

Encoding Graph Transformation in Linear Logic

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Graph Transformation

- Graph Transformation Systems (GTS) — high-level approach to system modelling, UML, model-driven development, stochastic simulation
- Existing formalisations — algebraic-categorical (SPO, DPO), 2nd-order predicate logic
- High-level character, strong mathematical foundation
- Double-pushout (DPO) — mature approach, based on category theory

Encoding GT in LL — why?

- LL close to process algebras (Abramsky, Pfenning, Cervesato)
- Parallel composition ($\alpha \otimes \beta$), choice ($\alpha \& \beta$), reachability ($\vdash \alpha \multimap \beta$), replication (!)
- Semantic motivation: taking closer graph transformation and process algebra
- Existing approach: hyperedge replacement
- What we do: logic-based hyperedge replacement
- Practical motivation: making proofs about GTS easier

Typed hypergraphs

- Hypergraph $G = \langle V, E, s \rangle$
 V set of nodes, E set of hyperedges
assignment $s : E \rightarrow V^*$
- H-graph morphism — $\langle \phi_V : V_1 \rightarrow V_2, \phi_E : E_1 \rightarrow E_2 \rangle$
assignment-preserving
- Type h-graph $TG = \langle \mathcal{V}, \mathcal{E}, ar \rangle$
 \mathcal{V} set of node types, \mathcal{E} set of h-edge types
 $ar(l) : \mathcal{E} \rightarrow \mathcal{V}^*$
- TG -typed h-graph (G, t) , with $t : G \rightarrow TG$
- TG -typed h-graph morphism $f : (G_1, t_1) \rightarrow (G_2, t_2)$
is h-morphism $f : G_1 \rightarrow G_2$ with $t_2 \circ f = t_1$

DPO diagram

- Graph transformation rule $p : L \xleftarrow{l} K \xrightarrow{r} R$
span of typed h-graph morphisms (l, r) ,
 K interface, L/K to be deleted, R/K to be created,
rule application determined by match morphism m ,
 m determined up to iso by interface morphism d
- DPO conditions — (1) Identification condition:
 - m never identifies distinct L/K elements
 - m never identifies L/K elements with K ones
 (2) Dangling condition: for each node $n \in L/K$, all edges connected to n are in L/K , too

$$\begin{array}{ccccc}
 L & \xleftarrow{l} & K & \xrightarrow{r} & R \\
 m \downarrow & & \downarrow d & & \downarrow m^* \\
 (1) & & (2) & & \\
 G & \xleftarrow{g} & D & \xrightarrow{h} & H
 \end{array}$$

Overall plan

- Algebraic characterisation of DPO-GTS — monoidal structure with restriction over node names (hyperedge replacement)
- edges as relations (predicates) over nodes, parallel composition (tensor), α -renaming of nodes (restriction, or *hiding*)
- Translation to a quantified extension of ILL
- maps graph algebraic components to derivations, hence proof terms and linear λ -calculus
- terms represent identity of nodes and edges
- formulas represent type and connectivity — enough for reasoning about graphs up to iso

QILL

- $\alpha = A \mid L(N_1, \dots, N_n) \mid \mathbf{1} \mid \alpha_1 \otimes \alpha_2 \mid \alpha_1 \multimap \alpha_2 \mid !\alpha_1 \mid \alpha_1 \& \alpha_2 \mid \forall x : \beta. \alpha \mid \hat{\exists} x : \beta. \alpha \mid \alpha \downarrow N \mid \alpha = \alpha$
- $M = x \mid p \mid u \mid \text{nil} \mid N_1 \otimes N_2 \mid \lambda x. N \mid \hat{\lambda} u. N \mid N_1 \hat{\wedge} N_2 \mid N_1 N_2 \mid M \mid \langle N_1, N_2 \rangle \mid \text{fst } N \mid \text{snd } N$
- $\alpha \hat{=} \beta =_{df} (\alpha \multimap \beta) \& (\beta \multimap \alpha)$
- Sequent calculus proof rules
- Double-entry sequents — linear premises (Δ) and non-linear ones (Γ , equivalent to $!\Gamma$)

$$\Gamma; \Delta \vdash N :: \alpha$$

Encoding graphs

- Graph constructors: edge predicates, Nil (empty graph), \otimes (parallel composition), $\hat{\exists}$ (linearly resource-bound quantifier) to type restriction
- (closed) h-graph as (closed) formula

$$\hat{\exists} \overline{x : A}. \gamma$$

$\overline{x : A}$ sequence of typed variables,
either $\gamma = \mathbf{1}$ (empty graph) or $\gamma = L_1(\bar{x}_1) \otimes \dots \otimes L_k(\bar{x}_k)$
(a multiset of edge components)

- Adequate graph representation

Encoding rules (node only interfaces)

- \multimap for transformation, \forall for interface nodes
- Transformation rule (α, β graph formulas)

$$\overline{\forall x : A. \alpha} \multimap \beta$$

- rule application schema

$$\frac{\begin{array}{l} \Gamma; \cdot \Vdash \alpha_G \hat{=} \alpha_{G'} \quad \Gamma; \cdot \Vdash \alpha_H \hat{=} \alpha_{H'} \\ \alpha_{G'} = \hat{\exists} \overline{z : A. \alpha_L} [\overline{z : A} \xleftarrow{d_n} \overline{x : A}] \otimes \alpha_C \\ \alpha_{H'} = \hat{\exists} \overline{z : A. \alpha_R} [\overline{z : A} \xleftarrow{d_n} \overline{x : A}] \otimes \alpha_C \end{array}}{\Gamma; \overline{\forall x : A. \alpha_L} \multimap \alpha_R \Vdash \alpha_G \multimap \alpha_H} \xRightarrow{p,m}$$

rules I

$$\frac{}{\Gamma; u :: \alpha \vdash u :: \alpha} \text{Id}$$

$$\frac{}{\Gamma, x :: \alpha; \cdot \vdash x :: \alpha} \text{UIId}$$

$$\frac{\Gamma; \Delta_1 \vdash M :: \alpha \quad \Gamma; \Delta_2 \vdash N :: \beta}{\Gamma; \Delta_1, \Delta_2 \vdash M \otimes N :: \alpha \otimes \beta} \otimes R$$

$$\frac{\Gamma; \Delta, u :: \alpha, v :: \beta \vdash N :: \gamma}{\Gamma; \Delta, w :: \alpha \otimes \beta \vdash \text{let } u \otimes v = w \text{ in } N :: \gamma} \otimes L$$

$$\frac{\Gamma; \Delta, u :: \alpha \vdash M :: \beta}{\Gamma; \Delta \vdash \hat{\lambda}u : \alpha. M :: \alpha \multimap \beta} \multimap R$$

$$\frac{\Gamma; \Delta_1 \vdash N :: \alpha \quad \Gamma; \Delta_2, u :: \beta \vdash M :: \gamma}{\Gamma; \Delta_1, \Delta_2, w :: \alpha \multimap \beta \vdash \text{let } u = \hat{w}N \text{ in } M :: \gamma} \multimap L$$

RBQ rules I

$$\frac{\begin{array}{l} \Gamma; \Delta \vdash M :: \alpha[N_\Delta/x] \quad \Gamma; \cdot \vdash N_\Delta :: \beta \\ \Gamma; \Delta' \vdash n :: \beta \downarrow N_\Delta \quad \Gamma, x :: \beta; \cdot \vdash \text{nil} :: (\alpha[N_\Delta/x])[x/N_\Delta] = \alpha \end{array}}{\Gamma; \Delta, \Delta' \vdash !N_\Delta \otimes n \otimes M :: \hat{\exists}x : \beta.\alpha} \hat{\exists}R$$

$$\frac{\Gamma, x :: \beta; \Delta, n :: \beta \downarrow x, v :: \alpha \vdash N :: \gamma}{\Gamma; \Delta, w :: \hat{\exists}x : \beta.\alpha \vdash N[w/(!x \otimes n \otimes v)] :: \gamma} \hat{\exists}L$$

RBQ right intro

$$\frac{\Gamma; \Delta \vdash M :: \alpha[N_\Delta/x] \quad \Gamma; \cdot \vdash N_\Delta :: \beta \quad \Gamma; \Delta' \vdash n :: \beta \downarrow N_\Delta \quad \Gamma, x :: \beta; \cdot \vdash \text{id}_\alpha :: (\alpha[N_\Delta/x])[x/N_\Delta] = \alpha}{\Gamma; \Delta, \Delta' \vdash (!N_\Delta \otimes n) \otimes M :: \hat{\exists}x : \beta.\alpha} \hat{\exists}I$$

- standard hips. (1) $\alpha[N/x]$ graph with N in place of free x
- (2) N well-typed
- (3) there has to be a node (linear resource) named by N — \downarrow denotes naming reference to term
- (4) N does not occur free in α (unless $x = N$)
— a freshness condition, expressed using type equality and substitution
- N (N_Δ) depends on the derivation of $\alpha[N_\Delta/x]$

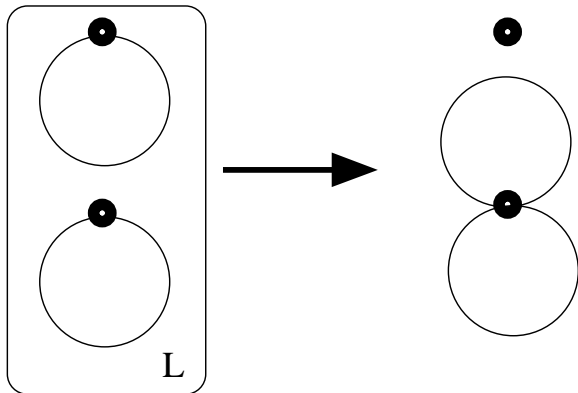
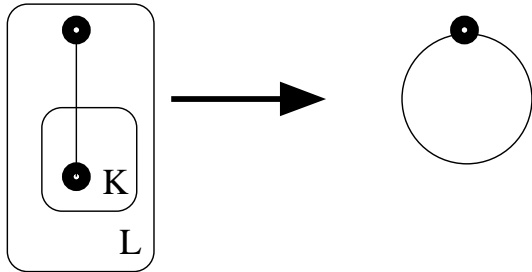
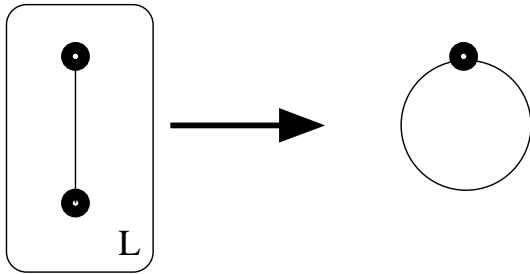
RBQ left intro

$$\frac{\Gamma, x :: \beta; \Delta, n :: \beta \downarrow x, v :: \alpha \vdash N :: \gamma}{\Gamma; \Delta, w :: \hat{\exists} x : \beta. \alpha \vdash \text{let } (!x \otimes n \otimes v) = w \text{ in } N :: \gamma} \hat{\exists}L$$

- (almost) standard rule
- $\hat{\exists}$ can be used to type restriction in graph expressions
- \downarrow introduction by axiom

$$\frac{\Gamma; \cdot \vdash N :: \alpha}{\Gamma; n :: \alpha \downarrow N \vdash n :: \alpha \downarrow N} \downarrow A$$

Incorrect matches



Quantifier and DPO conditions

- $\not\vdash (\hat{\exists}x : \beta. \alpha(x, x)) \multimap \hat{\exists}xy : \beta. \alpha(x, y)$
the resource for x cannot suffice for x and y .
- $\not\vdash \forall x : \beta. \beta \downarrow x \otimes \alpha(x, x) \multimap \hat{\exists}y : \beta. \alpha(y, x)$
 y and x should be instantiated with the same term —
blocked by the freshness condition in $\hat{\exists}$ introduction
- $\not\vdash (\hat{\exists}yx : \beta. \alpha_1(x) \otimes \alpha_2(x)) \multimap (\hat{\exists}x : \beta. \alpha_1(x)) \otimes \hat{\exists}x : \beta. \alpha_2(x)$
the two bound variables in the consequence require
distinct resources and refer to distinct occurrences

Examples I

$$\frac{x \vdash x \quad \frac{\quad}{x, \alpha(x, x) \vdash \hat{\exists}y.\alpha(x, y)} \hat{\exists}R \text{ fails}}{\frac{x, \alpha(x, x) \vdash \hat{\exists}xy.\alpha(x, y)}{\hat{\exists}x.\alpha(x, x) \vdash \hat{\exists}xy.\alpha(x, y)} \hat{\exists}L} \hat{\exists}R$$

$$\frac{x \vdash x \quad x, \alpha(x, x) \vdash \alpha(x/y, x)}{x, \alpha(x, x) \vdash \hat{\exists}y.\alpha(y, x)} \hat{\exists}R \text{ fails}$$

$$\frac{\frac{\dots}{x, \alpha(x) \vdash \hat{\exists}x.\alpha(x)} \hat{\exists}R \quad \frac{\quad}{y, \alpha(x) \vdash \hat{\exists}x.\alpha(x)} \hat{\exists}R \text{ fails}}{\frac{x, y, \alpha(x), \alpha(x) \vdash (\hat{\exists}x.\alpha(x)) \otimes \hat{\exists}x.\alpha(x)}{\hat{\exists}xy.\alpha(x) \otimes \alpha(x) \vdash (\hat{\exists}x.\alpha(x)) \otimes \hat{\exists}x.\alpha(x)} \hat{\exists}L(2)} \otimes R$$

Examples II — problem with Cut

$$\frac{\frac{\dots}{\Gamma; \alpha \downarrow x, \alpha \vdash \hat{\exists}x.\alpha(x)} \quad \frac{\dots}{\Gamma; \alpha \downarrow x, \alpha \vdash \hat{\exists}x.\alpha(x)}}{\Gamma; \alpha \downarrow x, \alpha \downarrow x, \alpha, \alpha \vdash (\hat{\exists}x.\alpha(x)) \otimes \hat{\exists}x.\alpha(x)} \otimes R$$

$$\Gamma; (\hat{\exists}x.\alpha(x)) \otimes \hat{\exists}x.\alpha(x) \vdash \hat{\exists}xy.\alpha(x) \otimes \alpha(y)$$

$$\Gamma; \alpha \downarrow x, \alpha \downarrow x, \alpha, \alpha \not\vdash \hat{\exists}xy.\alpha(x) \otimes \alpha(y)$$

Solution:

$$\frac{\frac{\dots}{\Gamma_1; \alpha \downarrow x, \alpha \vdash \hat{\exists}x.\alpha(x)} \quad \frac{\dots}{\Gamma_2; \alpha \downarrow x, \alpha \vdash \hat{\exists}x.\alpha(x)}}{\Gamma_1, \Gamma_2; \alpha \downarrow x, \alpha \downarrow y, \alpha, \alpha[y/x] \vdash (\hat{\exists}x.\alpha(x)) \otimes \hat{\exists}x.\alpha(x)} \otimes R$$

rules II

$$\frac{}{\Gamma; u :: \alpha \vdash u :: \alpha} \text{Id}$$

$$\frac{}{\Gamma, x :: \alpha; \cdot \vdash x :: \alpha} \text{UIId}$$

$$\frac{\Gamma_1; \Delta_1 \vdash M :: \alpha \quad \Gamma_2; \Delta_2 \vdash N :: \beta}{\Gamma_1, \Gamma_2; \Delta_1, \Delta_2 \vdash M \otimes N :: \alpha \otimes \beta} \otimes R$$

$$\frac{\Gamma; \Delta, u :: \alpha, v :: \beta \vdash N :: \gamma}{\Gamma; \Delta, w :: \alpha \otimes \beta \vdash \text{let } u \otimes v = w \text{ in } N :: \gamma} \otimes L$$

$$\frac{\Gamma; \Delta, u :: \alpha \vdash M :: \beta}{\Gamma; \Delta \vdash \hat{\lambda}u : \alpha. M :: \alpha \multimap \beta} \multimap R$$

$$\frac{\Gamma_1; \Delta_1 \vdash N :: \alpha \quad \Gamma_2; \Delta_2, u :: \beta \vdash M :: \gamma}{\Gamma_1, \Gamma_2; \Delta_1, \Delta_2, w :: \alpha \multimap \beta \vdash \text{let } u = w \hat{\lambda}N \text{ in } M :: \gamma} \multimap L$$

RBQ rules II

$$\Gamma; \Delta \vdash M :: \alpha[N/x] \qquad \Gamma; \cdot \vdash N :: \beta$$

$$\Gamma; \Delta' \vdash n :: \beta \downarrow$$

$$\Gamma, x :: \beta; \cdot \vdash \text{nil} :: (\alpha[N/x])[x/N] = \alpha$$

$$\frac{\Gamma, x :: \beta; \Delta, \Delta' \vdash !N \otimes n \otimes M :: \hat{\exists}x : \beta.\alpha}{\hat{\exists}R}$$

$$\Gamma, x :: \beta; \Delta, n :: \beta \downarrow, v :: \alpha \vdash N :: \gamma$$

$$\frac{\Gamma, x :: \beta; \Delta, n :: \beta \downarrow, v :: \alpha \vdash N :: \gamma}{\Gamma; \Delta, w :: \hat{\exists}x : \beta.\alpha \vdash N[w/(!x \otimes n \otimes v)] :: \gamma} \hat{\exists}L$$

Reachability

- Transformation — G_0, G_1 closed h-graphs, G_0 initial, P_1, \dots, P_k rules
 - G_1 reachable from by some application of the rules

$$!P_1, \dots, !P_k, G_0 \vdash G_1$$

- G_1 reachable by applying each rule once

$$P_1, \dots, P_k, G_0 \vdash G_1$$

- Translation complete with respect to reachability (sequent provable if graph reachable)
- Soundness — work in progress, general idea — logically valid implications are “read-only” transformations

Conclusion and further work

- Proof theory-driven approach to GT
- uses resource logic
- new quantifier to deal with restriction
- Extension to generalised interfaces ($\hat{\forall}$)
- two-level embedding approach
- Interest in mechanised theorem proving

Other rules

$$\frac{}{\Gamma; \cdot \vdash \text{nil} :: \mathbf{1}} \mathbf{1}I$$

$$\frac{\Gamma; \Delta \vdash M :: \mathbf{1} \quad \Gamma; \Delta' \vdash N :: \alpha}{\Gamma; \Delta, \Delta' \vdash \text{let nil} = M \text{ in } N :: \alpha} \mathbf{1}E$$

$$\frac{\Gamma; \Delta \vdash M :: \alpha \quad \Gamma; \Delta \vdash N :: \beta}{\Gamma; \Delta \vdash \langle M, N \rangle :: \alpha \& \beta} \&I$$

$$\frac{\Gamma; \Delta \vdash M :: \alpha \& \beta}{\Gamma; \Delta \vdash \text{fst } M :: \alpha} \&E1$$

$$\frac{\Gamma; \Delta \vdash M :: \alpha \& \beta}{\Gamma; \Delta \vdash \text{snd } M :: \beta} \&E2$$

$$\frac{\Gamma; \cdot \vdash M :: \alpha}{\Gamma; \cdot \vdash !M :: !\alpha} !I \quad \frac{\Gamma; \Delta_1 \vdash M :: !\alpha \quad \Gamma, p :: \alpha; \Delta_2 \vdash N :: \beta}{\Gamma; \Delta_1, \Delta_2 \vdash \text{let } p = M \text{ in } N :: \beta} !E$$

$$\frac{\Gamma, x :: \beta; \Delta \vdash M :: \alpha}{\Gamma; \Delta \vdash \lambda x. M :: \forall x : \beta. \alpha} \forall I \quad \frac{\Gamma; \Delta \vdash M :: \forall x : \beta. \alpha \quad \Gamma; \cdot \vdash N :: \beta}{\Gamma; \Delta \vdash MN :: \alpha[N/x]} \forall E$$

Encoding rules II

- \multimap for transformation, \forall (first order, standard) for interface nodes, $\hat{\forall}$ (second order, non-linearly resource bound) for interface edges

- Transformation rule as closed formula

$$\overline{\forall x : A. \hat{\forall} \overline{y : \gamma_i. \alpha}} \multimap \beta$$

with α, β, γ_i graph formulas

- applying a rule gives a transformation where α is deleted (consumed), β is created, after instantiating first nodes \bar{x} and then edges \bar{y} — the rule interface

Rule application schema

$$\begin{array}{c}
 \Gamma; \cdot \Vdash \alpha_G \hat{=} \alpha_{G'} \qquad \Gamma; \cdot \Vdash \alpha_H \hat{=} \alpha_{H'} \\
 \alpha_{G'} = \hat{\exists} \overline{z : A}. (\alpha_L \otimes (\bigotimes [\overline{\gamma_i} \xleftarrow{d_e} \overline{v : \gamma_i}])) [\overline{z : A} \xleftarrow{d_n} \overline{x : A}] \otimes \alpha_C \\
 \alpha_{H'} = \hat{\exists} \overline{z : A}. (\alpha_R \otimes (\bigotimes [\overline{\gamma_i} \xleftarrow{d_e} \overline{v : \gamma_i}])) [\overline{z : A} \xleftarrow{d_n} \overline{x : A}] \otimes \alpha_C \\
 \hline
 \Gamma; \forall x : A. \hat{\forall} \overline{v : \gamma_i}. \alpha_L \multimap \alpha_R \Vdash \alpha_G \multimap \alpha_H \quad \xRightarrow{p,m}
 \end{array}$$

For rules with node-only interfaces

$$\begin{array}{c}
 \Gamma; \cdot \Vdash \alpha_G \hat{=} \alpha_{G'} \qquad \Gamma; \cdot \Vdash \alpha_H \hat{=} \alpha_{H'} \\
 \alpha_{G'} = \hat{\exists} \overline{z : A}. \alpha_L [\overline{z : A} \xleftarrow{d_n} \overline{x : A}] \otimes \alpha_C \\
 \alpha_{H'} = \hat{\exists} \overline{z : A}. \alpha_R [\overline{z : A} \xleftarrow{d_n} \overline{x : A}] \otimes \alpha_C \\
 \hline
 \Gamma; \forall x : A. \alpha_L \multimap \alpha_R \Vdash \alpha_G \multimap \alpha_H \quad \xRightarrow{p,m}
 \end{array}$$

Translation — I

Constituents

$$\llbracket e_i(m, \dots, n) : L_i(A_m, \dots, A_n) \rrbracket =_{df} Id [\Gamma;; c_i :: L_i(x_m, \dots, x_n)]$$

$$\llbracket Nil \rrbracket =_{df} \mathbf{1}I [\Gamma]$$

$$\llbracket M \parallel N \rrbracket =_{df} \otimes I [\llbracket M \rrbracket;; \llbracket N \rrbracket]$$

$$\llbracket \nu n : A.N \rrbracket =_{df} \hat{\exists}I [\llbracket N \rrbracket;;$$

$$UIId [\Gamma;; x_n :: A];;$$

$$Id [\Gamma;; n :: A \downarrow x_n];;$$

$$\Gamma, y :: A; \cdot \vdash id : MainType(\llbracket N \rrbracket)[y/x_n]\#(y, x_n)]$$

Translation — II

Graph interfaces

$$\llbracket n : A \rrbracket =_{df} Id [\Gamma, x :: A;; \quad n :: A \downarrow x]$$

$$\llbracket \{n : A\} \rrbracket =_{df} \llbracket n : A \rrbracket$$

$$\llbracket \{n_1 : A_1\} \cup X \rrbracket =_{df} \otimes I [\llbracket \{n_1 : A_1\} \rrbracket;; \llbracket X \rrbracket]$$

Graph expressions

$$\llbracket X \vDash C \rrbracket =_{df} \otimes I [\llbracket X \rrbracket_I;; \llbracket C \rrbracket]$$

Graph derivations

- *graph formulas* — $\mathbf{1}, \otimes, \hat{\exists}, \downarrow$ fragment of the logic containing only primitive graph types (node and edge types)
- *graph context* — multiset of typed nodes and typed edge components.
- *graph derivation* — derivable sequent $\Gamma; \Delta \vdash N :: \gamma$, where γ is a graph formula, Δ is a graph context, Γ the environment, N a normal derivation.
- Uses only axioms and the introduction rules $\mathbf{1}I, \otimes I, \hat{\exists}I$.

Quantifier and congruence

$\hat{\exists}$ satisfies properties of renaming, exchange and distribution over \otimes

- $\vdash (\hat{\exists}x : \alpha.\beta(x)) \hat{=} (\hat{\exists}y : \alpha.\beta(y))$
- $\vdash (\hat{\exists}xy : \alpha.\gamma) \hat{=} (\hat{\exists}yx : \alpha.\gamma)$
- $\vdash (\hat{\exists}x : \alpha.\beta \otimes \gamma(x)) \hat{=} (\beta \otimes \hat{\exists}x : \alpha.\gamma(x)) \quad (x \text{ not in } \alpha)$

Equivalence between α and $\hat{\exists}x. \alpha$ generally fails in both directions, even when x does not occur free in α

Graphs and types — adequacy

- Isomorphism between graph expressions and graph derivations
- Isomorphism between graphs (congruence classes of graph expressions) and graph formulas modulo linear equivalence
- Curry-Howard style correspondence
- Possibility to implement hypergraphs and to reason about them

Graph transformation

- Less interested in component identity, higher-level translation, based on logic formulas
- Linear implication as transformation
- Standard quantifier for interface nodes
- Rule names as non-linear resources (unlimited application)

$$\llbracket M \Longrightarrow N \rrbracket^T =_{df} \llbracket M \rrbracket^T \multimap \llbracket N \rrbracket^T$$

$$\llbracket \Lambda x : A.N \rrbracket^T =_{df} \forall x : A. \llbracket N \rrbracket^T$$

$$\llbracket \pi(p) \rrbracket =_{df} FId [\Gamma;; \quad p :: \overline{\forall x : A_x. \llbracket L \rrbracket^T} \multimap \llbracket R \rrbracket^T]$$

Completeness and soundness

- Let $\Gamma_P = \Sigma \cup [\rho | \rho = \llbracket \pi(p) \rrbracket^T, p \in P]$, then for each reachable h-graph G

$$\Gamma_P; \llbracket G_0 \rrbracket^T \vdash \llbracket G \rrbracket^T$$

- Let R be a multiset of transformations, $\Delta_R = [\tau | \tau = \llbracket t \rrbracket^T, t \in R]$, then for each h-graph G reachable from G_0 by executing R

$$\Sigma; \llbracket G_0 \rrbracket^T, \Delta_R \vdash \llbracket G \rrbracket^T$$

- This is for completeness
- Soundness requires more work on the interpretation of linear implication