Graph Transformation with Topological Constraints

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Graph transformation

- GT: declarative modelling technique that extends term rewriting
- states as graphs, transitions as application of transformation rules (transformation steps), indeterministic character
- structured graphs
- use of preorders and derived topologies to define higher-level views of graphs

Algebraic GT

- category of graphs sets of edges and vertexes with source and target functions
- transformation rule $L \implies R$:
 - partial injective morphism single-pushout (SPO)
 - spans of total injective morphisms (from an interface) double-pushout (DPO)
- **graph** G, rule match $m : L \to G$:
 - total morphism that does not identify preserved elements and deleted ones
 - extra requirement (DPO): leaves no dangling edges

Rules and actions

- suggested intuition: rules as actions, rule application as action event, led by an agent, in a context
- dangling condition (DPO): all the effects of the transformation step are included in the match (modularity wrt rule application)
- interface subgraph of the match that is preserved
- Iocality of formulation (SPO): the specification of an action event depends on the agent, not on the context
- boundary includes the edges that may be deleted as side-effect

Distributed systems

- DS: structure made of multiple components and connections
- GT approach based on two-layer hierarchy (local/global) and DPO (Taentzer *et al.*)
 - global network architecture and reconfiguration
 - Iocal components and their behaviour
 - interfaces between components

Loose distributed approach

- network architecture multiple levels of connections
- architecture preservation graphs with constraints
 - Iocal: disabling rule matches
 - global: invalidating transformation steps
- simple representation: transitive associations a preorder
- Jooser than a hierarchy (e.g. containment, a poset)

LD systems

- behaviour modelled using SPO dangling condition dropped locally
- network architecture as preorder of places
- underlying graph elements mapped to places
- preorder-derived network topology
- region of application, implied by the topology, including the boundary — modularity recovered at the architectural level, in a looser sense wrt DPO

summarising

- SPO rule: specification of the action of an agent
- region of application: affected subgraph
- association as abstract connection relation
- modelling of granular systems
- possible use: high-level search for connection paths by pattern-matching

GT example



- SPO approach, initial graph (with two components) and transformation rule
- two applications of the rule, one to each component, may lead to disconnected components
- different ways to rule disconnection out e.g. by negative application condition
- here we look at a direct one an invariant stating that the two components stay connected

Spatial graphs

structured graph G (decoupled presentation)

- underlying graph U_G
- network architecture (spatial type graph): distinguished directed graph P_G in which nodes are places and edges express association. stronger requirement (proper hierarchy): P_G is acyclic (a containment hierarchy)
- total surjective *location* map (*loc*) from elements of U_G to places, represented as coupling edges
- coupling as containment, no empty places
- algebraic characterisation

Location

- \square minimal requirements on P_G
 - refl-trans closure of association gives ≤ as a preorder
 - *loc* is a function
 - for each edge *e* between n_1, n_2 in U_G , it holds $loc(n_1), loc(n_2) \le loc(e)$
 - for each n_3 s.t. $loc(n_3) \le loc(e)$, either $loc(n_3) \le loc(n_1)$ or $loc(n_3) \le loc(n_2)$
- stronger requirements:
 - \leq is a poset
 - there is a (unique) prime join in the preorder for each pair of places that are connected by an edge

Places and components

- \leq induces a subcomponent relation
- can be used to express pre/post-conditions in rules (using non-emptiness)
- *ctl*(*p*) = {*x* : *loc*(*x*) = *p*} is not generally a subgraph (e.g. an edge)
- hierarchy of components (vertical)
- given $p_1 < p_2$, then $ctl(p_2)$ is a subcomponent of $ctl(p_1)$
- connections (horizontal)
- given $p_1 ≤ q, p_2 ≤ q$, then ctl(q) is a connection
 (common connecting subcomponent) between $ctl(p_1)$ and $ctl(p_2)$

shapes



A and B are associated to the same component

A is in the interface of the component associated to B

shapes (continued)

E is embedded in A

E is independent



A and B are associated to components that share a connector





A and B are in mirror components

Derived topology

- s the specialisation preorder of an Alexandroff topology
- upper-closed sets of places are the open sets
- downward-closed sets of places are the closed sets
- the topology of the network (abstract regions) can be mapped back to the underlying graph (concrete regions)
- closed concrete regions are subgraphs closed view — gluing aspect
- open concrete regions are complements of subgraphs open view connecting aspect

Regions and matches

- each rule match gives an open abstract region $reg(m) = \bigcup_{x \in m} \{p : loc(x) \le p\}$ (subbase)
- ▶ the open concrete region $ctl(m) = \{x : loc(x) \in reg(m)\}$ includes all the dangling edges
- the closed concrete region proj(m) (closure of ctl(m))
 the smallest subgraph wrt the topology that includes all the side-effects (the boundary)

examples: incomplete view



- (Left) component A connected to B through C
- (Right) component A connected to B that includes C
- boxes as places, inclusion as reverse order

examples: open view



- prime join added, map extended to edges
- boxes as upper-closed sets (open sets)

examples: closed view



boxes as downward-closed sets (closed sets)

examples: closure view



boxes as non-point-like closed sets

Relations over regions

- relations between regions to express constraints on the model
 - inclusion between abstract regions: abstract subcomponent relation
 - intersection of open abstract regions (hence of concrete regions) is not empty: components are connected — they share a connector, e.g. a boundary edge
 - previous one false, intersection of closure of open abstract regions is not empty: components are adjacent — there is a component (concrete) that connects with both

GT example - revised



- initial graph with closed view and transformation rule
- prime join added to the original hierarchy
- mapping extended to edges
- constraint as rule invariant (places are non-empty)

SPO and DPO

- from a formal point of view
 - each match can be completed with an open abstract region
 - therefore with a concrete region, which includes all the side effects
 - possible to extract a DPO rule (minimal wrt the topology) that corresponds to the application of the SPO one — the closure region gives its match
- this can be shown diagrammatically

SPO diagram



- SPO rule application diagram with hierarchy
- **pushouts 2**, [L, R, G, H]
- pullbacks 1,3,4,5

Diagram scheme

derived rule	$ proj(L) < K' \longrightarrow proj(R) $
original rule	
topological constraint	
derived regions	$reg(L) \iff K \implies reg(R)$
dag transformation	$P_{G} < P_{D} \rightarrow P_{H}$
graph transformation	$G \iff D \implies H^{\mu}$

SPO match and derived DPO rule

SPO-DPO diagram



- embedded SPO diagram
- pullbacks 1–4, 7, 8, [K, K', reg(L), proj(L)], [K, K', reg(R), proj(R)]
- **pushouts 5**, 6, [K', proj(L), D, G], [K', proj(R), D, H]

Limit examples

- trivial underlying graph: a set of isolated nodes, connected by the network
- trivial network:
 - converting SPO matches into DPO ones:
 - let *loc* defined as an injection on nodes, such that for each pair of distinct n_1, n_2 , $loc(n_1)$ and $loc(n_2)$ are \leq -incomparable, and edges are mapped to prime joins
 - then for each SPO match, its closed concrete region is the smallest DPO one
 - in general, they are only the smallest wrt the topology

Conclusion

- possibility to extend notion of distributed graph transformation, allowing for more levels
- SPO with a weak notion of DPO-style compositionality
- Iocal dangling condition dropped to allow for simpler rules
- network architecture, global dangling condition
- algebraic characterisation
- work to be done on the modelling as well as on the formalisation