

Tutorial on Fundamentals of Algebraic Graph Transformation

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Based on
FAGT-Book, EATCS Monographs in TCS, Springer 2006



Overview

- 1 General Introduction and Motivation
- 2 Category of Graphs and Gluing Construction
- 3 Graph Transformation Systems
- 4 Independence of Graph Transformations and Critical Pairs
- 5 Adhesive HLR Categories and Typed Attributed Graph Transformation Systems
- 6 Advanced Features and Conclusion



Part I

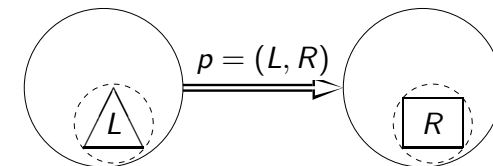
General Introduction and Motivation

- 1 What is Graph Transformation?
- 2 Aims and Paradigms of Graph Transformation
- 3 Graph Transformation Approaches
- 4 Application Areas of Graph Transformation Systems



What is Graph Transformation?

Rule-based modification of graphs



- from Chomsky grammars on strings to graph grammars;
- from term rewriting to graph rewriting;
- from textual description to visual modeling.



Computing by graph transformation is a fundamental concept for

- visual modeling and specification,
- model transformation,
- concurrency and distribution,
- software development.

Projects

Supported by EU projects since 1990:
COMPUGRAPH 1 + 2, GETGRATS, APPLIGRAPH, SEGRAVIS.



- 1 Node label replacement approach
- 2 Hyperedge replacement approach
- 3 Algebraic approach
 - Double Pushout (DPO) (since 1973)
 - Single Pushout (SPO) (since 1984/90)
 - High Level Replacement (HLR) (since 1991/2004)
- 4 Logical approach
- 5 Theory of 2-structures
- 6 Programmed graph replacement approach

Literature

Handbook of Graph Grammars and Computing by Graph Transformation,
Vol. 1 (1997)



Application areas are

- model and program transformation;
- syntax and semantics of visual languages;
- visual modeling of behavior and programming;
- modeling, metamodeling, and model-driven architecture;
- software architectures and evolution;
- refactoring of programs and software systems;
- security policies.

Literature

Handbook of Graph Grammars and Computing by Graph Transformation,
Vol. 2 (1999)
Proc. ICGT '02-06, LNCS



Part II

Category of Graphs and Gluing Construction

- 5 Graphs, Typed Graphs and Morphisms
- 6 Categories of Sets and Graphs
- 7 Mono-, Epi- and Isomorphisms
- 8 Pushouts as Gluing Construction
- 9 Composition and Decomposition of Pushouts
- 10 Pullbacks as Dual Construction of Pushouts



Definition

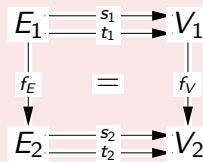
graph $G = (V, E, s, t)$ consists of

- sets V of nodes and E of edges, and
- source and target functions $s, t : E \rightarrow V$

graph morphism $f : G_1 \rightarrow G_2$, $f = (f_V, f_E)$ consists of two functions $f_V : V_1 \rightarrow V_2$ and $f_E : E_1 \rightarrow E_2$ with

$$f_V \circ s_1 = s_2 \circ f_E \text{ and } f_V \circ t_1 = t_2 \circ f_E$$

composition $g \circ f = (g_V \circ f_V, g_E \circ f_E) : G_1 \rightarrow G_3$ of $f : G_1 \rightarrow G_2$ and $g : G_2 \rightarrow G_3$ is graph morphism



Example

Top: graph $G_S = (V_S, E_S, s_S, t_S)$, with

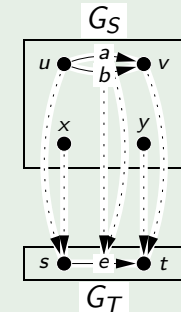
- $V_S = \{u, v, x, y\}$, $E_S = \{a, b\}$,
- $s_S : E_S \rightarrow V_S : a, b \mapsto u$,
- $t_S : E_S \rightarrow V_S : a, b \mapsto v$

Bottom: graph $G_T = (V_T, E_T, s_T, t_T)$, with

- $V_T = \{s, t\}$, $E_T = \{e\}$,
- $s_T : E_T \rightarrow V_T : e \mapsto s$,
- $t_T : E_T \rightarrow V_T : e \mapsto t$

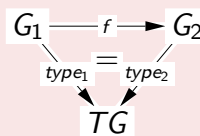
Inbetween: graph morphism $f : G_S \rightarrow G_T$ with

- $f_V : V_S \rightarrow V_T : u, x \mapsto s; v, y \mapsto t$
- $f_E : E_S \rightarrow E_T : a, b \mapsto e$

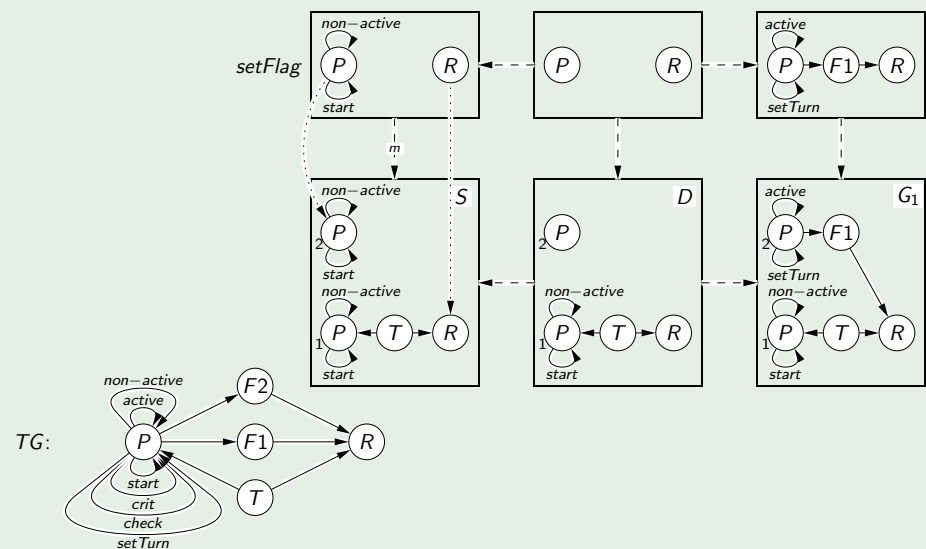


Definition

- **type graph** is a distinguished graph $TG = (V_{TG}, E_{TG}, s_{TG}, t_{TG})$
- **typed graph** $G^T = (G, type)$ over TG is graph G and graph morphism $type : G \rightarrow TG$
- **typed graph morphism** $f : G_1^T \rightarrow G_2^T$ is graph morphism $f : G_1 \rightarrow G_2$ with $type_2 \circ f = type_1$



Example



Definition

category $\mathbf{C} = (Ob_{\mathbf{C}}, Mor_{\mathbf{C}}, \circ, id)$ defined by

- class $Ob_{\mathbf{C}}$ of **objects**;
- set $Mor_{\mathbf{C}}(A, B)$ of **morphisms** $\forall A, B \in Ob_{\mathbf{C}}$;
- **composition** $\circ : Mor_{\mathbf{C}}(B, C) \times Mor_{\mathbf{C}}(A, B) \rightarrow Mor_{\mathbf{C}}(A, C)$
 $\forall A, B, C \in Ob_{\mathbf{C}}$,
- **identity** morphism $id_A \in Mor_{\mathbf{C}}(A, A) \forall A \in Ob_{\mathbf{C}}$;

such that:

- 1 **Associativity.** $(h \circ g) \circ f = h \circ (g \circ f) \quad \forall A \xrightarrow{f} B \xrightarrow{g} C \xrightarrow{h} D$
- 2 **Identity.** $f \circ id_A = f$ and $id_B \circ f = f \quad \forall f : A \rightarrow B$

for $f \in Mor_{\mathbf{C}}(A, B)$, we write $f : A \rightarrow B$



1 category **Sets**

- objects: sets, morphisms: functions $f : A \rightarrow B$,
- composition for $f : A \rightarrow B$ and $g : B \rightarrow C$ defined by
 $(g \circ f)(x) = g(f(x))$,
- identity: identical mapping $id_A : A \rightarrow A : x \mapsto x$.

2 category **Graphs**

- objects: graphs, morphisms: graph morphisms,
- composition and identity: componentwise on nodes and edges.

3 category **Graphs_{TG}**

- objects: typed graphs, morphisms: typed graph morphisms,
- composition and identity: as in **Graphs**.

4 category **Alg(Σ)**

- objects: algebras over a given signature Σ , morphisms: homomorphisms
- composition and identity: componentwise on the carrier sets.



Definition

$m : B \rightarrow C \in Mor_{\mathbf{C}}$ is **monomorphism** if

$$m \circ f = m \circ g \text{ implies } f = g \quad \forall f, g : A \rightarrow B \in Mor_{\mathbf{C}}$$

$$A \begin{array}{c} \xrightarrow{f} \\ \xrightarrow{g} \end{array} B \xrightarrow{m} C \quad A \xrightarrow{e} B \begin{array}{c} \xrightarrow{f} \\ \xrightarrow{g} \end{array} C$$

$e : A \rightarrow B \in Mor_{\mathbf{C}}$ is **epimorphism** if

$$f \circ e = g \circ e \text{ implies } f = g \quad \forall f, g : B \rightarrow C \in Mor_{\mathbf{C}}$$

$i : A \rightarrow B \in Mor_{\mathbf{C}}$ is **isomorphism** if

$$\text{there is } i^{-1} : B \rightarrow A \in Mor_{\mathbf{C}} \text{ with } i \circ i^{-1} = id_B \text{ and } i^{-1} \circ i = id_A$$

Fact

In **Sets**, **Graphs**, and **Graphs_{TG}** the monomorphisms (or epimorphisms or isomorphisms) are exactly those morphisms which are injective (or surjective or bijective, respectively).

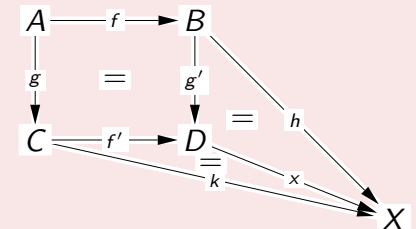


Definition

pushout (PO) over morphisms

$f : A \rightarrow B$ and $g : A \rightarrow C$ defined by

- a pushout object D and
- morphisms $f' : C \rightarrow D$ and $g' : B \rightarrow D$ with $f' \circ g = g' \circ f$



with *universal property*:

For all objects X , morphisms $h : B \rightarrow X$, $k : C \rightarrow X$ with $k \circ g = h \circ f$: there is a unique morphism $x : D \rightarrow X$ with $x \circ g' = h$ and $x \circ f' = k$

The pushout construction is unique up to isomorphism.

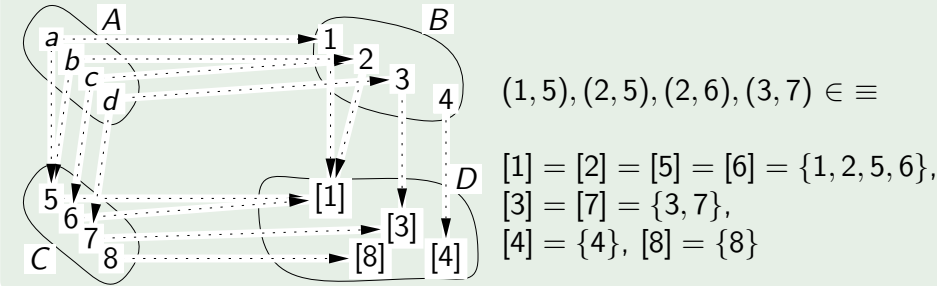


Pushouts in Sets

Fact

In **Sets**, pushout $C \xrightarrow{f'} D \xleftarrow{g'} B$ over $f : A \rightarrow B$ and $g : A \rightarrow C$ is $D = B \dot{\cup} C \equiv$, with \equiv generated by $(f(a), g(a)) \in \equiv \quad \forall a \in A$ and $f'(c) = [c] \quad \forall c \in C$ and $g'(b) = [b] \quad \forall b \in B$.

Example

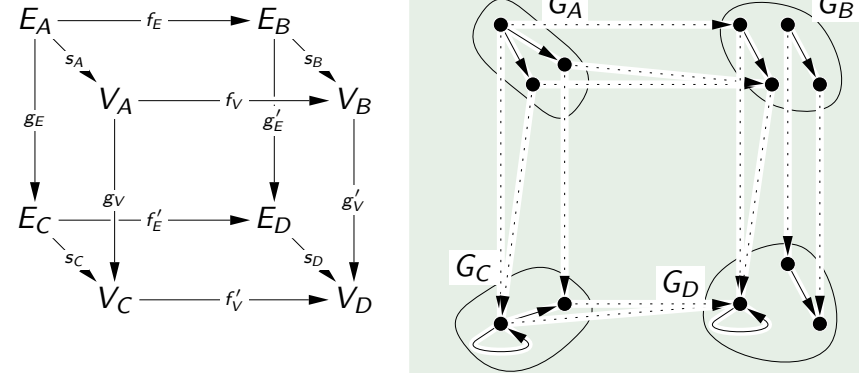


Pushouts in Graphs and Graphs_{TG}

Fact

In **Graphs** and **Graphs_{TG}**, pushouts can be constructed componentwise for nodes and edges in **Sets**.

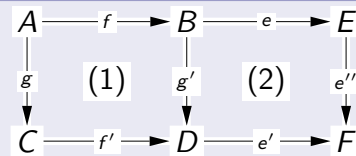
Example



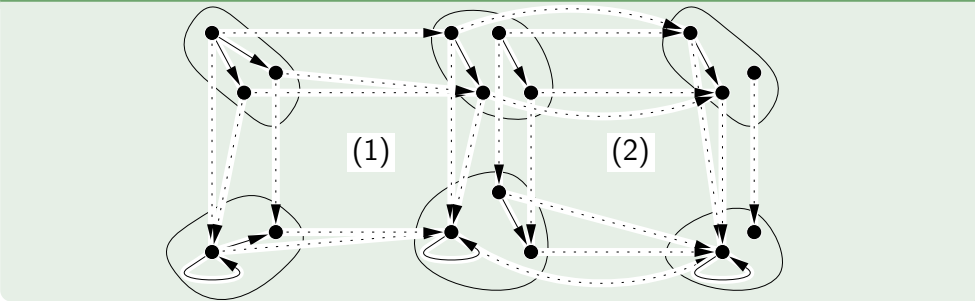
Composition and Decomposition of Pushouts

Fact

- **PO composition:**
(1) and (2) POs \Rightarrow (1) + (2) PO
- **PO decomposition:**
(1) and (1) + (2) POs \Rightarrow (2) PO



Example

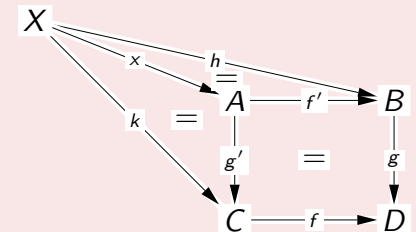


Pullbacks as Dual Construction of Pushouts

Definition

pullback (PB) over morphisms $f : C \rightarrow D$ and $g : B \rightarrow D$ defined by

- a pullback object A and
- morphisms $f' : A \rightarrow B$ and $g' : A \rightarrow C$ with $g \circ f' = f \circ g'$



with **universal property**:

For all objects X , morphisms $h : X \rightarrow B$, $k : X \rightarrow C$ with $f \circ k = g \circ h$: there is a unique morphism $x : X \rightarrow A$ with $f' \circ x = h$ and $g' \circ x = k$.

The composition and decomposition of pullbacks is dual to pushouts.



Fact

In **Sets**, pullback $C \xleftarrow{g'} A \xrightarrow{f'} B$ over $f : C \rightarrow D$ and $g : B \rightarrow D$:
 $A = \bigcup_{d \in D} f^{-1}(d) \times g^{-1}(d) = \{(c, b) \mid f(c) = g(b)\} \subseteq C \times B$
 with $f' : A \rightarrow B : (c, b) \mapsto b$ and $g' : A \rightarrow C : (c, b) \mapsto c$.

Special case: $A \cong B \cap C$ for inclusions f and g .

In **Graphs** and **Graphs_{TG}**, pullbacks can be constructed componentwise for nodes and edges in **Sets**.



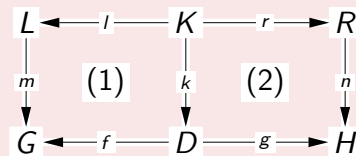
Graph Productions and Transformations

Definition

(typed) graph production

$p = (L \xleftarrow{l} K \xrightarrow{r} R)$ consists of

- (typed) graphs L , K , and R ,
- injective (typed) graph morphisms l and r



direct (typed) graph transformation $G \xrightarrow{p,m} H$ given by POs (1) and (2), production p and match $m : L \rightarrow G$

(typed) graph transformation, $G_0 \xrightarrow{*} G_n$, is sequence $G_0 \Rightarrow G_1 \Rightarrow \dots \Rightarrow G_n$ of direct (typed) graph transformations



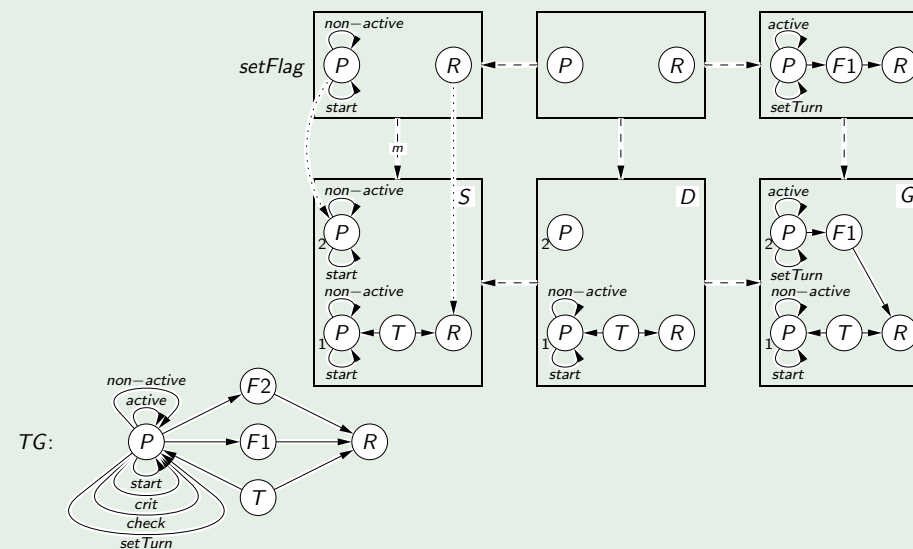
Graph Transformation Systems

- 11 Graph Productions and Transformations
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- 15 Construction of Graph Transformations
- 16 Embedding of Transformations



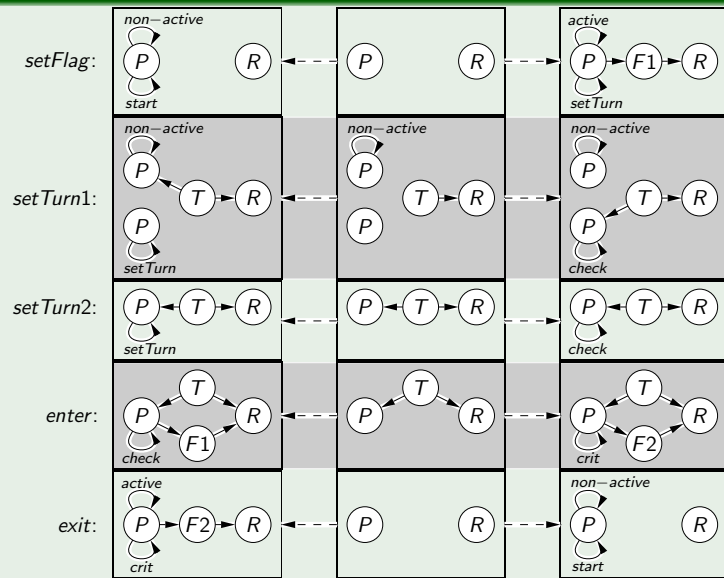
Recap: Example Mutual Exclusion

Example



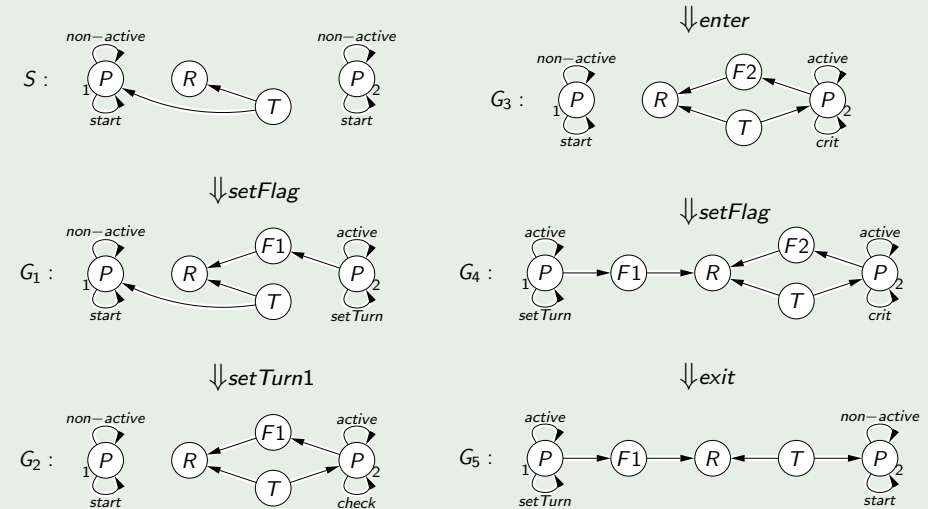
Example: Mutual Exclusion 2

Example



Example: Mutual Exclusion 3

Example



Graph Transformation Systems, Grammars and Languages

Definition

- (typed) graph transformation system $GTS = (TG, P)$ consists of (type graph TG and) set of (typed) graph productions P
- (typed) graph grammar $GG = (GTS, S)$ consists of GTS and (typed) start graph S
- (typed) graph language L of GG is defined by

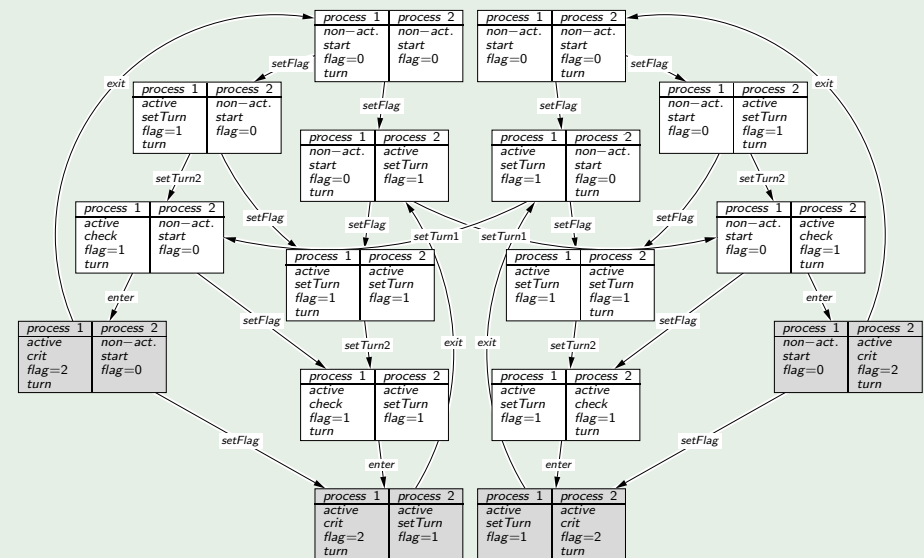
$$L = \{G \mid \exists (\text{typed}) \text{ graph transformation } S \xrightarrow{*} G\}.$$

Example

- typed graph transformation system $ME = (TG, P)$
- typed graph grammar $MutualExclusion = (TG, P, S)$
- $P = \{setFlag, setTurn1, setTurn2, enter, exit\}$.

Example: Language of Mutual Exclusion Grammar

Example

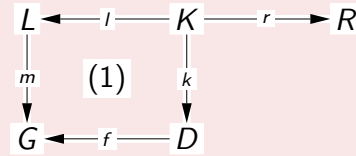


Applicability and Gluing Condition

Problem: When is production p applicable via match m ?

Definition

production p is **applicable** to G via match m if context graph D exists such that (1) is PO



Gluing condition: $IP \cup DP \subseteq GP$

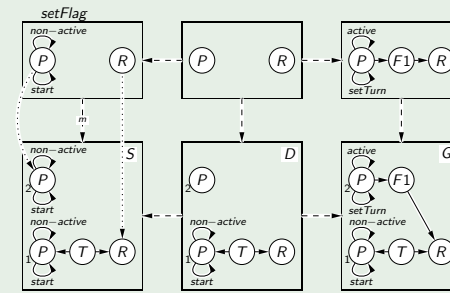
- **gluing points** $GP = I_V(V_K) \cup I_E(E_K) = I(K)$
- **identification points** $IP = \{v \in V_L \mid \exists w \in V_L, w \neq v : mv(v) = mv(w)\} \cup \{e \in E_L \mid \exists f \in E_L, f \neq e : m_E(e) = m_E(f)\}$
- **dangling points** $DP = \{v \in V_L \mid \exists e \in E_G \setminus m_E(E_L) : s_G(e) = mv(v) \text{ or } t_G(e) = mv(v)\}$

Fact

Context graph D with the PO (1) exists iff the gluing condition is satisfied. If D exists, it is unique up to isomorphism.

Example and Counterexample: Gluing Condition

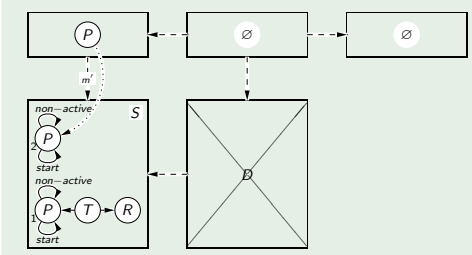
Example



- $GP = I(K)$: both nodes in L ,
- $IP = \emptyset$,
- $DP = \text{node labelled } R$.

gluing condition is satisfied with $IP \cup DP \subseteq GP$

Counterexample



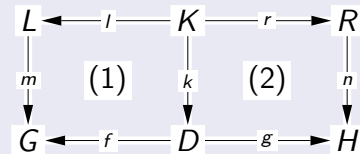
- $GP = I(K) = \emptyset$,
- $IP = \emptyset$,
- $DP = \text{node labelled } P$.

gluing condition is not satisfied, because $DP \not\subseteq GP$

Construction of Direct Graph Transformations

Fact

If gluing condition is satisfied, $G \xrightarrow{p,m} H$ can be constructed in two steps:



- 1 Delete those nodes and edges in G that are reached by the match m , but keep the image of K , i.e. $D = (G \setminus m(L)) \cup m(I(K))$, such that $G = L +_K D$ in PO (1).
- 2 Add those nodes and edges that are newly created in R , i.e. $H = D \dot{\cup} (R \setminus r(K))$, such that $H = R +_K D$ in PO (2).

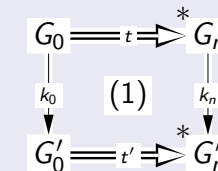
This construction is unique up to isomorphism.

Embedding of Graph Transformations

Problem: When can graph transformation $t : G_0 \xrightarrow{*} G_n$ be extended to $t' : G'_0 \xrightarrow{*} G'_n$ for $k_0 : G_0 \rightarrow G'_0$?

Theorem

Given transformation $t : G_0 \xrightarrow{*} G_n$ and consistent morphism $k_0 : G_0 \rightarrow G'_0$ w.r.t. t , then there is an extension diagram (1) over t and k_0 .



Problem: What is consistency of k_0 with respect to t ?

Definition

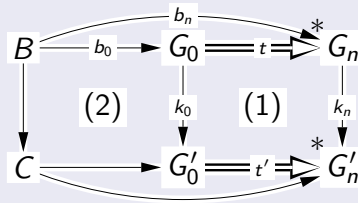
boundary B is smallest subgraph of G_0 containing IP and DP of $k_0 : G_0 \rightarrow G'_0$

context C is smallest subgraph of G'_0 such that $G'_0 = G_0 +_B C$

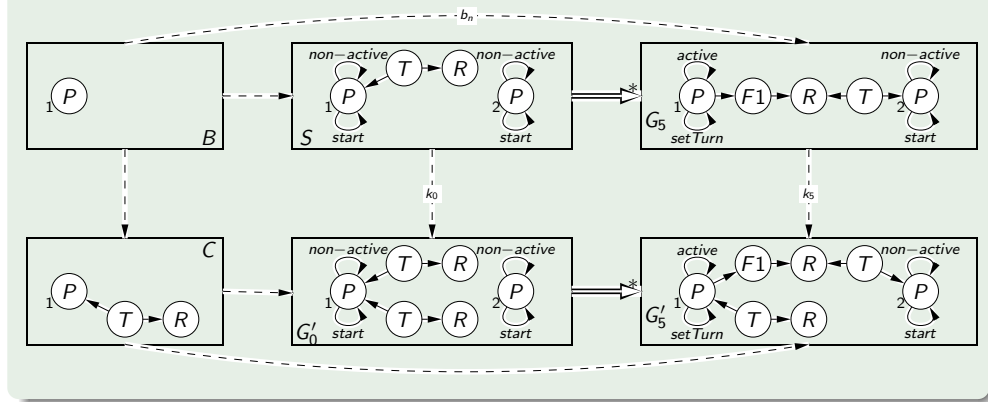
consistency: boundary B is preserved by $G_0 \xrightarrow{t} G_n$ leading to $b_n : B \rightarrow G_n$

Fact

In case of consistency we also have $G'_n = G_n +_B C$



Example



Part IV

Independence of Graph Transformations and Critical Pairs

- 17 Parallel and Sequential Independence
- 18 Local Church-Rosser Theorem
- 19 Parallelism Theorem
- 20 Global Determinism and Confluence
- 21 Critical Pairs
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Parallel and Sequential Independence

Problem: When are direct transformations commutable?

Definition

$G \xrightarrow{p_1, m_1} H_1$ and $G \xrightarrow{p_2, m_2} H_2$ are **parallel independent** if $m_1(L_1) \cap m_2(L_2) \subseteq m_1(l_1(K_1)) \cap m_2(l_2(K_2))$.

$G \xrightarrow{p_1, m_1} H_1 \xrightarrow{p_2, m_2} H_2$ are **sequentially independent** for comatch $n_1 : R_1 \rightarrow H_1$ if $n_1(R_1) \cap m_2(L_2) \subseteq n_1(r_1(K_1)) \cap m_2(l_2(K_2))$.

Fact

$G \xrightarrow{p_1, m_1} H_1$ and $G \xrightarrow{p_2, m_2} H_2$ are parallel independent iff there exist morphisms $i : L_1 \rightarrow D_2$ and $j : L_2 \rightarrow D_1$ such that $f_2 \circ i = m_1$ and $f_1 \circ j = m_2$.

Similar for sequential independence.

Examples: Parallel and Sequential Independence

Example

parallel independent:
 $m(L_1) \cap m'(L_2)$
 $= \{\text{node labelled } R\}$
 $= m(l_1(K_1)) \cap m'(l_2(K_2))$

Example

sequentially independent:
 $n_2(R_1) \cap m_3(L_2)$
 $= \{\text{node labelled } R\}$
 $= n_2(r_1(K_1)) \cap m_3(l_2(K_2))$

Local Church-Rosser Theorem

Theorem

- If $G \xrightarrow{p_1, m_1} H_1$ and $G \xrightarrow{p_2, m_2} H_2$ are parallel independent, there are $G' \xrightarrow{p_1, m'_1} H_1$ and $G' \xrightarrow{p_2, m'_2} H_2$ such that $G \xrightarrow{p_1, m_1} H_1 \xrightarrow{p_2, m'_2} G'$ and $G \xrightarrow{p_2, m_2} H_2 \xrightarrow{p_1, m'_1} G'$ are sequentially independent.

- If $G \xrightarrow{p_1, m_1} H_1 \xrightarrow{p_2, m'_2} G'$ are sequentially independent, there are H_2 and $G' \xrightarrow{p_1, m'_1} H_1$ such that $G \xrightarrow{p_1, m_1} H_1$ and $G \xrightarrow{p_2, m_2} H_2$ are parallel independent.



Example: Local Church-Rosser Theorem

Example

Overview of Parallelism and Concurrency

SKIP

- Problem:** How to compose productions p_1 and p_2 ?
- Solution:**
1. Parallel composition $p_1 + p_2$ (independency)
 2. E-concurrent production $p_1 *_E p_2$ (dependency)

Theorem

Parallelism

Concurrency



Parallel Productions and Transformations

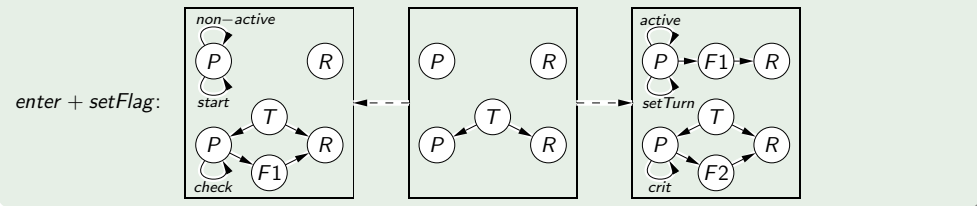
Definition

- Given productions $p_1 = (L_1 \xleftarrow{h_1} K_1 \xrightarrow{r_1} R_1)$ and $p_2 = (L_2 \xleftarrow{h_2} K_2 \xrightarrow{r_2} R_2)$, the **parallel production** $p_1 + p_2$ is defined by the disjoint union

$$p_1 + p_2 = (L_1 \dot{\cup} L_2 \xleftarrow{h_1 \dot{\cup} h_2} K_1 \dot{\cup} K_2 \xrightarrow{r_1 \dot{\cup} r_2} R_1 \dot{\cup} R_2)$$

- The application of a parallel (typed) graph production is called a **parallel direct (typed) graph transformation**.

Example

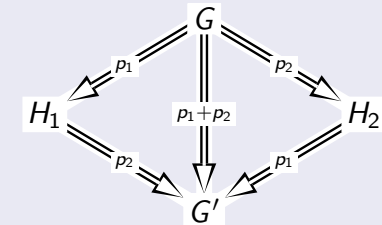


Parallelism Theorem

Theorem

Given a transformation system GTS, we have:

- Synthesis.** If $G \Rightarrow H_1 \Rightarrow G'$ via productions (p_1, p_2) are sequentially independent, then there is a parallel transformation $G \Rightarrow G'$ via the parallel production $p_1 + p_2$.
- Analysis.** For $G \Rightarrow G'$ via $p_1 + p_2$ there are sequentially independent $G \Rightarrow H_1 \Rightarrow G'$ via (p_1, p_2) and $G \Rightarrow H_2 \Rightarrow G'$ via (p_2, p_1) .
- Bijective correspondence.** The synthesis and analysis constructions are inverse to each other up to isomorphism.



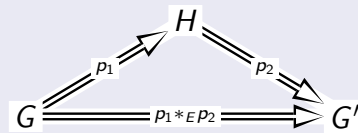
Concurrency Theorem

Problem: How to compare productions and transformations in general?

Theorem

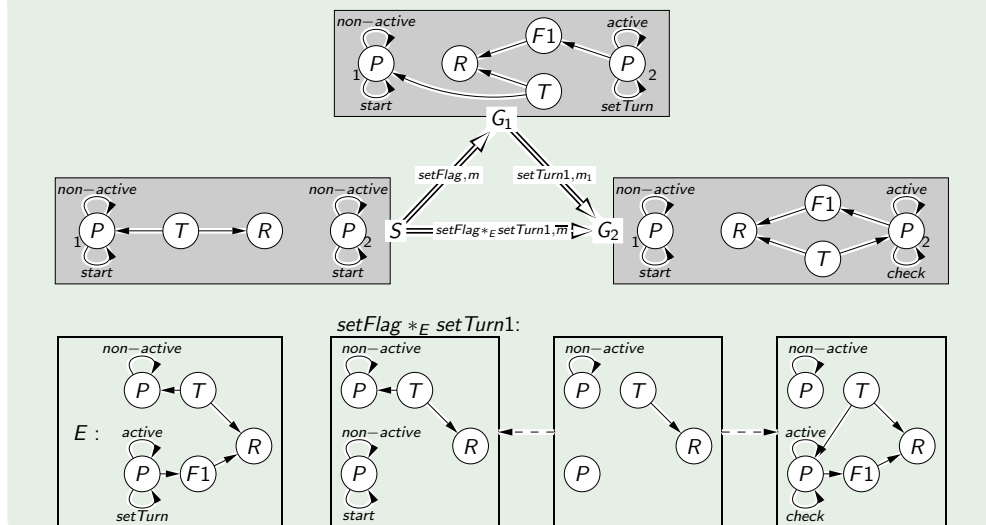
Given productions p_1 and p_2 with E -concurrent production $p_1 *_E p_2$, then:

- Synthesis.** Given an E -related transformation sequence $G \Rightarrow H \Rightarrow G'$ via (p_1, p_2) , then there is a **synthesis construction** leading to a direct transformation $G \Rightarrow G'$ via $p_1 *_E p_2$.
- Analysis.** Given a direct transformation $G \Rightarrow G'$ via $p_1 *_E p_2$, then there is an **analysis construction** leading to an E -related transformation sequence $G \Rightarrow H \Rightarrow G'$ via (p_1, p_2) .
- Bijective correspondence.** The synthesis and analysis constructions are inverse to each other up to isomorphism.



Example: Concurrency Theorem

Example

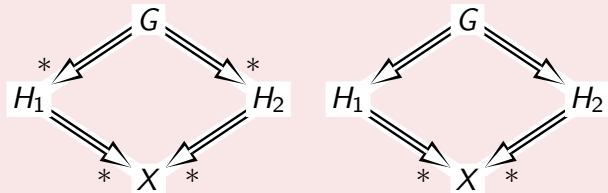


Global Determinism and Confluence

Problem: How to achieve global determinism of a GTS in spite of local nondeterminism?

Definition

A GTS is **(locally) confluent** if, for all (direct) transformations $G \xRightarrow{*} H_1$ and $G \xRightarrow{*} H_2$, there is X and transformations $H_1 \xRightarrow{*} X$ and $H_2 \xRightarrow{*} X$.



Lemma

Every confluent GTS is globally deterministic.

Termination and Confluence

Definition

A GTS is **terminating** if there is no infinite sequence of graph transformations $(t_n : G \xRightarrow{*} G_n)_{n \in \mathbb{N}}$ with $t_{n+1} = G \xRightarrow{t_n} G_n \Rightarrow G_{n+1}$.

Lemma

Every terminating and locally confluent GTS is also confluent.

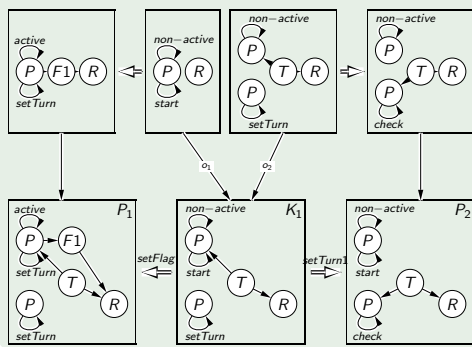
Problem: How to obtain local confluence in spite of parallel dependent graph transformations?

Critical Pairs

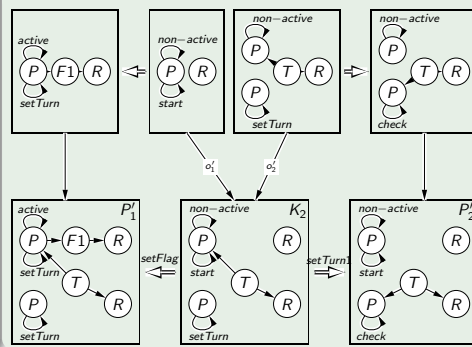
Definition

Pair $P_1 \xleftarrow{p_1, o_1} K \xrightarrow{p_2, o_2} P_2$ of direct transformations is called a **critical pair** if it is parallel dependent and minimal, i.e. the matches $o_1 : L_1 \rightarrow K$ and $o_2 : L_2 \rightarrow K$ are jointly surjective.

Critical Pair 1



Critical Pair 2

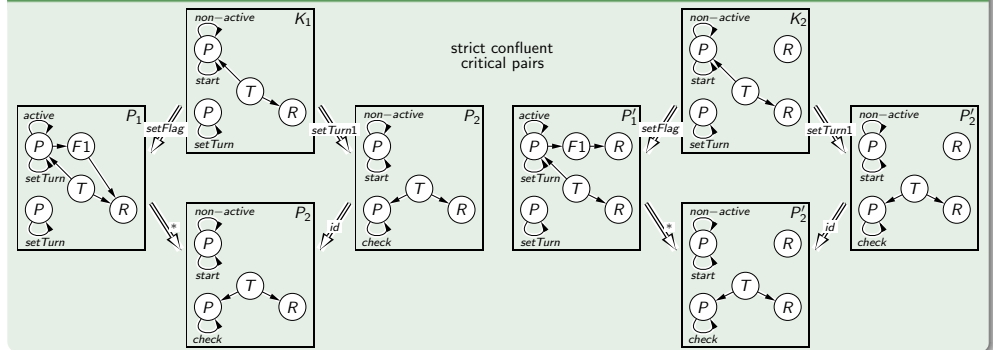


Local Confluence Theorem - Critical Pair Lemma

Theorem

A (typed) graph transformation system GTS is locally confluent if all its critical pairs are strictly confluent.

Example



Theorem

If a GTS is terminating and locally confluent, it has functional behavior:

- 1 For each G , there is a terminating transformation $G \xrightarrow{*} H$ in GTS, and H is unique up to isomorphism.
- 2 Each pair $G \xrightarrow{*} H_1$ and $G \xrightarrow{*} H_2$ can be extended to terminating transformations $G \xrightarrow{*} H_1 \xrightarrow{*} H$ and $G \xrightarrow{*} H_2 \xrightarrow{*} H$ with the same H .

Theorem

Every layered typed graph grammar $GG = (TG, P, G_0)$ with injective matches terminates if it satisfies suitable layer conditions for deleting and nondeleting productions.



Adhesive HLR Categories and Typed AGT Systems

- 24 Motivation for a Categorical Framework
- 25 Van Kampen Squares
- 26 Adhesive and Adhesive HLR Categories
- 27 Adhesive HLR Systems
- 28 Typed Attributed Graphs
- 29 Typed Attributed Graph Transformation Systems



Motivation for a Categorical Framework

- **Problem:**
 - Up to now we have graph transformation theory for **Graphs**, **Graphs_{TG}** only
 - But the theory is required also for
 - hypergraph transformation systems,
 - Petri net transformation systems,
 - transformation systems of algebraic specifications and
 - typed attributed graph transformation systems.
- **Solution:**
 - Replace **Graphs** by suitable category.
 - Suitable is Adhesive HLR category based on van Kampen property.



Overview of Adhesive HLR Categories

► SKIP

Axioms: Adhesive HLR categories $(\mathbf{C}, \mathcal{M})$ satisfy:

- 1 $\mathcal{M} \subseteq \text{Monos}$ closed under composition and decomposition
- 2 pushouts (POs) and pullbacks (PBs) along \mathcal{M} -morphisms
- 3 compatibility of POs and PBs by van Kampen squares

Examples: **Sets**, **Graphs**, **Graphs_{TG}**, **PTNets**, **AHLNets**, **(AGraphs_{ATG}, \mathcal{M})**

Theorem

- 1 construction of adhesive HLR categories by product, slice, coslice, comma and functor categories
- 2 properties of adhesive HLR categories are sufficient for all constructions and results of Parts II-IV

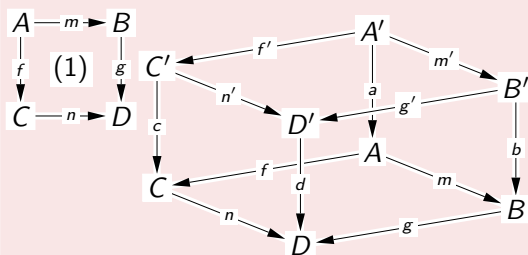


Idea: compatibility of pushouts and pullbacks

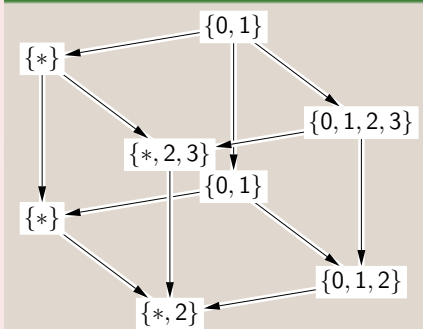
Definition

Pushout (1) is a **van Kampen square** if, for any commutative cube with (1) in the bottom and where the back faces are pullbacks, we have:

The top face is pushout iff the front faces are pullbacks.



Example



Definition

category **C** is an **adhesive category** if:

- 1 **C** has pushouts along monomorphisms (i.e. pushouts where at least one of the given morphisms is a monomorphism)
- 2 **C** has pullbacks
- 3 Pushouts along monomorphisms are VK squares

Examples: **Sets**, **Graphs**, **Graphs_{TG}**, **Hypergraphs**, **ElemNets**

Counterexamples: **PTNets**, **AGraphs_{ATG}**

Idea for generalization: Replace monomorphisms by subclass \mathcal{M} and pullbacks by those along monomorphisms

Definition

category **C** with a morphism class \mathcal{M} is called a **(weak) adhesive HLR category** if:

- 1 \mathcal{M} is a class of monomorphisms closed under isomorphisms, composition ($f : A \rightarrow B \in \mathcal{M}, g : B \rightarrow C \in \mathcal{M} \Rightarrow g \circ f \in \mathcal{M}$), and decomposition ($g \circ f \in \mathcal{M}, g \in \mathcal{M} \Rightarrow f \in \mathcal{M}$)
- 2 **C** has pushouts and pullbacks along \mathcal{M} -morphisms, and \mathcal{M} -morphisms are closed under pushouts and pullbacks
- 3 Pushouts in **C** along \mathcal{M} -morphisms are (weak) VK squares

Examples: **(PTNets, \mathcal{M}_{mono})**, **(Spec, \mathcal{M}_{strict})**, **(AHLNets, \mathcal{M}_{mono})**, **(AGraphs_{ATG}, \mathcal{M})** (see below)

Theorem

If $(\mathbf{C}, \mathcal{M}_1)$ and $(\mathbf{D}, \mathcal{M}_2)$ are (weak) adhesive HLR categories, then the following categories are (weak) adhesive HLR categories:

- 1 the **product category** $(\mathbf{C} \times \mathbf{D}, \mathcal{M}_1 \times \mathcal{M}_2)$, the **slice category** $(\mathbf{C} \setminus \mathbf{X}, \mathcal{M}_1 \cap \mathbf{C} \setminus \mathbf{X})$ and the **coslice category** $(\mathbf{X} \setminus \mathbf{C}, \mathcal{M}_1 \cap \mathbf{X} \setminus \mathbf{C})$,
- 2 the **functor category** $([\mathbf{X}, \mathbf{C}], \mathcal{M} - \text{functor transformations})$,
- 3 the **comma category** $(\text{ComCat}(F, G; \mathbf{I}), (\mathcal{M}_1 \times \mathcal{M}_2) \cap \text{Mor}_{\text{ComCat}})$, where $F : \mathbf{C} \rightarrow \mathbf{X}$ preserves pushouts along \mathcal{M}_1 -morphisms and $G : \mathbf{D} \rightarrow \mathbf{X}$ preserves pullbacks (along \mathcal{M}_2 -morphisms).

In (weak) adhesive categories, the following properties hold:

- 1 **Pushouts along \mathcal{M} -morphisms are pullbacks**
- 2 **\mathcal{M} pushout-pullback decomposition lemma**
- 3 **Cube pushout-pullback lemma**
- 4 **Uniqueness of pushout complements**

Definition

- **adhesive HLR system** $AHS = (\mathbf{C}, \mathcal{M}, P)$ consists of (weak) adhesive HLR category $(\mathbf{C}, \mathcal{M})$ and set of productions P with morphisms in \mathcal{M}
- **adhesive HLR grammar** $AHG = (AHS, S)$ is an adhesive HLR system together with a distinguished start object S
- **language** L of an adhesive HLR grammar is defined by

$$L = \{G \mid \exists \text{ transformation } S \xRightarrow{*} G\}.$$

The categorical framework allows to prove the results from Parts III and IVj for all the instantiations (like **Graphs**, **HyperGraphs**, **PTNets** etc.).

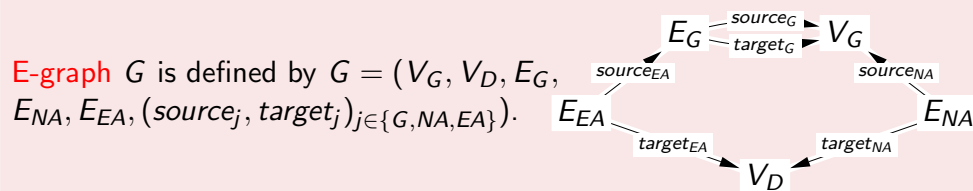


Typed attributed graph transformation (AGT) is

- integration of **typed graph transformation** with
- **data types** as attributes for
 - **modeling of visual languages** (VL) with
 - alphabet of a VL given by attributed type graph,
 - syntax given by generating grammar,
 - operational semantics given by simulating grammar and animation.
 - **model transformations** between VLs by
 - typed AGT systems.



Definition



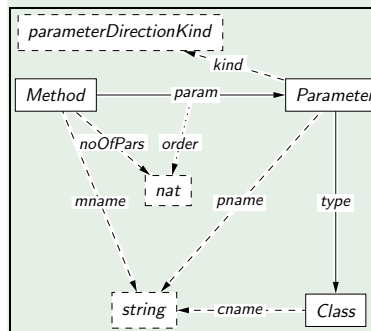
Let $DSIG = (S_D, OP_D)$ be a data signature with $S'_D \subseteq S_D$.
Attributed graph $AG = (G, D)$ is E-graph G and $DSIG$ -algebra D with $\dot{\cup}_{s \in S'_D} D_s = V_D$.

AGraphs_{ATG} = category of typed attributed graphs (G, D) and typed attributed graph morphisms (f_G, f_D) consistent w.r.t. S'_D over an attributed type graph ATG



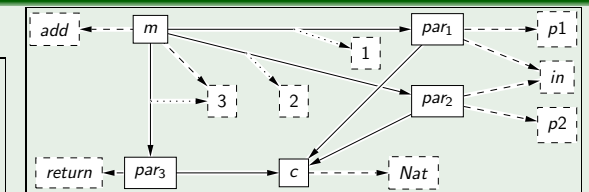
Example

Type graph ATG :

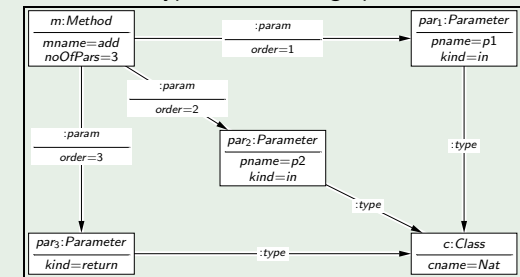


$DSIG = CHAR + STRING + NAT +$

sorts : parameterDirectionKind
 opns : in, out, inout, return \rightarrow parameterDirectionKind
 $S'_D = \{string, nat, parameterDirectionKind\}$



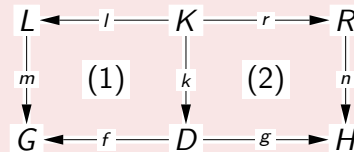
Notations for typed attributed graphs:



Definition

- **typed attributed graph production** $p = (L \xleftarrow{l} K \xrightarrow{r} R)$ consists of typed attributed graphs L, K, R with common $DSIG$ -termalgebra $T_{DSIG}(X)$ with variables X , and $l, r \in \mathcal{M}$, with $\mathcal{M} = \{f = (f_G, f_D) \mid f_g \text{ injective, } f_D \text{ isomorphism of } DSIG\text{-algebras}\}$

- **direct typed attributed graph transformation** $G \xrightarrow{p,m} H$ from G to H via the match m is given by the following double pushout diagram in **AGraphs_{ATG}**



Idea: Instantiation of theory for adhesive HLR systems

Theorem

(**AGraphs_{ATG}**, \mathcal{M}) is an adhesive HLR category.

Corollary

In **AGraphs_{ATG}**, the following results hold:

- Construction of typed attributed graph transformations,
- Embedding Theorem,
- Local Church-Rosser Theorem,
- Parallelism Theorem,
- Concurrency Theorem,
- Local Confluence Theorem.



Part VI

Advanced Features and Conclusion

- 30 Graph Constraints
- 31 Application Conditions
- 32 Typed AGT Systems with Inheritance
- 33 Modeling of Visual Languages
- 34 Model Transformations
- 35 Implementation of Typed AGT Systems in AGG
- 36 Conclusion



Overview of Constraints and Application Conditions ▶ SKIP

Idea of graph constraints:

Restriction of graphs / graph languages by existence or nonexistence of suitable graph patterns, called constraints c

Idea of application conditions:

Restriction of direct graphs transformations $G \xrightarrow{p,m} H$ by suitable conditions for the match m (e.g. gluing condition)

Theorem

Construction of application condition acc for match m from graph constraint c such that $H \models c$ if $m \models acc$.

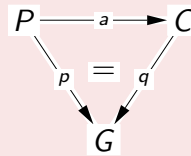


Graph Constraints

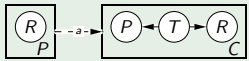
Problem: How to define graph constraints?

Definition

- **atomic (typed) graph constraint** is of form $PC(a)$, where $a : P \rightarrow C$ is (typed) graph morphism
- **(typed) graph constraint** is Boolean formula over atomic (typed) graph constraints
- $G \models PC(a)$, if, for every injective morphism $p : P \rightarrow G$, there exists injective morphism $q : C \rightarrow G$ such that $q \circ a = p$. This can be extended to boolean formulas.



Example



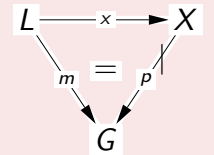
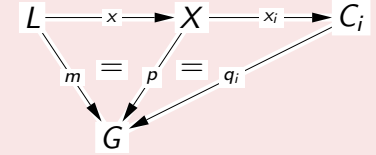
G satisfies this constraint if, for each resource node R , there is a turn variable that connects it to a process.

Application Conditions

Problem: How to define application conditions?

Definition

- **atomic application condition** over L is given by $P(x, \forall_{i \in I} x_i)$
- $m \models P(x, \forall_{i \in I} x_i)$, if, for all injective $p : X \rightarrow G$ with $p \circ x = m$, there exist $i \in I$ and injective $q_i : C_i \rightarrow G$ with $q_i \circ x_i = p$. This can be extended to boolean formulas.
- **negative application condition** $NAC(x)$ is a morphism $x : L \rightarrow X$. A morphism $m : L \rightarrow G$ satisfies $NAC(x)$ if there **does not** exist an injective $p : X \rightarrow G$ with $p \circ x = m$.



Productions with Application Conditions

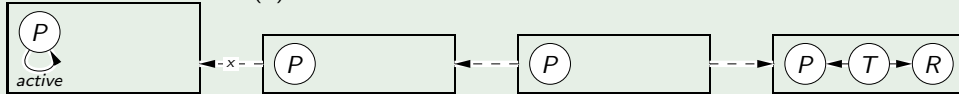
Definition

application condition $A(p) = (A_L, A_R)$ for production p consists of left application condition A_L over L and right application condition A_R over R

$G \xrightarrow{p, m} H$ with comatch $n : R \rightarrow H$ satisfies $A(p)$ if $m \models A_L$ and $n \models A_R$.

Example

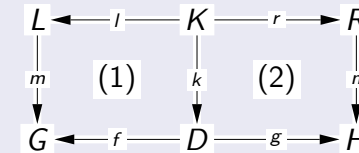
addResource with $NAC(x)$:



Construction of Application Conditions

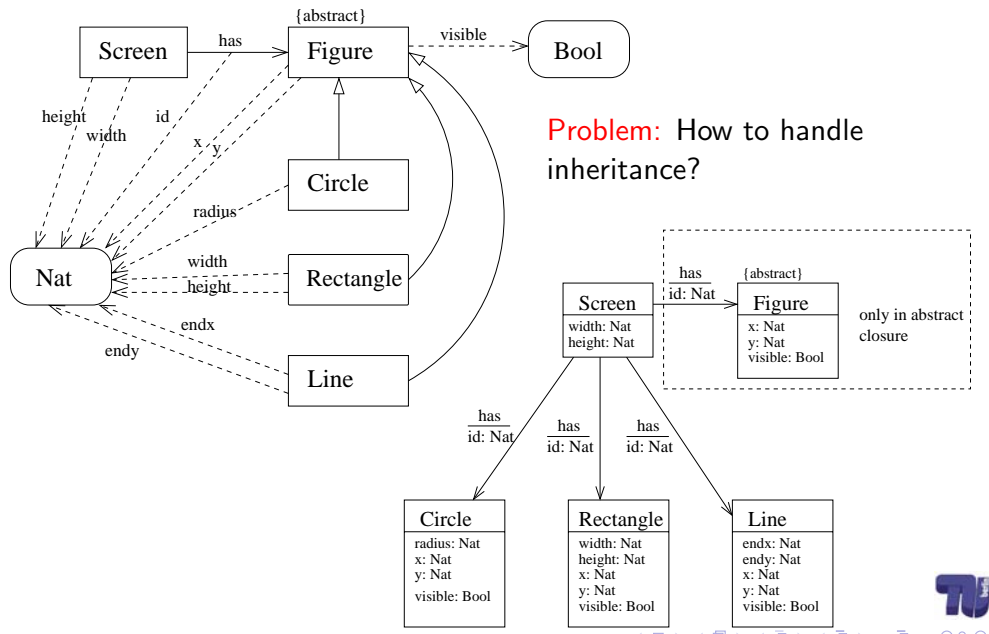
Theorem

- For each graph constraint c for H , there is an equivalent right application condition $racc$ for the comatch n .
- For each right application condition $racc$ for comatch n , there is an equivalent left application condition $lacc$ for match m .



- $H \models c$, if $m \models lacc$.

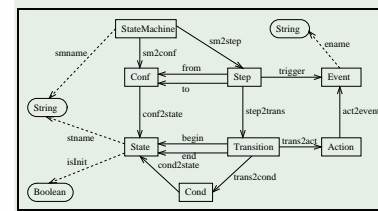
Typed AGT Systems with Inheritance



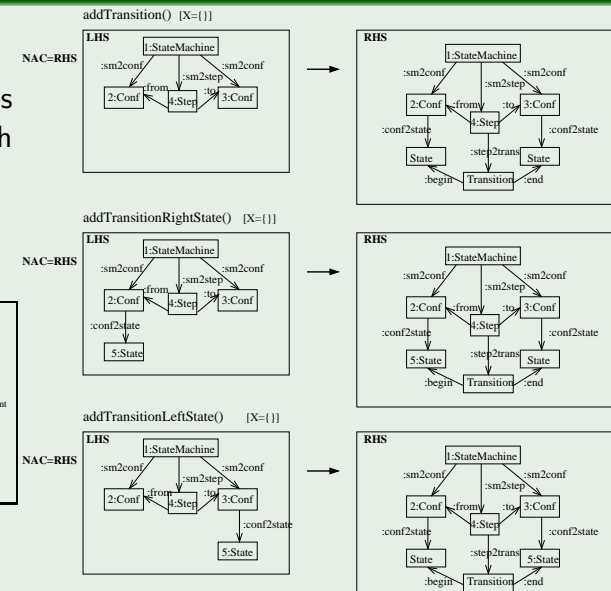
Modeling of Visual Languages

Example

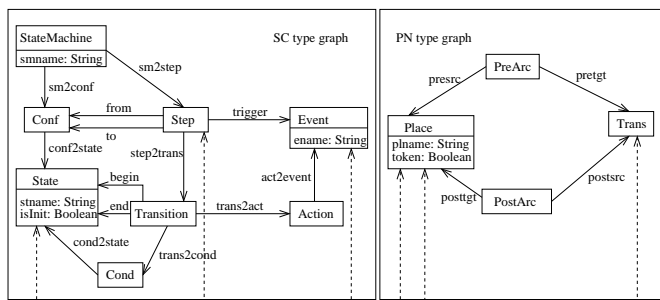
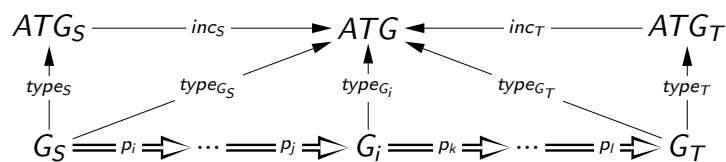
Generation of Statecharts by typed attributed graph grammar



SC type graph



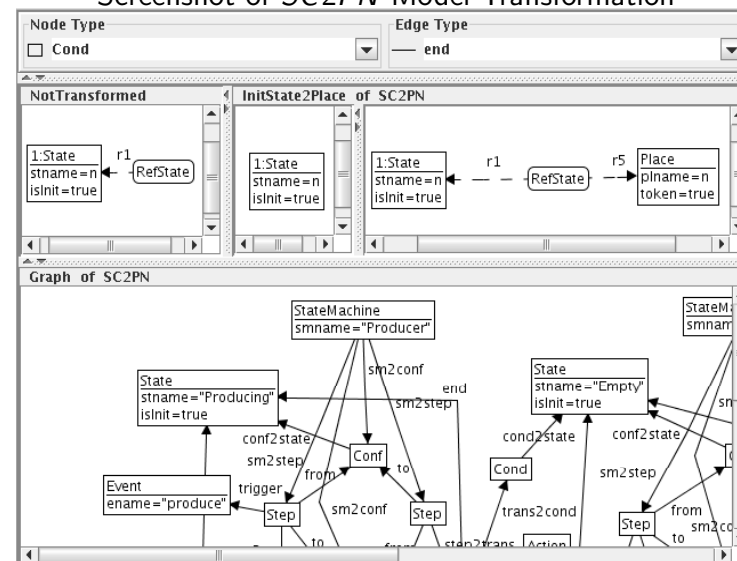
Model Transformation from Statecharts to Petri Nets



SC2PN type graph ATG

Implementation of Typed AGT Systems in AGG

Screenshot of SC2PN Model Transformation



Fundamental aspects of algebraic graph transformation:

- 1 Algebraic concept of graph transformation based on
 - gluing construction and double pushouts.
- 2 Basic results concerning
 - independence, parallelism, critical pairs.
- 3 Categorical framework of AHLR systems for
 - unified constructions and proofs.
- 4 Typed attributed graph transformation for
 - modeling of software systems,
 - model transformations of visual languages.

