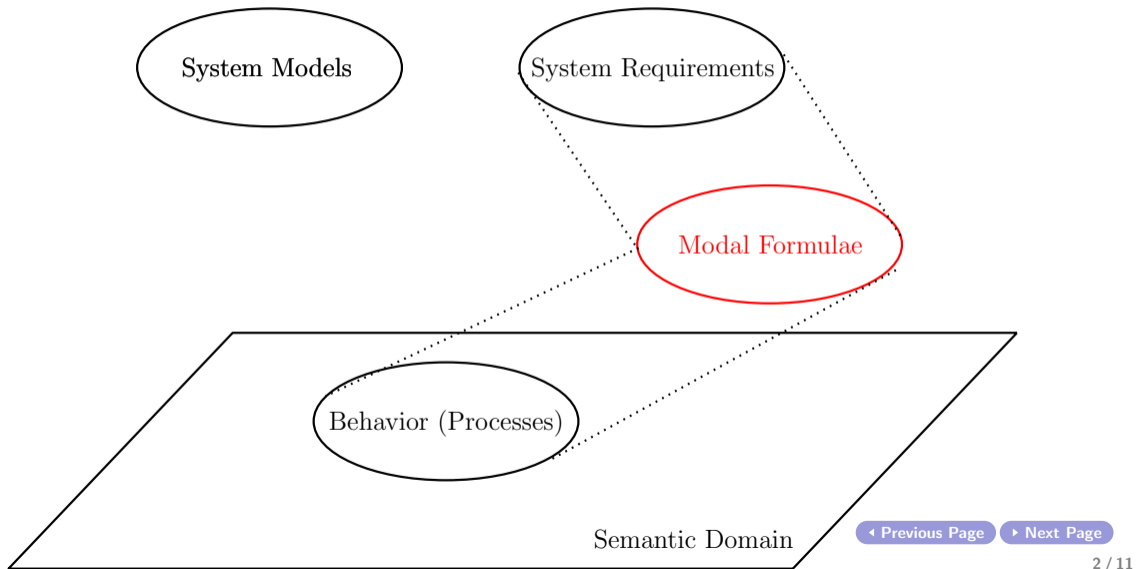


System Validation: Extensions of Hennessy-Milner Logic

Mohammad Mousavi and Jeroen Keiren

General Overview



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$$Inv(\varphi) = \varphi \wedge [true]\varphi \wedge [true][true]\varphi \wedge \dots$$

- ▶ there is a reachable state which satisfies φ

$$Pos(\varphi) = \varphi \vee \langle true \rangle \varphi \vee \langle true \rangle \langle true \rangle \varphi \vee \dots$$

Extending HML to Sets of Actions

For $A = \{a_1, \dots, a_n\} \subseteq Act$ with $n \geq 1$

- ▶ $\langle A \rangle \varphi$ denotes $\langle a_1 \rangle \varphi \vee \dots \vee \langle a_n \rangle \varphi$ and $\langle \emptyset \rangle \varphi = \text{false}$

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- ▶ $[A] \varphi$ denotes $[a_1] \varphi \wedge \dots \wedge [a_n] \varphi$ and $[\emptyset] \varphi = true$

Action formula

A described using the following syntax ($a \in Act$):

$$A, B ::= false \mid true \mid a \mid \bar{A} \mid A \cup B \mid A \cap B$$

where $\bar{A} = Act \setminus A$, $true$ matches all actions, $false$ matches no action.

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$$[true]\varphi \wedge \langle true \rangle true$$

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Limitations of HML revisited

Formulas for properties that cannot be expressed in HML

- ▶ the scientist always produces a publication after drinking two coffees in a row

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- ▶ $Inv(\varphi)$

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- ▶ $Pos(\varphi)$

$$\langle true^* \rangle \varphi$$

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Using regular HML we still cannot express some intuitive properties:

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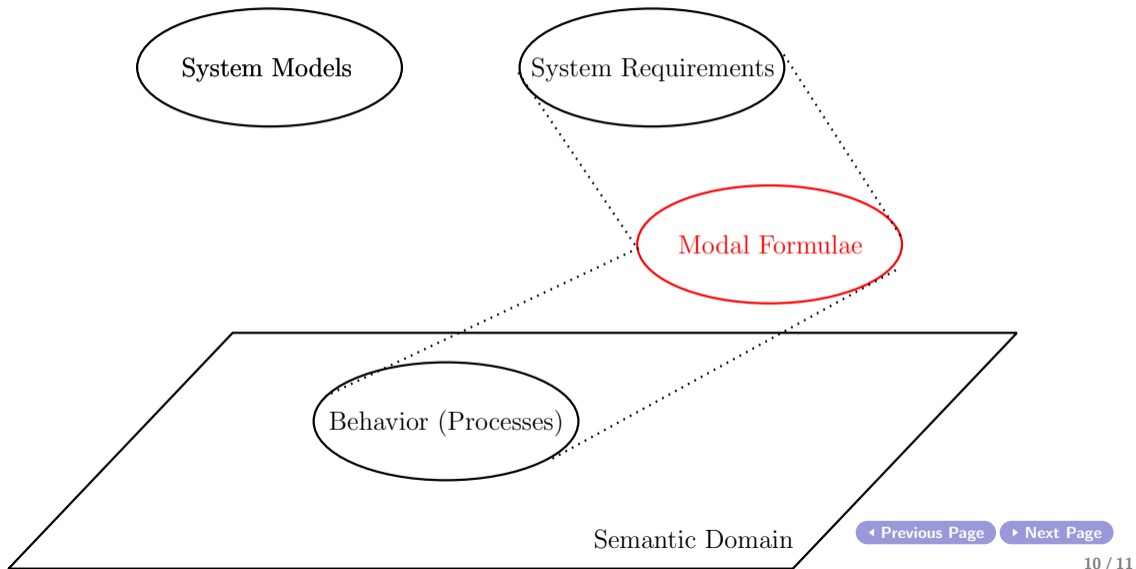
Why not use **recursion**?

- ▶ $Inev(\varphi)$ expressed by $X \stackrel{\text{def}}{=} \varphi \vee [true]X$
- ▶ $Safe(\varphi)$ expressed by $X \stackrel{\text{def}}{=} \varphi \wedge \langle true \rangle X$

Summary

- ▶ Allowing sets inside modalities \implies more compact formulas
- ▶ **Regular HML** allows describing properties of **infinite depth**
- ▶ Some desirable properties cannot be described using regular HML

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Thank you very much.