## Linear Programming Models for Traffic Engineering Under Combined IS-IS and MPLS-TE Protocols

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## Part I

# Introduction and Background

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## **Problem Description**

#### Scenario

- Very large scale networks have been built by the Network Engineers
- Experience and Best Common Practice
  - Planning
  - Reaction to critical Network Events



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- Network Design and Capacity Allocation
- Traffic Management and Restoration

Collection of IP Networks and routers controlled by a single administrative entity

#### Two routing protocols

- End System-to-Intermediate System (ES-IS)
- Intermediate System-to-Intermediate System (IS-IS)

IS-IS: link state routing protocol

## Interior Gateway Protocol

## IS-IS/OSPF

- Metric associated to each arc
- Route selection using Dijkstra's Shortest Path Algorithm
- Equal Cost Multiple Paths (ECMP)



## MPLS Technology

## MPLS-TE

- Allows the configuration of the traffic in order to optimize the resources.
  - Allows the building of VPN (Virtual Private Networks), using LSP (Label Switched Paths)-Tunnels.
- Extends existing IP protocol



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## **Restoration Schemes: Link Restoration**



Figure: Link Restoration for single failure condition

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## Restoration Schemes: Path Restoration



Figure: Path Restoration for single failure condition

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• 20% : scheduled network maintenance activities

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- 80% : unplanned failures where :
  - 30% shared link failures
  - 70% single link failures

- Is it possible to obtain a robust configuration of the network using the combination of IS-IS routing and MPLS-TE techniques?
- Is it possible to formulate the question as a pure LP problem?

- $\min c \cdot x$
- $A \cdot x = b$
- x ≥ 0

#### Graphs and Network Flows

• Generally, in Operations Research, the term network denotes a weighted graph G = (N, A) where the weights are numeric values associated to nodes and/or arcs of the graph.

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## **MMCF** Problem Definition

#### Notation

- G = (N, A) where N is the set of nodes and A ⊆ N × N is the set of arcs
- *K* is the set of commodities
- h th commodity determined by: (d<sup>h</sup>, s<sup>h</sup>, t<sup>h</sup>), where s<sup>h</sup> ∈ N and t<sup>h</sup> ∈ N, with s<sup>h</sup> ≠ t<sup>h</sup>, are the starting and ending node, and d<sup>h</sup> is the quantity to be moved from s<sup>h</sup> to t<sup>h</sup>

#### Formulations

- node-arc formulation : the variables are  $x_{ii}^h$
- arc-path formulation: the variables are  $f_p$

## MMCF: Node-arc formulation

#### The problem

• 
$$\min \sum_{h \in \mathcal{K}} \sum_{(i,j) \in \mathcal{A}} c_{ij}^h \cdot x_{ij}^h$$
  
• 
$$\sum_{(j,i) \in \mathcal{BS}(i)} x_{ji}^h - \sum_{(i,j) \in \mathcal{FS}(i)} x_{ij}^h = \begin{cases} -d^h & i = s^h \\ d^h & i = t^h \\ 0 & \text{otherwise} \end{cases}$$
  
• 
$$\sum_{h \in \mathcal{K}} x_{ij}^h \le u_{ij} \quad (i,j) \in \mathcal{A}$$
  
• 
$$x_{ij}^h \ge 0 \quad (i,j) \in \mathcal{A}$$

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|N||K| + |A| constraints |K||A| variables

## MMCF: Arc-path formulation

#### The notation

- $P^h$ : the set of paths in G from the node  $s^h$  to the node  $t^h$
- $P = \bigcup_{h \in K} P^h$ : the set of all relevant paths
- *p* ∈ *P* belongs to a unique commodity, identified by the starting and ending nodes of *p*; *h*(*p*)

• 
$$c_p = \sum_{(i,j) \in p} c_{ij}$$
 cost of the path  $p$ 

#### The problem

• min 
$$\sum_{h \in \mathcal{K}} \sum_{p \in \mathcal{P}^h} c_p$$
  
•  $\sum_{p \in P^h} f_p = d^h \quad h \in K$   
•  $\sum_{p:(i,j) \in p} f_p \leq u_{ij} \quad (i,j) \in A$   
•  $f_p \geq 0 \quad p \in P$ 

## The problem has |A| + |K| constraints



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Let's consider a reduced set of paths  $B \subset P$ .

$A_B$	$A_{(P/B)}$
$E_B$	$E_{(P/B)}$



# $D_B$ • max $\lambda u + \gamma d$ • $\lambda A_B + \gamma E_B \leq c_B$ • $\lambda \leq 0$

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$$D_B$$
• max  $\lambda u + \gamma d$ 
•  $\lambda A_B + \gamma E_B \leq c_B$ 
•  $\lambda \leq 0$ 

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- If we solve the master problem we obtain:  $\hat{f}_B$  and  $(\hat{\lambda}, \hat{\gamma})$ .
- Strong Duality: if  $(\hat{\lambda}, \hat{\gamma})$  is feasible to DMMCF then  $\hat{f}_B$  is optimal for MMCF
- Feasibility of the dual problem can be conveniently restated in terms of *reduced cost* of paths

$$ar{c}_{p} = c_{p} - \hat{\gamma}_{h(p)} - \sum_{(i,j)\in P} \hat{\lambda}_{ij} = \sum_{(i,j)\in P} (c_{ij} - \hat{\lambda}_{ij}) - \hat{\gamma}_{h(p)}$$

- For all the paths p that belong to the set B we have that  $\bar{c}_p \ge 0$ .
- What can we say about the paths  $p \in P \setminus B$ ?

- For each  $h \in K$ , we compute a minimum cost path from  $s^h$  to  $t^h$  by associating with each arc the new costs  $c_{ij} \hat{\lambda}_{ij}$
- This minimum cost path is indicated by p̂<sub>h</sub> reduced cost of paths
- We compute the *reduced cost* c
  <sub>p̂h</sub>: if it's greater or equal to zero for all h ∈ K: the set B holds the optimal paths
- If, instead, at least one path  $\hat{p}_h$  has negative reduced cost, then it can be added to B and the process is iterated.

## Part II

Models

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## LP MODEL with Node-Arc Formulation

#### Data

- ${\cal N}$  Node set
- $\mathcal{A}$  Edge set
- $\mathcal{F}$  Commodity set
- $u_{ij}$  Capacity associated with link (i, j)
- d<sup>f</sup> Effective bit rate of flow f
- $x_{ij}^{f}$  Share of flow f carried by IS-IS and traversing link (i, j)

#### Variables

- $u_{max}$  Maximum utilization in the network objective function
- *is<sup>f</sup>* Flow *f* carried by IS-IS
- $flow_{ij}^{f}$  Flow f carried by MPLS and traversing link (i, j)

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#### Variables

- $u_{max}$  Maximum utilization in the network objective function
- is<sup>f</sup> Flow f carried by IS-IS
- flow  $f_{ij}$  Flow f carried by MPLS and traversing link (i, j)

## Commodities aggregation by source node

$$flow_{ij}^h = \sum_{f:I(f)=h} flow_{ij}^f$$



#### Example

Commodities  $A \rightarrow B$ ,  $A \rightarrow C$ , and  $A \rightarrow D$ are replaced by a single commodity "A"

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## Commodities aggregation by source node

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#### Example

Commodities  $A \rightarrow B$ ,  $A \rightarrow C$ , and  $A \rightarrow D$ are replaced by a single commodity "A"

#### Objective function

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$$\begin{aligned} z &= \min(u_{max}) \\ \sum_{f \in \mathcal{F}} x_{ij}^{f} \cdot is^{f} + \sum_{h \in \mathcal{N}} flow_{ij}^{h} \leq u_{max} \cdot u_{ij} \quad \forall (i,j) \in \mathcal{A} \\ \sum_{j:(j,i) \in \mathcal{A}} flow_{ji}^{h} - \sum_{j:(i,j) \in \mathcal{A}} flow_{ij}^{h} = \begin{cases} -\sum_{f \in F(h)} d^{f} + is^{f} & i = h \\ d^{f} - is^{f} & if i \neq h, i = E(f), f \in F(h) \\ 0 & \text{otherwise} \end{cases} \\ flow_{ii}^{h} \geq 0 \quad \forall (i,j) \in \mathcal{A}, \ \forall h \in \mathcal{N} \end{aligned}$$

 $is^{f} \geq 0 \quad \forall f \in \mathcal{F}$ 

#### Capacity constraints

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$$z = \min(u_{max})$$

$$\sum_{f \in \mathcal{F}} x_{ij}^{f} \cdot is^{f} + \sum_{h \in \mathcal{N}} flow_{ij}^{h} \leq u_{max} \cdot u_{ij} \quad \forall (i, j) \in \mathcal{A}$$

$$\sum_{j:(j,i) \in \mathcal{A}} flow_{ji}^{h} - \sum_{j:(i,j) \in \mathcal{A}} flow_{ij}^{h} = \begin{cases} -\sum_{f \in F(h)} d^{f} + is^{f} & i = h \\ d^{f} - is^{f} & if i \neq h, i = E(f), f \in F(h) \\ 0 & \text{otherwise} \end{cases}$$

$$flow_{ij}^{h} \geq 0 \quad \forall (i, i) \in \mathcal{A} \quad \forall h \in \mathcal{N}$$

 $\begin{aligned} & \text{flow}_{ij}^{ii} \geq 0 \quad \forall (i,j) \in \mathcal{A}, \ \forall h \in \mathcal{N} \\ & \text{is}^{f} \geq 0 \quad \forall f \in \mathcal{F} \end{aligned}$ 

Flow conservation equations

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$$z = \min(u_{max})$$

$$\sum_{f \in \mathcal{F}} x_{ij}^{f} \cdot is^{f} + \sum_{h \in \mathcal{N}} flow_{ij}^{h} \leq u_{max} \cdot u_{ij} \quad \forall (i,j) \in \mathcal{A}$$

$$\sum_{j:(j,i) \in \mathcal{A}} flow_{ji}^{h} - \sum_{j:(i,j) \in \mathcal{A}} flow_{ij}^{h} = \begin{cases} -\sum_{f \in F(h)} d^{f} + is^{f} & i = h \\ d^{f} - is^{f} & if i \neq h, i = E(f), f \in F(h) \\ 0 & \text{otherwise} \end{cases}$$

$$flow_{ii}^{h} \geq 0 \quad \forall (i,i) \in \mathcal{A}, \forall h \in \mathcal{N}$$

 $iow_{ij} \ge 0 \quad \forall (I,J) \in \mathcal{A},$  $is^{f} \ge 0 \quad \forall f \in \mathcal{F}$ 

## Positivity constraint

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$$z = \min(u_{max})$$

$$\sum_{f \in \mathcal{F}} x_{ij}^{f} \cdot is^{f} + \sum_{h \in \mathcal{N}} flow_{ij}^{h} \leq u_{max} \cdot u_{ij} \quad \forall (i, j) \in \mathcal{A}$$

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$$flow_{ij}^{h} \geq 0 \quad \forall (i, i) \in \mathcal{A} \quad \forall h \in \mathcal{N}$$

 $\begin{aligned} & \textit{flow}_{ij}^n \geq 0 \quad \forall (i,j) \in \mathcal{A}, \; \forall h \in \mathcal{N} \\ & \textit{is}^f \geq 0 \quad \forall f \in \mathcal{F} \end{aligned}$ 

## Positivity constraint

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$$z = \min(u_{max})$$

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$$flow_{ij}^{h} \geq 0 \quad \forall (i, i) \in \mathcal{A} \quad \forall h \in \mathcal{N}$$

 $\begin{aligned} & \text{flow}_{ij}^* \geq 0 \quad \forall (i,j) \in \mathcal{A}, \ \forall h \in \mathcal{N} \\ & \text{is}^f \geq 0 \quad \forall f \in \mathcal{F} \end{aligned}$ 



 $\sum_{f \in \mathcal{F}} x_{ij}^{f,l} \cdot is^{f} + \sum_{h \in \mathcal{N}} \textit{flow}_{ij}^{h} + \sum_{h \in \mathcal{N}} (x_{ij}^{l+,l} \cdot \textit{flow}_{l_{+}}^{h} + x_{ij}^{l-,l} \cdot \textit{flow}_{l_{-}}^{h}) \leq u_{max} \cdot c_{ij} \quad \forall (i,j) \neq l_{+}, l_{-} \in \mathcal{A}$ 

Share of flow carried by IS-IS when edge *I* fails

Flow carried by explicit MPLS LSP along link (i, j)

Share of flow flowing through edge l from node p to node q (arc  $l_+$ ) and those from node q to node p (arc  $l_-$ ) that is rerouted by IS-IS along link (i, j)

#### ▶ Proof

$$\sum_{f \in \mathcal{F}} x_{ij}^{f,l} \cdot is^{f} + \sum_{h \in \mathcal{N}} \textit{flow}_{ij}^{h} + \sum_{h \in \mathcal{N}} (x_{ij}^{l_+,l} \cdot \textit{flow}_{l_+}^{h} + x_{ij}^{l_-,l} \cdot \textit{flow}_{l_-}^{h}) \leq u_{max} \cdot c_{ij} \quad \forall (i,j) \neq l_+, l_- \in \mathcal{A}$$

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#### Proof

## **TINet Italy-Normal Condition**



- 18 nodes
- 54 arcs

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- 306 flows
- 1279 variables
- 378 constraints

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## **TINet Italy-Normal Condition**



- 18 nodes
- 54 arcs
- 306 flows
- 1279 variables
- 378 constraints

Routing Optimization						
[		U <sub>max</sub>	Gain (Def)	Gain (Tis)	# LSP	
	Default	$u_{max} = 72\%$	—	—	0	
	Existing metrics	$u_{max} = 66\%$	8.3%	_	0	
	IS-IS opt.	$u_{max} = 61\%$	15.2%	7.6%	0	
	MPLS-TE opt.	$u_{max} = 59\%$	18.1%	10.6%	105	

## TINet Italy - Survivability



- 18 nodes
- 54 arcs
- 306 flows
- 1279 variables
- 1782 constraints

#### Survivability Optimization

	U <sub>max</sub>	Gain (Def)	Gain (Tis)	# LSP
Default	$u_{max} = 128\%$	-	-	0
Existing metrics	$u_{max} = 117\%$	8.6%	-	0
IS-IS opt.	$u_{max} = 85\%$	33.6%	27.3%	0
MPLS-TE opt.	$u_{max} = 83\%$	35.2%	29.1%	86

## Graphical Results - Routing



## Graphical Results - Routing



## Graphical Results - Survivability





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## Graphical Results - Survivability





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## **IBCN** European Network



- 37 nodes
- 114 arcs

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- 1332 flows
- 5551 variables
- 1483 constraints
- 7867 constraints (with survivability)

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## **IBCN** - Normal condition



- 37 nodes
- 114 arcs
- 1332 flows
- 5551 variables
- 1483 constraints
- 7867 constraints (with survivability)

#### **Routing Optimization**

	Work. Cond.	Failure Cond.	# LSP
IS-IS/OSPF with def. metrics	71%	101%	0
IS-IS with optim. metrics	54%	74%	0
LP models with optim. metrics	40%	64%	543



Figure: Is-Is Routing Normal Condition Default Metrics Umax=71% Figure: Is-Is Routing Normal Condition Optimized Metrics Umax=54%

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Figure: Is-Is Routing Normal Condition Optimized Metrics Umax=54% Figure: Mpls Routing Normal Condition Optimized Metrics Umax=40%

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Figure: Is-Is Routing Failure Condition Default Metrics Umax=101% Figure: Is-Is Routing Failure Condition Optimized Metrics Umax=74%

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Figure: Is-Is Routing Failure Condition Optimized Metrics Umax=74% Figure: Mpls Routing Failure Condition Optimized Metrics Umax=64%

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An extended description of this work is available as Technical Report of the University of Pisa at the following link:

http://compass2.di.unipi.it/TR/Files/TR-08-24.pdf.gz

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Thank you for your attention

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