, y) (A[\text{tell}_A \downarrow_x (B!int \oplus B!bool) . \text{fuse} . \text{do}_B^x \text{int}] \mid B[\text{tell}_A \downarrow_y (A?int + A?bool) . \text{do}_A^y \text{int}])$$

B is dishonest, since it is not ready for the bool branch of its contract. However, system S has progress: when B establishes a session with A, the latter will never take the bool branch; hence, B will not remain culpable. This kind of “group honesty” may be used to validate (sub-)systems of participants developed by the same organization: it would ensure that they never “cheat each other”, and are collectively honest when deployed in any context. Furthermore, the group honesty of all participants in a system S may turn out to be a necessary condition for the global progress of S .

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A Semantics of Local Types

Below are the rest of the semantic rules for local types / contracts (extending the ones on page 4). λ ranges over the labels $A \rightarrow B : e$ and $A \leftarrow B : e$, where the former means that a message of sort e is sent by participant A to B , and the latter means that a message of sort e is received by A from B .

$$\begin{array}{l} \mu \mathbf{x}.c \equiv c \{ \mathbf{x} / \mu \mathbf{x}.c \} \\ T_1 \xrightarrow{\lambda} T'_1 \Rightarrow T_1 | T_2 \xrightarrow{\lambda} T'_1 | T_2 \end{array} \quad \begin{array}{l} \text{commutative monoidal laws for } | \text{ and } \mathbf{0} \\ T_2 \equiv T_1 \xrightarrow{\lambda} T'_1 \equiv T'_2 \Rightarrow T_2 \xrightarrow{\lambda} T'_2 \end{array}$$

We define $\mathbf{0} = \bigoplus_{i \in \emptyset} \alpha_i !e_i; c_i = \sum_{i \in \emptyset} \alpha_i ?e_i; c_i$

B Synthesising a global type

$$\begin{array}{l} [\cdot] \frac{\Gamma \vdash A \langle c \rangle | B \langle c' \rangle | T \triangleright \mathcal{G} \quad T \Downarrow}{\Gamma \vdash A \langle B!e; c \rangle | B \langle A?e; c' \rangle | T \triangleright A \rightarrow B : e; \mathcal{G}} \quad [|\cdot] \frac{\circ \vdash T \triangleright \mathcal{G} \quad \circ \vdash T' \triangleright \mathcal{G}'}{\Gamma \vdash T | T' \triangleright \mathcal{G} | \mathcal{G}'} \\ [\oplus] \frac{\Gamma \vdash A \langle c \rangle | T \triangleright \mathcal{G} \quad \Gamma \vdash A \langle c' \rangle | T \triangleright \mathcal{G}' \quad T \Downarrow}{\Gamma \vdash A \langle c \oplus c' \rangle | T \triangleright \mathcal{G} + \mathcal{G}'} \quad [+] \frac{\Gamma \vdash B \langle c \rangle | T \triangleright \mathcal{G} \quad T \Downarrow}{\Gamma \vdash B \langle c + c' \rangle | T \triangleright \mathcal{G}} \\ [\mu] \frac{\exists 1 \leq i, j \leq k. (A_i \langle c_i \rangle | A_j \langle c_j \rangle) \Downarrow \quad \Gamma \cdot (A_1, \mathbf{x}_1) : \chi, \dots, (A_k, \mathbf{x}_k) : \chi \vdash A_1 \langle c_1 \rangle | \dots | A_k \langle c_k \rangle \triangleright \mathcal{G}}{\Gamma \vdash A_1 \langle \mu \mathbf{x}_1.c_1 \rangle | \dots | A_k \langle \mu \mathbf{x}_k.c_k \rangle \triangleright \mu \chi. \mathcal{G}} \\ [\mathbf{x}] \frac{\forall 1 \leq i \leq k. \Gamma(A_i, \mathbf{x}_i) = \chi}{\Gamma \vdash A_1 \langle \mathbf{x}_1 \rangle | \dots | A_k \langle \mathbf{x}_k \rangle \triangleright \chi} \quad [eq] \frac{T' \equiv T' \quad \Gamma \vdash T' \triangleright \mathcal{G}}{\Gamma \vdash T \triangleright \mathcal{G}} \quad [0] \frac{\forall n \in \mathcal{P}(T). T(n) = \mathbf{0}}{\Gamma \vdash T \triangleright \mathbf{0}} \end{array}$$

We define the *ready set* of a system as follows:

$$R(T) = \begin{cases} \{A \leftarrow B_i | i \in I\} \cup R(T') & \text{if } T \equiv A \langle \sum_{i \in I} B_i ?e_i; c_i \rangle | T' \\ \{A \rightarrow B_i | i \in I\} \cup R(T') & \text{if } T \equiv A \langle \bigoplus_{i \in I} B_i !e_i; c_i \rangle | T' \\ \{A \rightarrow B\} \cup R(T') & \text{if } T \equiv (AB) : e \cdot \rho | T' \\ \emptyset & \text{if } T \equiv \mathbf{0} \end{cases}$$

We overload $R(\cdot)$ on behaviours as expected, and define $T \Downarrow \iff \exists A \rightarrow B : A \rightarrow B \in R(T) \wedge B \leftarrow A \in R(T)$; we write $T \Downarrow$ if $T \Downarrow$ does not hold.

C Semantics of CO₂

Below is the rest of the semantic rules for CO₂ (extending the ones on page 6).

$$\begin{array}{l} [\text{CO}_2\text{-TAU}] \quad A[\tau.P + P' | Q] \rightarrow A[P | Q] \\ [\text{CO}_2\text{-DEF}] \quad \frac{X(\vec{u}, \vec{a}) := P \quad (\vec{z}, \vec{c}) (A[P \{ \vec{v} / \vec{u} \} \{ \vec{\beta} / \vec{a} \} | Q] | S) \rightarrow S'}{(\vec{z}, \vec{c}) (A[X(\vec{v}, \vec{\beta}) | Q] | S) \rightarrow S'} \\ [\text{CO}_2\text{-PAR}] \quad \frac{S \rightarrow S'}{S | S'' \rightarrow S' | S''} \quad [\text{CO}_2\text{-DEL}] \quad \frac{S \rightarrow S'}{(\vec{u}, \vec{a})S \rightarrow (\vec{u}, \vec{a})S'} \end{array}$$

Structural congruence for CO₂ (Z, Z', Z'' range over processes, systems, or latent contracts):

$$\begin{aligned}
(\vec{u}, \vec{b})A[(\vec{v}, \vec{c})P] &\equiv (\vec{u}, \vec{b})(\vec{v}, \vec{c})A[P] & A[\mathbf{0}] &\equiv \mathbf{0} & A[K] \mid A[K'] &\equiv A[K \mid K'] \\
Z \mid \mathbf{0} &\equiv Z & Z \mid Z' &\equiv Z' \mid Z & (Z \mid Z') \mid Z'' &\equiv Z \mid (Z' \mid Z'') \\
Z \mid (\vec{u}, \vec{a})Z' &\equiv (\vec{u}, \vec{a})(Z \mid Z') & \text{if } \vec{u} \cap \text{fnv}(Z) = \vec{a} \cap \text{fnv}(Z) = \emptyset & & \\
(\vec{u}, \vec{a})(\vec{v}, \vec{b})Z &\equiv (\vec{v}, \vec{b})(\vec{u}, \vec{a})Z & (\vec{u}, \vec{a})(\vec{v}, \vec{b})Z &\equiv (\vec{u} \parallel \vec{v}, \vec{a} \parallel \vec{b})Z & \\
(\vec{u}, \vec{a})Z &\equiv Z & \text{if } \vec{u} \cap \text{fnv}(Z) = \vec{a} \cap \text{fnv}(Z) = \emptyset & &
\end{aligned}$$